Journal Articles

[J1] Rodola, Emanuele, Lähner, Zorah, Bronstein, Alex M., Bronstein, Michael M., Solomon and Justin,
Functional Maps Representation on Product Manifolds,

[J2] F. Pasa, V. Golkov, F. Pfeiffer, D. Cremers and D. Pfeiffer,
Efficient Deep Network Architectures for Fast Chest X-Ray Tuberculosis Screening and Visualization,

[J3] R. Wang, N. Yang, J. Stueckler and D. Cremers,
DirectShape: Photometric Alignment of Shape Priors for Visual Vehicle Pose and Shape Estimation,

[J4] J. Schuchardt, V. Golkov and D. Cremers,
Learning to Evolve,

A Non-invasive 3D Body Scanner and Software Tool towards Analysis of Scoliosis,

[J6] M. Eisenberger, Z. Lähner and D. Cremers,
Smooth Shells: Multi-Scale Shape Registration with Functional Maps,

[J7] Haefner, B., Peng, S., Verma, A., Queau, Y., Cremers and D.,
Photometric Depth Super-Resolution,

[J8] Brahimi, M., Queau, Y., Haefner, B., Cremers and D.,
On well-posedness of uncalibrated photometric stereo under general lighting,

[J9] J. Engel, V. Koltun and D. Cremers,
Direct Sparse Odometry,
March 2018.

[J10] N. Yang, R. Wang, X. Gao and D. Cremers,
Challenges in Monocular Visual Odometry: Photometric Calibration, Motion Bias and Rolling Shutter Effect,

LED-based Photometric Stereo: Modeling, Calibration and Numerical Solution,
[J12] Queau, Y., Durou, J.-D., Aujol and J.-F.,
Normal Integration: A Survey,

[J13] Queau, Y., Durou, J.-D., Aujol and J.-F.,
Variational Methods for Normal Integration,

[J14] Melou, J., Queau, Y., Durou, J.-D., Castan, F., Cremers and D.,
Variational Reflectance Estimation from Multi-view Images,

[J15] P. Bergmann, R. Wang and D. Cremers,
Online Photometric Calibration of Auto Exposure Video for Realtime Visual Odometry and SLAM,

[J16] E. Aljalbout, V. Golkov, Y. Siddiqui, M. Strobel and D. Cremers,
Clustering with Deep Learning: Taxonomy and New Methods,

[J17] L. Ma., J. Stueckler, T. Wu and D. Cremers,
Detailed Dense Inference with Convolutional Neural Networks via Discrete Wavelet Transform,
Aug 2018.

[J18] Tjaden, Henning, Schwanecke, Ulrich, Schömer, Elmar, Cremers and Daniel,
A Region-based Gauss-Newton Approach to Real-Time Monocular Multiple Object Tracking,

[J19] Queau, Y., Mecca, R., Durou, J.-D., Descombes and X.,
Photometric Stereo with Only Two Images: A Theoretical Study and Numerical Resolution,

3D Deep Learning for Biological Function Prediction from Physical Fields,

[J21] Bähr, M., Breus, M., Queau, Y., Bouroujerdi, A. S., Durou and J.-D.,
Fast and accurate surface normal integration on non-rectangular domains,

Genetic defects in s-spectrin and tau sensitize C. elegans axons to movement-induced damage via torque-tension coupling,


[J35] J. Diebold, C. Nieuwenhuis and D. Cremers,
Midrange Geometric Interactions for Semantic Segmentation,
2015.

[J36] J. Diebold, S. Tari and D. Cremers,
The Role of Diffusion in Figure Hunt Games,

[J37] S. Madhogaria, P. M. Baggenstoss, M. Schikora, W. Koch and D. Cremers,
Car detection by fusion of HOG and causal MRF,

[J38] M. Klodt, K. Herzog, R. Töpfer and D. Cremers,
Field phenotyping of grapevine growth using dense stereo reconstruction,

[J39] M. Jaimez and J. Gonzalez-Jimenez,
Fast Visual Odometry for 3-D Range Sensors,

[J40] J. Stueckler and S. Behnke,
Efficient Dense Rigid-Body Motion Segmentation and Estimation in RGB-D Video,
January 2015.

NimbRo Explorer: Semi-Autonomous Exploration and Mobile Manipulation in Rough Terrain,

[J42] D. Droeschel, M. Nieuwenhuisen, M. Beul, J. Stueckler, D. Holz and S. Behnke,
Multi-Layered Mapping and Navigation for Autonomous Micro Aerial Vehicles,

[J43] E. Rodola, A. Albarelli, D. Cremers and A. Torsello,
A Simple and Effective Relevance-based Point Sampling for 3D Shapes,

[J44] R. Mecca, E. Rodola and D. Cremers,
Realistic Photometric Stereo Using Partial Differential Irradiance Equation Ratios,

[J45] T. Möllenhoff, E. Strekalovskiy, M. Möller and D. Cremers,
The Primal-Dual Hybrid Gradient Method for Semiconvex Splittings,

Cloud-based collaborative 3D mapping in real-time with low-cost robots,

[J47] Hugo Grimmett, Rudolph Triebel, Rohan Paul and Ingmar Posner,
Introspective classification for robot perception,
[J48] T. Whelan, L. Ma, E. Bondarev, P. de With and J. McDonald,
Incremental and Batch Planar Simplification of Dense Point Cloud Maps,

[J49] B. Goldluecke, M. Aubry, K. Kolev and D. Cremers,
*A Super-resolution Framework for High-Accuracy Multiview Reconstruction*,

[J50] E. Strekalovskiy, A. Chambolle and D. Cremers,
*Convex Relaxation of Vectorial Problems with Coupled Regularization*,

[J51] J. Engel, J. Sturm and D. Cremers,
*Scale-Aware Navigation of a Low-Cost Quadrocopter with a Monocular Camera*,

[J52] E. Rodola, S. Rota Bulo and D. Cremers,
*Robust Region Detection via Consensus Segmentation of Deformable Shapes*,

[J53] M. Schadler, J. Stueckler and S. Behnke,
*Rough Terrain Mapping and Navigation using a Continuously Rotating 2D Laser Scanner*,

[J54] J. Stueckler, B. Waldvogel, H. Schulz and S. Behnke,
*Dense Real-Time Mapping of Object-Class Semantics from RGB-D Video*,
2014.

