Conference and Workshop Papers

[C1] J. Sturm, C. Plagemann and W. Burgard,
*Adaptive Body Scheme Models for Robust Robotic Manipulation,*

[C2] J. Sturm, C. Plagemann and W. Burgard,
*Body Scheme Learning and Life-Long Adaptation for Robotic Manipulation,*
*Proc. of the Workshop on Robot Manipulation at the Robotics: Science and Systems Con-
ference (RSS),* Zurich, Switzerland, June 2008.