[J55] J. Stueckler and S. Behnke,
*Multi-Resolution Surfel Maps for Efficient Dense 3D Modeling and Tracking*,

[J56] E. Rodola, A. Albarelli, F. Bergamasco and A. Torsello,
*A Scale Independent Selection Process for 3D Object Recognition in Cluttered Scenes*,

[J57] A. Torsello, A. Albarelli and E. Rodola,
*Stable and Fast Techniques for Unambiguous Compound Phase Coding*,

[J58] C. Nieuwenhuis and D. Cremers,
*Spatially Varying Color Distributions for Interactive Multi-Label Segmentation*,

[J59] C. Nieuwenhuis, E. Toeppe and D. Cremers,
*A Survey and Comparison of Discrete and Continuous Multi-label Optimization Approaches for the Potts Model*,
[J60] B. Goldluecke, E. Strekalovskiy and D. Cremers,
Tight Convex Relaxations for Vector-Valued Labeling,

[J61] F. Endres, J. Hess, J. Sturm, D. Cremers and W. Burgard,
3D Mapping with an RGB-D Camera,

[J62] Liu, Z., Beetz, M., Cremers, D., Gall, J., Li, W., Pangercic, D., Sturm, J., Tai and Y.-W.,
Introduction to the special issue on visual understanding and applications with
RGB-D cameras,

[J63] A. Albarelli, E. Rodola and A. Torsello,
Imposing Semi-local Geometric Constraints for Accurate Correspondences Selection in Structure from Motion: a Game-Theoretic Perspective,

[J64] A. Chambolle, D. Cremers and T. Pock,
A Convex Approach to Minimal Partitions,

[J65] T. Schoenemann and D. Cremers,
A Coding Cost Framework for Super-resolution Motion Layer Decomposition,

[J66] T. Schoenemann, F. Kahl, S. Masnou and D. Cremers,
A linear framework for region-based image segmentation and inpainting involving curvature penalization,

[J67] D. Cremers,
Optimal Solutions for Semantic Image Decomposition,

[J68] S. Chen, D. Cremers and R. J. Radke,
Image segmentation with one shape prior - A template-based formulation,

[J69] B. Goldluecke, E. Strekalovskiy and D. Cremers,
The Natural Total Variation Which Arises from Geometric Measure Theory,

[J70] U. Schlickewei,
On the André motive of certain irreducible symplectic varieties,

[J71] K. Kolev, T. Brox and D. Cremers,
Fast Joint Estimation of Silhouettes and Dense 3D Geometry from Multiple Images,
An image classification approach to analyze the suppression of plant immunity by the human pathogen Salmonella Typhimurium,

[J73] D. Cremers and E. Strekalovskiy,
*Total Cyclic Variation and Generalizations*,

[J74] J. Stueckler, R. Steffens, D. Holz and S. Behnke,
*Efficient 3D Object Perception and Grasp Planning for Mobile Manipulation in Domestic Environments*,

[J75] J. Stueckler, R. Steffens, D. Holz and S. Behnke,
*RoboCup@Home: Demonstrating Everyday Manipulation Skills in RoboCup@Home*,

[J76] T. Windheuser, U. Schlickewei, F. R. Schmidt and D. Cremers,
*Large-Scale Integer Linear Programming for Orientation-Preserving 3D Shape Matching*,

[J77] D. Cremers and K. Kolev,
*Multiview Stereo and Silhouette Consistency via Convex Functionals over Convex Domains*,

[J78] A. Wedel, T. Brox, T. Vaudrey, C. Rabe, U. Franke and D. Cremers,
*Stereoscopic Scene Flow Computation for 3D Motion Understanding*,

[J79] T. Schoenemann, S. Masnou and D. Cremers,
*The Elastic Ratio: Introducing Curvature into Ratio-Based Globally Optimal Image Segmentation*,
20(9): 2565-2581, 2011.

[J80] A. Sellent, M. Eisemann, B. Goldluecke, D. Cremers and M. Magnor,
*Motion Field Estimation from Alternate Exposure Images*,

[J81] S. Chitta, J. Sturm, M. Piccoli and W. Burgard,
*Tactile Sensing for Mobile Manipulation*,
*IEEE Transactions on Robotics (T-RO)*, 2011.

*A Variational Approach to Vesicle Membrane Reconstruction from Fluorescence Imaging*,
All: 1
List of Publications

[J83] J. Sturm, C. Stachniss and W. Burgard,
A Probabilistic Framework for Learning Kinematic Models of Articulated Objects,
Journal on Artificial Intelligence Research (JAIR), 41: 477-626, August 2011.

[J84] J. Kybic and C. Nieuwenhuis,
Bootstrap Optical Flow and Uncertainty Measure,

[J85] T. Pock, D. Cremers, H. Bischof and A. Chambolle,
Global Solutions of Variational Models with Convex Regularization,

[J86] T. Schoenemann and D. Cremers,
A Combinatorial Solution for Model-based Image Segmentation and Real-time Tracking,

[J87] U. Schlickewei,
The Hodge conjecture for self-products of certain K3 surfaces,

[J88] U. Schlickewei,
Stability of tautological vector bundles on Hilbert squares of surfaces,

[J89] Y. Arboleda-Estudillo, M. Krieg, J. Stühmer, N. A. Licata, D. J. Muller and C.-P. Heisenberg,
Movement Directionality in Collective Migration of Germ Layer Progenitors,

[J90] L. Spinello, R. Triebel and R. Siegwart,
Multiclass Multimodal Detection and Tracking in Urban Environments,

[J91] T. Brox and D. Cremers,
On local region models and a statistical interpretation of the piecewise smooth Mumford-Shah functional,

[J92] T. Brox, B. Rosenhahn, J. Gall and D. Cremers,
Combined region- and motion-based 3D tracking of rigid and articulated objects,

[J93] K. Kolev, M. Klodt, T. Brox and D. Cremers,
Continuous Global Optimization in Multiview 3D Reconstruction,

[J94] A. Wedel, C. Rabe, H. Badino, H. Loose, U. Franke and D. Cremers,
B-Spline Modeling of Road Surfaces with an Application to Free Space Estimation,
[J95] U. Schlickewei,
Hodge classes on self-products of K3 surfaces,

[J96] E. Strekalovskiy,
Folgen von Höhenfußpunktdreiecken und ihre Grenzpunkte,

[J97] J. Sturm, C. Plagemann and W. Burgard,
Body schema learning for robotic manipulators from visual self-perception,

[J98] J. Sturm, and A. Visser,
An appearance-based visual compass for mobile robots,

[J99] T. Brox, O. Kleinschmidt and D. Cremers,
Efficient Nonlocal Means for Denoising of Textural Patterns,

[J100] D. Cremers,
Nonlinear Dynamical Shape Priors for Level Set Segmentation,

[J101] H. Jin, D. Cremers, D. Wang, A. Yezzi, E. Prados and S. Soatto,
3-D Reconstruction of Shaded Objects from Multiple Images Under Unknown Illumination,

[J102] C. Michel, M. T. Elm, S. D. Baranovskii, P. Thomas, W. Heimbrodt, B. Goldluecke and P. J. Klar,
Influence of non-random incorporation of Mn ions on the magnetotransport properties of Ga_{1-x}Mn_xAs alloys,

[J103] C. Michel, M. T. Elm, B. Goldluecke, S. D. Baranovskii, P. Thomas, W. Heimbrodt and P. J. Klar,
Tailoring the magnetoresistance of MnAs/GaAs:Mn granular hybrid nanostructures,

[J104] R. Kümmerle, R. Triebel, P. Pfaff and W. Burgard,
Monte Carlo localization in outdoor terrains using multilevel surface maps,

[J105] S. Behnke and J. Stueckler,
Hierarchical Reactive Control for Humanoid Soccer Robots,

[J106] T. Pock, M. Pock and H. Bischof,
Algorithmic Differentiation: Application to Variational Problems in Computer Vision,
2007.
[J107] B. Rosenhahn, T. Brox and J. Weickert,  
Three-dimensional shape knowledge for joint image segmentation and pose tracking,  

[J108] Y.-J. Kim, T. Brox, W. Feiden and J. Weickert,  
Fully automated segmentation and morphometrical analysis of muscle fibre images,  

[J109] D. Cremers,  
Computer Lernen Sehen,  

[J110] D. Cremers, M. Rousson and R. Deriche,  
A review of statistical approaches to level set segmentation: integrating color, texture, motion and shape,  

[J111] B. Goldluecke, I. Ihrke, C. Linz and M. Magnor,  
Weighted Minimal Hypersurface Reconstruction,  

Quantitative modeling of the annealing-induced changes of the magnetotransport in Ga$_{1-x}$Mn$_x$As alloys,  

[J113] O. Martinez Mozos, R. Triebel, P. Jensfelt, A. Rottmann and W. Burgard,  
Supervised semantic labeling of places using information extracted from sensor data,  

[J114] P. Pfaff, R. Triebel and W. Burgard,  
An Efficient Extension to Elevation Maps for Outdoor Terrain Mapping and Loop Closing,  

[J115] H. Andreasson, R. Triebel and A. Lilienthal,  
Non-iterative Vision-based Interpolation of 3D Laser Scans,  

[J116] T. Brox and J. Weickert,  
Level Set Segmentation with Multiple Regions,  

[J117] T. Brox and J. Weickert,  
A TV flow based local scale estimate and its application to texture discrimination,  
17(5): 1053-1073, October 2006.

[J118] D. Cremers,  
Dynamical statistical shape priors for level set based tracking,  
[J119] D. Cremers, S. J. Osher and S. Soatto,
Kernel density estimation and intrinsic alignment for shape priors in level set segmentation,

[J120] D. Cremers, N. Sochen and C. Schnörr,
A multiphase dynamic labeling model for variational recognition-driven image segmentation,

[J121] S. Manay, D. Cremers, B.-W. Hong, A. Yezzi and S. Soatto,
Integral invariants for shape matching,

[J122] N. Papenberg, A. Bruhn, T. Brox, S. Didas and J. Weickert,
Highly accurate optic flow computation with theoretically justified warping,
67(2): 141-158, April 2006.

[J123] T. Brox, J. Weickert, B. Burgeth and P. Mrazek,
Nonlinear structure tensors,

[J124] M. Breus, T. Brox, A. Bürgel, T. Sonar and J. Weickert,
Numerical aspects of TV flow,

[J125] B. Rosenhahn, T. Brox, U. G. Kersting, A. W. Smith, J. Gurney and R. Klette,
A system for marker-less motion capture,
Künstliche Intelligenz, 45-51, January 2006.

[J126] C. Michel, S. D. Baranovskii, P. J. Klar, P. Thomas and B. Goldluecke,
Strong non-Arrhenius temperature dependence of the resistivity in the regime of traditional band transport,

[J127] D. Cremers and S. Soatto,
Motion Competition: A variational framework for piecewise parametric motion segmentation,

Spin-dependent localization effects in GaAs:Mn/MnAs granular paramagnetic-ferromagnetic hybrids at low temperatures,

[J129] G. Steidl, J. Weickert, T. Brox, P. Mrazek and M. Welk,
On the equivalence of soft wavelet shrinkage, total variation diffusion, total variation regularization, and SIDEs,

[J130] D. Cremers, T. Kohlberger and C. Schnörr,
Shape Statistics in Kernel Space for Variational Image Segmentation,
[J131] D. Cremers and C. Schnörr,
Statistical shape knowledge in variational motion segmentation,

[J132] J. Keuchel, C. Schnörr, C. Schellewald and D. Cremers,
Binary partitioning, perceptual grouping, and restoration with semidefinite
programming,

[J133] D. Cremers and A. V. M. Herz,
Travelling waves of excitation in neural field models: Equivalence of rate des-
criptions and integrate-and-fire dynamics,

[J134] D. Cremers, F. Tischhäuser, J. Weickert and C. Schnörr,
Diffusion Snakes: Introducing statistical shape knowledge into the Mumford–
Shah functional,

[J135] D. Cremers and A. Mielke,
Flow equations for the Héon-Heiles Hamiltonian,

Books

[B1] D. Cremers, I. Reid, H. Saito and M.-S. Yang (Editors),
Computer Vision: ACCV 2014,
Springer 2014.

[B2] J. Sturm,
Approaches to Probabilistic Model Learning for Mobile Manipulation Robots,
Springer 2013.

[B3] Guest Editors: Y. Boykov, F. Kahl, V. Lempitsky and F. R. Schmidt,
Special Issue: Energy Optimization Methods,
Springer 2013.

[B4] A. Wedel and D. Cremers,
Stereoscopic Scene Flow for 3D Motion Analysis,
Springer 2011.

[B5] Y. Boykov, F. Kahl, V. Lempitsky and F. R. Schmidt (Editors),

Video Processing and Computational Video,
Springer 2010.

[B7] D. Cremers, Y. Boykov, A. Blake and F. R. Schmidt (Editors),
Energy Minimization Methods for Computer Vision and Pattern Recognition
(EMMCVPR),
Springer 2009.
[B8] D. Cremers, B. Rosenhahn, A. L. Yuille and F. R. Schmidt (Editors),
Statistical and Geometrical Approaches to Visual Motion Analysis,
Springer 2009.

Energy Minimization Methods for Computer Vision and Pattern Recognition
(EMMCVPR),

Book Chapters

[BC1] Vestner, M., Rodola, E., Windheuser, T., Bulo, Rota Bulo, S., Cremers and D.,
Applying Random Forests to the Problem of Dense Non-rigid Shape Correspondence,

Skeleton-Based Recognition of Shapes in Images via Longest Path Matching,

[BC3] V. Golkov, J. M. Portegies, A. Golkov, R. Duits and D. Cremers,
Holistic Image Reconstruction for Diffusion MRI,
Computational Diffusion MRI, Munich, Germany, Springer, October 2015, Book Chapter, and Oral Presentation at MICCAI 2015 Workshop on Computational Diffusion MRI.

Joint Super-Resolution Using Only One Anisotropic Low-Resolution Image per q-Space Coordinate,
Computational Diffusion MRI, Springer, 2014, Book Chapter, and Oral Presentation at MICCAI 2014 Workshop on Computational Diffusion MRI.

[BC5] M. Klodt, F. Steinbruecker and D. Cremers,
Moment Constraints in Convex Optimization for Segmentation and Tracking,

A Game-Theoretic Approach to Pairwise Clustering and Matching,

[BC7] Sturm, J., Plagemann, C., Burgard and W.,
Body Schema Learning,

[BC8] M. Schikora, W. Koch, R. L. Streit and D. Cremers,
A Sequential Monte Carlo Method for Multi-Target Tracking with the Intensity Filter,
[BC9] D. Cremers, T. Pock, K. Kolev and A. Chambolle, 
Convex Relaxation Techniques for Segmentation, Stereo and Multiview Reconstruction, 

[BC10] D. Cremers, 
Image Segmentation with Shape Priors: Explicit Versus Implicit Representations, 

[BC11] A. Chambolle, V. Caselles, D. Cremers, M. Novaga and T. Pock, 
An Introduction to Total Variation for Image Analysis, 

[BC12] T. Brox, B. Rosenhahn and D. Cremers, 
Contours, optic flow, and prior knowledge: cues for capturing 3D human motion in videos, 

Tracking clothed people, 

[BC14] D. Cremers and M. Rousson, 
Efficient kernel density estimation of shape and intensity priors for level set segmentation, 

Adaptive structure tensors and their applications, 

[BC16] D. Cremers and T. Kohlberger, 
Probabilistic kernel PCA and its application to statistical shape modeling and inference, 

[BC17] S. Manay, D. Cremers, B. W. Hong, A. Yezzi and S. Soatto, 
Integral Invariants and Shape Matching, 
Statistical analysis of shapes (modeling and simulation in science, engineering and technology), Birkhauser, 137-167, May 2006.

[BC18] J. Weickert, A. Bruhn, T. Brox and N. Papenberg, 
A survey on variational optic flow methods for small displacements, 

PDEs for tensor image processing, 
J. Weickert, G. Steidl, P. Mrazek, M. Welk and T. Brox,
Diffusion filters and wavelets: What can they learn from each other?,

Conference and Workshop Papers

[C1] Sang, L., Haefner, B., Cremers and D.,
Inferring Super-Resolution Depth from a Moving Light-Source Enhanced RGB-D Sensor: A Variational Approach,

[C2] A. Vasilev, V. Golkov, M. Meissner, I. Lipp, E. Sgarlata, V. Tomassini, D. K. Jones and D. Cremers,
q-Space Novelty Detection with Variational Autoencoders,
MICCAI 2019 International Workshop on Computational Diffusion MRI, 2019, Oral Presentation.

[C3] P. Swazinna, V. Golkov, I. Lipp, E. Sgarlata, V. Tomassini, D. K. Jones and D. Cremers,
Negative-Unlabeled Learning for Diffusion MRI,
2019.

[C4] E. Bylow, R. Maier, F. Kahl and C. Olsson,
Combining Depth Fusion and Photometric Stereo for Fine-Detailed 3D Models,
Scandinavian Conference on Image Analysis (SCIA), Norrköping, Sweden, June 2019, Oral Presentation, received the SCIA 2019 Honourable Mention award.

[C5] E. Laude, T. Wu and D. Cremers,
Optimization of Inf-Convolution Regularized Nonconvex Composite Problems,
International Conference on Artificial Intelligence and Statistics (AISTATS), 2019.

[C6] V. Usenko, N. Demmel, D. Schubert, J. Stueckler and D. Cremers,
Visual-Inertial Mapping with Non-Linear Factor Recovery,

[C7] T. Frerix and J. Bruna,
Approximating Orthogonal Matrices with Effective Givens Factorization,

[C8] Haefner, B., Ye, Z., Gao, M., Wu, T., Queau, Y., Cremers and D.,
Variational Uncalibrated Photometric Stereo under General Lighting,
International Conference on Computer Vision (ICCV), Seoul, South Korea, October 2019.

[C9] Q. Khan, P. Wenzel, D. Cremers and L. Leal-Taixe,
Towards Generalizing Sensorimotor Control Across Weather Conditions,

[C10] E.Y. Puang, P. Lehner, Z.C. Marton, M. Durner, R. Triebel and A. Albu-Schäffer,
Visual Repetition Sampling for Robot Manipulation Planning,
2019.
[C11] M. Moeller, T. Möllenhoff and D. Cremers,
Controlling Neural Networks via Energy Dissipation,
*International Conference on Computer Vision (ICCV)*, Seoul, South Korea, 10 2019.

[C12] S. Weiss, R. Maier, R. Westermann, D. Cremers and N. Thuerey,
Sparse Surface Constraints for Combining Physics-based Elasticity Simulation and Correspondence-Free Object Reconstruction,

[C13] D. Schubert, N. Demmel, L. von Stumberg, V. Usenko and D. Cremers,
Rolling-Shutter Modelling for Visual-Inertial Odometry,
November 2019.

[C14] Caner Hazirbas, Sebastian Georg Soyer, Maximilian Christian Staab, Laura Leal-Taixe and Daniel Cremers,
Deep Depth From Focus,
*Asian Conference on Computer Vision (ACCV)*, December 2018.

[C15] E. Laude, T. Wu and D. Cremers,
A Nonconvex Proximal Splitting Algorithm under Moreau-Yosida Regularization,
*International Conference on Artificial Intelligence and Statistics (AISTATS)*, 2018.

[C16] T. Möllenhoff, Z. Ye, T. Wu and D. Cremers,
Combinatorial Preconditioners for Proximal Algorithms on Graphs,
*International Conference on Artificial Intelligence and Statistics (AISTATS)*, 2018.

q-Space Novelty Detection in Short Diffusion MRI Scans of Multiple Sclerosis, 2018.


[C19] B. T. Do, V. Golkov, G. E. Gürel and D. Cremers,

[C20] P. Haeusser, J. Plapp, V. Golkov, E. Aljalbout and D. Cremers,
Associative Deep Clustering - Training a Classification Network with no Labels,
*Proc. of the German Conference on Pattern Recognition (GCPR)*, October 2018.

[C21] Nikolaus Mayer, Eddy Ilg, Philipp Fischer, Caner Hazirbas, Daniel Cremers, Alexey Dosovitskiy and Thomas Brox,
What Makes Good Synthetic Training Data for Learning Disparity and Optical Flow Estimation?,
September 2018.
[C22] T. Frerix, T. Möllenhoff, M. Moeller and D. Cremers,
Proximal Backpropagation,

Discrete-Continuous ADMM for Transductive Inference in Higher-Order MRFs,
2018.

[C24] L. von Stumberg, V. Usenko and D. Cremers,
Direct Sparse Visual-Inertial Odometry using Dynamic Marginalization,
May 2018.

The TUM VI Benchmark for Evaluating Visual-Inertial Odometry,
October 2018.

[C26] X. Gao, R. Wang, N. Demmel and D. Cremers,
LDSO: Direct Sparse Odometry with Loop Closure,
*iros*, October 2018.

[C27] Z. Lähner, D. Cremers and T. Tung,
DeepWrinkles: Accurate and Realistic Clothing Modeling,
September 2018, *Oral Presentation*.

[C28] D. Schubert, N. Demmel, V. Usenko, J. Stueckler and D. Cremers,
Direct Sparse Odometry With Rolling Shutter,
September 2018, *Oral Presentation*.

[C29] V. Usenko, N. Demmel and D. Cremers,
The Double Sphere Camera Model,

[C30] I. Chiotellis, F. Zimmermann, D. Cremers and R. Triebel,
Incremental Semi-Supervised Learning from Streams for Object Classification,

6DoF Pose Estimation for Industrial Manipulation based on Synthetic Data,

[C32] C. Nissler, M. Durner, Z.-C. Marton and R. Triebel,
Simultaneous Calibration and Mapping,

[C33] P. Wenzel, Q. Khan, D. Cremers and L. Leal-Taixe,
Modular Vehicle Control for Transferring Semantic Information Between Weather Conditions Using GANs,
*Conference on Robot Learning (CoRL)*, 2018.
[C34] Haefner, B., Queau, Y., Möllenhoff, T., Cremers and D.,
Fight ill-posedness with ill-posedness: Single-shot variational depth super-
resolution from shading,
*IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2018, Spotlight
Presentation.

[C35] I. Grixa, P. Schulz, W. Stürzl and R. Triebel,
Appearance-Based Along-Route Localization for Planetary Missions,

[C36] M. Sundermeyer, Z. Marton, M. Durner, M. Brucker and R. Triebel,
Implicit 3D Orientation Learning for 6D Object Detection from RGB Images,
September 2018, Best Paper Award.

[C37] M. Denninger and R. Triebel,
Persistent Anytime Learning of Objects from Unseen Classes,

[C38] M. Jaimez, C. Kerl, J. Gonzalez-Jimenez and D. Cremers,
Fast Odometry and Scene Flow from RGB-D Cameras based on Geometric
Clustering,
*Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA)*, 2017.

[C39] M. Jaimez, T. J. Cashman, A. Fitzgibbon, J. Gonzalez-Jimenez and D. Cremers,
An Efficient Background Term for 3D Reconstruction and Tracking with
Smooth Subdivision Surface Models,
2017.

[C40] L. Ma, J. Stueckler, C. Kerl and D. Cremers,
Multi-View Deep Learning for Consistent Semantic Mapping with RGB-D
Cameras,
Vancouver, Canada, Sep 2017.

[C41] Vestner, M., Litman, R., Rodola, E., Bronstein, A., Cremers and D.,
Product Manifold Filter: Non-Rigid Shape Correspondence via Kernel Density
Estimation in the Product Space,
2017.

[C42] M. Dzitsiuk, J. Sturm, R. Maier, L. Ma and D. Cremers,
De-noising, Stabilizing and Completing 3D Reconstructions On-the-go using
Plane Priors,

[C43] L. von Stumberg, V. Usenko, J. Engel, J. Stueckler and D. Cremers,
From Monocular SLAM to Autonomous Drone Exploration,

[C44] Florian Walch, Caner Hazirbas, Laura Leal-Taixe, Torsten Sattler, Sebastian Hilsenbeck
and Daniel Cremers,
Image-based localization using LSTMs for structured feature correlation,
October 2017.
All: 1

List of Publications


[C64] Peng, S., Haefner, B., Queau, Y., Cremers and D., Depth Super-Resolution Meets Uncalibrated Photometric Stereo, *International Conference on Computer Vision Workshops (ICCVW)*, 2017, Oral Presentation at ICCV Workshop on Color and Photometry in Computer Vision.


[C68] Z. Lähner, E. Rodola, F. R. Schmidt, M. M. Bronstein and D. Cremers, 
Efficient Globally Optimal 2D-to-3D Deformable Shape Matching, 
May 2016.

[C69] A. Narr, R. Triebel and D. Cremers, 
Stream-based Active Learning for Efficient and Adaptive Classification of 3D Objects, 
May 2016.

[C70] Z. Lähner, E. Rodola, M. M. Bronstein, D. Cremers, O. Burghard, L. Cosmo, A. Dieckmann, R. Klein and Y. Sahillioglu, 
SHREC16: Matching of Deformable Shapes with Topological Noise, 
May 2016.

[C71] L. Cosmo, E. Rodola, M. M. Bronstein, A. Torsello, D. Cremers and Y. Sahillioglu, 
SHREC16: Partial Matching of Deformable Shapes, 
May 2016.

[C72] T. Möllenhoff, E. Laude, M. Moeller, J. Lellmann and D. Cremers, 
Sublabel-Accurate Relaxation of Nonconvex Energies, 
2016.

[C73] L. Ma, C. Kerl, J. Stueckler and D. Cremers, 
CPA-SLAM: Consistent Plane-Model Alignment for Direct RGB-D SLAM, 
May 2016.

[C74] J. Engel, V. Usenko and D. Cremers, 
A Photometrically Calibrated Benchmark For Monocular Visual Odometry, 

[C75] J. Engel, V. Koltun and D. Cremers, 
Direct Sparse Odometry, 

[C76] E. Laude, T. Möllenhoff, M. Moeller, J. Lellmann and D. Cremers, 
Sublabel-Accurate Convex Relaxation of Vectorial Multilabel Energies, 
October 2016.

[C77] T. Windheuser and D. Cremers, 
A Convex Solution to Spatially-Regularized Correspondence Problems, 
October 2016.

[C78] S. Sharifzadeh, I. Chiotellis, R. Triebel and D. Cremers, 
Learning to Drive using Inverse Reinforcement Learning and Deep Q-Networks, 
NIPS Workshops, December 2016.

[C79] D. Klostermann, A. Osep, J. Stueckler and B. Leibe, 
Unsupervised Learning of Shape-Motion Patterns for Objects in Urban Street Scenes, 
British Machine Vision Conference (BMVC), 2016.

[C80] D. Kochanov, A. Osep, J. Stueckler and B. Leibe, 
Scene Flow Propagation for Semantic Mapping and Object Discovery in Dynamic Street Scenes, 
[C81] F. Engelmann, J. Stueckler and B. Leibe,
Joint Object Pose Estimation and Shape Reconstruction in Urban Street Scenes Using 3D Shape Priors,
Proc. of the German Conference on Pattern Recognition (GCPR), 2016.

[C82] M. Moeller, J. Diebold, G. Gilboa and D. Cremers,

[C83] J. Diebold, N. Demmel, C. Hazirbas, M. Möller and D. Cremers,

[C84] C. Hazirbas, J. Diebold and D. Cremers,

[C85] A. Kanezaki, E. Rodola and T. Harada,
RGB-D [Graph matching gakushuu wo mochiita RGB-D gazou kara no butai kenshutsu] - Learning graph matching for object detection from RGB-D images,
20 - Robotics Symposia (RS), Karuizawa, Japan, March 2015.

[C86] T. Möllenhoff, E. Strekalovskiy, M. Möller and D. Cremers,

[C87] M. Jaimez, M. Souiai, J. Gonzalez-Jimenez and D. Cremers,
A Primal-Dual Framework for Real-Time Dense RGB-D Scene Flow,
Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA), 2015.

[C88] J. Stühmer and D. Cremers,
A Fast Projection Method for Connectivity Constraints in Image Segmentation,
X.-C. Tai, E. Bae, T. F. Chan and M. Lysaker(Eds.), , 2015.

[C89] R. Mecca, E. Rodola and D. Cremers,
Analysis of Surface Parametrizations for Modern Photometric Stereo Modeling,
International Conference on Quality Control by Artificial Vision (QCAV), 2015.

[C90] F. Bergamasco, A. Albarelli, L. Cosmo, A. Torsello, E. Rodola and D. Cremers,
Adopting an Unconstrained Ray Model in Light-field Cameras for 3D Shape Reconstruction, 2015.

[C91] D. Mund, R. Triebel and D. Cremers,
Active Online Confidence Boosting for Efficient Object Classification,

Using Diffusion and Structural MRI for the Automated Segmentation of Multiple Sclerosis Lesions, 2015.


[C100] D. Caruso, J. Engel and D. Cremers, Large-Scale Direct SLAM for Omnidirectional Cameras, 2015.


[C104] E. Rodola, M. Moeller and D. Cremers,
Point-wise Map Recovery and Refinement from Functional Correspondence,
Aachen, Germany, 2015, Received the Best Paper Award.

[C105] C. Kerl, J. Stueckler and D. Cremers,
Dense Continuous-Time Tracking and Mapping with Rolling Shutter RGB-D Cameras,
Santiago, Chile, 2015.

[C106] M. Souiai, M. R. Oswald, Y. Kee, J. Kim, M. Pollefeys and D. Cremers,
Entropy Minimization for Convex Relaxation Approaches,
Santiago, Chile, 2015.

[C107] F. Stark, C. Hazirbas, R. Triebel and D. Cremers,
CAPTCHA Recognition with Active Deep Learning,
GCPR Workshop on New Challenges in Neural Computation, Aachen, Germany, 2015.

[C108] N. Nagaraja, F. R. Schmidt and T. Brox,
Video Segmentation with Just a Few Strokes,
Santiago, Chile, Dec 2015.

[C109] J. St"uhmer, S. Nowozin, A. Fitzgibbon, R. Szeliski, T. Perry, S. Acharya, D. Cremers and J. Shotton,
Model-Based Tracking at 300Hz using Raw Time-of-Flight Observations,
Santiago, Chile, 2015.

Novel Acquisition Scheme for Diffusion Kurtosis Imaging Based on Compressed-Sensing Accelerated DSI Yielding Superior Image Quality,
2014.

Total Variation-Regularized Compressed Sensing Reconstruction for Multi-Shell Diffusion Kurtosis Imaging,
2014.

Direct Reconstruction of the Average Diffusion Propagator with Simultaneous Compressed-Sensing-Accelerated Diffusion Spectrum Imaging and Image Denoising by Means of Total Generalized Variation Regularization,
2014.

[C113] V. Golkov, M.I. Menzel, T. Sprenger, A. Haase, D. Cremers and J.I. Sperl,
Semi-Joint Reconstruction for Diffusion MRI Denoising Imposing Similarity of Edges in Similar Diffusion-Weighted Images,
2014.

Improved Diffusion Kurtosis Imaging and Direct Propagator Estimation Using 6-D Compressed Sensing,
2014.

[C115] D. Weikersdorfer, D. B. Adrian, D. Cremers and J. Conrad,
Event-based 3D SLAM with a depth-augmented dynamic vision sensor,
2014.
[C116] F. Steinbruecker, J. Sturm and D. Cremers,
Volumetric 3D Mapping in Real-Time on a CPU,
Hongkong, China, 2014.

[C117] E. Rodola, S. Rota Bulo, T. Windheuser, M. Vestner and D. Cremers,
Dense Non-Rigid Shape Correspondence Using Random Forests,
2014.

[C118] Y. Kee, M. Souiai, D. Cremers and J. Kim,
Sequential Convex Relaxation for Mutual-Information-Based Unsupervised
Figure-Ground Segmentation,
2014.

[C119] H. Alvarez, L.M. Paz, J. Sturm and D. Cremers,
Collision Avoidance for Quadrotors with a Monocular Camera,

[C120] J. Engel, T. Schöps and D. Cremers,
LSD-SLAM: Large-Scale Direct Monocular SLAM,
September 2014, Oral Presentation.

[C121] T. Schöps, J. Engel and D. Cremers,
Semi-Dense Visual Odometry for AR on a Smartphone,
September 2014, Best Short Paper Award.

[C122] T. Windheuser, M. Vestner, E. Rodola, R. Triebel and D. Cremers,
Optimal Intrinsic Descriptors for Non-Rigid Shape Analysis,
2014.

[C123] M. Strobel, J. Diebold and D. Cremers,
Flow and Color Inpainting for Video Completion,
German Conference on Pattern Recognition (GCPR), Münster, Germany, September 2014, Oral Presentation.

[C124] R. Maier, J. Sturm and D. Cremers,
Submap-based Bundle Adjustment for 3D Reconstruction from RGB-D Data,
German Conference on Pattern Recognition (GCPR), Münster, Germany, September 2014.

[C125] T. Gurdan, M. R. Oswald, D. Gurdan and D. Cremers,
Spatial and Temporal Interpolation of Multi-View Image Sequences,
Münster, Germany, Vol. 36, September 2014.

[C126] M. R. Oswald and D. Cremers,
Surface Normal Integration for Convex Space-time Multi-view Reconstruction,
2014.

[C127] C. Nieuwenhuis, S. Hawe, M. Kleinsteuber and D. Cremers,
Co-Sparse Textural Similarity for Interactive Segmentation,
2014.

[C128] M. R. Oswald, J. Stühmer and D. Cremers,
Generalized Connectivity Constraints for Spatio-temporal 3D Reconstruction,

[C129] E. Strekalovskiy and D. Cremers,
Real-Time Minimization of the Piecewise Smooth Mumford-Shah Functional,
[C130] A. Kanezaki, E. Rodola and T. Harada,
RGB-D [RGB-D gazou kara no buttai kenshutsu ni okeru taiou tenshuugou ruijido no gakushuu],
*32 - The Robotics Society of Japan (RSJ)*, Fukuoka, Japan, September 2014, **2015 Encouragement Award**.

[C131] A. Kanezaki, E. Rodola, D. Cremers and T. Harada,
[Taiou tenshuugou ruijido gakushuu wo mochiita goutai-higoutai buttai kenshutsu],

[C132] M. Andreux, E. Rodola, M. Aubry and D. Cremers,
Anisotropic Laplace-Beltrami Operators for Shape Analysis,
*Sixth Workshop on Non-Rigid Shape Analysis and Deformable Image Alignment (NOR-DIA)*, 2014.

[C133] O. Dunkley, J. Engel, J. Sturm and D. Cremers,
Visual-Inertial Navigation for a Camera-Equipped 25g Nano-Quadrotor,

[C134] R. Triebel, J. Stühmer, M. Souiai and D. Cremers,
Active Online Learning for Interactive Segmentation Using Sparse Gaussian Processes,
*German Conference on Pattern Recognition*, 2014.

[C135] S. Debnath, S. S. Baishya, R. Triebel, V. Dutt and D. Cremers,
Environment-adaptive Learning: How Clustering Helps to Obtain Good Training Data,

[C136] A. Kanezaki, E. Rodola, D. Cremers and T. Harada,
Learning Similarities for Rigid and Non-Rigid Object Detection,

[C137] D. Bender, M. Schikora, J. Sturm and D. Cremers,
INS-Camera Calibration without Ground Control Points,

[C138] C. Kerl, M. Souiai, J. Sturm and D. Cremers,
Towards Illumination-invariant 3D Reconstruction using ToF RGB-D Cameras,

[C139] J. Stueckler and S. Behnke,
Adaptive Tool-Use Strategies for Anthropomorphic Service Robots,

[C140] D. Droeschel, J. Stueckler and S. Behnke,
Local Multi-Resolution Surfel Grids for MAV Motion Estimation and 3D Mapping,
[C141] J. Stueckler, A. Gutt and S. Behnke, 
Combining the Strengths of Sparse Interest Point and Dense Image Registration for RGB-D Odometry, 
Proc. of the Joint 45th International Symposium on Robotics (ISR) and 8th German Conference on Robotics (ROBOTIK), to appear, June 2014.

[C142] J. Stueckler and S. Behnke, 
Efficient deformable registration of multi-resolution surfel maps for object manipulation skill transfer, 

[C143] D. Droeschel, J. Stueckler and S. Behnke, 
Local multi-resolution representation for 6D motion estimation and mapping with a continuously rotating 3D laser scanner, 
Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA), 5221-5226, May 2014.

[C144] M. Schwarz, J. Stueckler and S. Behnke, 
Mobile Teleoperation Interfaces with Adjustable Autonomy for Personal Service Robots, 

[C145] F. R. Schmidt, T. Windheuser, U. Schlickewei and D. Cremers, 
Dense Elastic 3D Shape Matching, 

[C146] Bergbauer, Julia, Tari and Sibel, 
Wimmelbild Analysis with Approximate Curvature Coding Distance Images, 

[C147] Bergbauer, Julia, Tari and Sibel, 
Top-down visual search in Wimmelbild, 

[C148] F. Bergamasco, A. Albarelli, E. Rodola and A. Torsello, 
Can a fully unconstrained imaging model be applied effectively to central cameras?, 2013.

[C149] M. Souiai, C. Nieuwenhuis, E. Strekalovskiy and D. Cremers, 
Convex Optimization for Scene Understanding, 
ICCV Workshop on Graphical Models for Scene Understanding, 2013.

[C150] J. Bergbauer, C. Nieuwenhuis, M. Souiai and D. Cremers, 
Proximity Priors for Variational Semantic Segmentation and Recognition, 
ICCV Workshop on Graphical Models for Scene Understanding, 2013.

[C151] V. Golkov, T. Sprenger, A. Menini, M.I. Menzel, D. Cremers and J.I. Sperl, 


[C162] D. Weikersdorfer, A. Schick and D. Cremers,
Depth-adative Supervoxels for RGB-D Video Segmentation,
2013.

[C163] R. Triebel, H. Grimmett and I. Posner,
Confidence Boosting: Improving the Introspectiveness of a Boosted Classifier for Efficient Learning,

Introspective Active Learning for Scalable Semantic Mapping,

[C165] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers,
Real-Time Camera Tracking and 3D Reconstruction Using Signed Distance Functions,

[C166] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers,
Direct Camera Pose Tracking and Mapping With Signed Distance Functions,
Demo Track of the RGB-D Workshop on Advanced Reasoning with Depth Cameras at the Robotics: Science and Systems Conference (RSS), June 2013.

[C167] J. Sturm and W. Burgard,
Learning Probabilistic Models for Mobile Manipulation Robots,
Proc. of the International Joint Conference on Artificial Intelligence (IJCAI), Track on Best papers in Sister Conferences, 2013.

[C168] M. Souiai, E. Strekalovskiy, C. Nieuwenhuis and D. Cremers,
A Co-occurrence Prior for Continuous Multi-Label Optimization,
2013.

[C169] F. Stangl, M. Souiai and D. Cremers,
Performance Evaluation of Narrow Band Methods for Variational Stereo,
35th German Conference on Pattern Recognition (GCPR), 2013.

[C170] T. Möllenhoff, C. Nieuwenhuis, E. Toeppe and D. Cremers,
Efficient Convex Optimization for Minimal Partition Problems with Volume Constraints,
2013.

[C171] C. Kerl, J. Sturm and D. Cremers,
Dense Visual SLAM for RGB-D Cameras,

[C172] T. Naseer, J. Sturm and D. Cremers,
FollowMe: Person Following and Gesture Recognition with a Quadrocopter,

[C173] M. Klodt, J. Sturm and D. Cremers,
Scale-Aware Object Tracking with Convex Shape Constraints on RGB-D Images,
German Conference on Pattern Recognition (GCPR), Saarbrücken, Germany, September 2013.
All: 1

List of Publications

[C174] J. Sturm, E. Bylow, F. Kahl and D. Cremers,
Dense Tracking and Mapping with a Quadrocopter,
*Unmanned Aerial Vehicle in Geomatics (UAV-g)*, Rostock, Germany, September 2013.

[C175] D. Bender, M. Schikora, J. Sturm and D. Cremers,
Graph-based bundle adjustment for INS-camera calibration,
*Unmanned Aerial Vehicle in Geomatics (UAV-g)*, Rostock, Germany, September 2013,
*Best research paper award*.

[C176] J. Sturm, E. Bylow, F. Kahl and D. Cremers,
CopyMe3D: Scanning and Printing Persons in 3D,
*German Conference on Pattern Recognition (GCPR)*, Saarbrücken, Germany, September 2013.

[C177] E. Rodola, T. Harada, Y. Kuniyoshi and D. Cremers,
Efficient Shape Matching using Vector Extrapolation,
2013.

[C178] J. Engel, J. Sturm and D. Cremers,
Semi-Dense Visual Odometry for a Monocular Camera,
Sydney, Australia, December 2013.

[C179] E. Rodola, A. Torsello, T. Harada, Y. Kuniyoshi and D. Cremers,
Elastic Net Constraints for Shape Matching,
Sydney, Australia, December 2013.

[C180] J. Lellmann, E. Strekalovskiy, S. Koetter and D. Cremers,
Total Variation Regularization for Functions with Values in a Manifold,
Sydney, Australia, December 2013.

[C181] C. Nieuwenhuis, E. Strekalovskiy and D. Cremers,
Proportion Priors for Image Sequence Segmentation,
Sydney, Australia, December 2013.

[C182] J. Stühmer, P. Schröder and D. Cremers,
Tree Shape Priors with Connectivity Constraints using Convex Relaxation on General Graphs,
Sydney, Australia, December 2013, *Oral Presentation*.

[C183] G. Kuschk and D. Cremers,
Fast and Accurate Large-scale Stereo Reconstruction using Variational Methods,
*ICCV Workshop on Big Data in 3D Computer Vision*, Sydney, Australia, December 2013.

[C184] M. R. Oswald and D. Cremers,
A Convex Relaxation Approach to Space Time Multi-view 3D Reconstruction,
*ICCV Workshop on Dynamic Shape Capture and Analysis (4DMOD)*, 2013.

[C185] F. Steinbruecker, C. Kerl, J. Sturm and D. Cremers,
Large-Scale Multi-Resolution Surface Reconstruction from RGB-D Sequences,
Sydney, Australia, 2013.

[C186] T. Naseer, J. Sturm and D. Cremers,
Interactive Person Following and Gesture Recognition with a Flying Robot,
*Proc. of the Assistance and Service Robotics Workshop (ASROB) at the IE-EE. Int. Conf. on Intelligent Robots and Systems (IROS)*, Nov. 2013.
All: 1 List of Publications

Driven Learning for Driving: How Introspection Improves Semantic Mapping,
The International Symposium on Robotics Research (ISRR), 2013.

[C188] D. Cremers, E. Rodola and T. Windheuser,
Relaxations for Minimizing Metric Distortion and Elastic Energies for 3D Shape Matching,

[C189] M. Schadler, J. Stueckler and S. Behnke,
Multi-resolution surfel mapping and real-time pose tracking using a continuously rotating 2D laser scanner,

[C190] J. Stueckler and S. Behnke,
Efficient Dense 3D Rigid-Body Motion Segmentation in RGB-D Video,

[C191] M. McElhone, J. Stueckler and S. Behnke,
Joint detection and pose tracking of multi-resolution surfel models in RGB-D,

[C192] T. Fiolka, J. Stueckler, D. A. Klein, D. Schulz and S. Behnke,
Distinctive 3D surface entropy features for place recognition.,

[C193] A. Berner, Jun Li, D. Holz, J. Stueckler, S. Behnke and R. Klein,
Combining contour and shape primitives for object detection and pose estimation of prefabricated parts,

[C194] J. Stueckler and S. Behnke,
Hierarchical Object Discovery and Dense Modelling From Motion Cues in RGB-D Video,

[C195] M. Nieuwenhuisen, D. Droeschel, D. Holz, J. Stueckler, A. Berner, Jun Li, R. Klein and S. Behnke,
Mobile bin picking with an anthropomorphic service robot,

[C196] L. Gorelick, F. R. Schmidt and Y. Boykov,
Fast Trust Region for Segmentation,
Portland, Oregon, Jun 2013.

[C197] L. Ma, T. Whelan, E. Bondarev, P. H. N. de With and J. McDonald,
Planar simplification and texturing of dense point cloud maps,
List of Publications

[C198] E. Rodola, A.M. Bronstein, A. Albarelli, F. Bergamasco and A. Torsello, 
A game-theoretic approach to deformable shape matching, 

[C199] F. Endres, J. Hess, N. Engelhard, J. Sturm, D. Cremers and W. Burgard, 
An Evaluation of the RGB-D SLAM System, 

[C200] T. Ruehr, J. Sturm, D. Pangercic, M. Beetz and D. Cremers, 
A Generalized Framework for Opening Doors and Drawers in Kitchen Environments, 

[C201] Dominik Joho AND Gian Diego Tipaldi AND Nikolas Engelhard AND Cyrill Stachniss 
AND Wolfram Burgard, 
Nonparametric Bayesian Models for Unsupervised Scene Analysis and Reconstruction, 

[C202] M. Schikora, A. Gning, L. Mihaylova, D. Cremers, W. Koch and R. Streit, 
Box-Particle Intensity Filter, 

[C203] M. Schikora, A. Gning, L. Mihaylova, D. Cremers and W. Koch, 
Box-Particle PHD Filter for Multi-Target Tracking, 
15th International Conference on Information Fusion (FUSION), Singapore, July 2012.

[C204] L. Zhang, J. Sturm, D. Cremers and D. Lee, 
Real-Time Human Motion Tracking using Multiple Depth Cameras, 

[C205] E. Strekalovskiy, C. Nieuwenhuis and D. Cremers, 
Nonmetric Priors for Continuous Multilabel Optimization, 
Firenze, Italy, Springer, October 2012.

[C206] T. Windheuser, H. Ishikawa and D. Cremers, 
Generalized Roof Duality for Multi-Label Optimization: Optimal Lower Bounds and Persistency, 
Firenze, Italy, October 2012.

[C207] T. Windheuser, H. Ishikawa and D. Cremers, 
QPBO [QPBO arugorizumu no tachika ni yoru hiretsu mojura enerugi saishoka], 
Meeting on Image Recognition and Understanding, Fukuoka, Japan, August 2012.

[C208] M. R. Oswald, E. Toeppe and D. Cremers, 
Fast and Globally Optimal Single View Reconstruction of Curved Objects, 
Providence, Rhode Island, 534-541, June 2012.

[C209] E. Strekalovskiy, A. Chambolle and D. Cremers, 
A Convex Representation for the Vectorial Mumford-Shah Functional, 
Providence, Rhode Island, June 2012.
[C210] J. Engel, J. Sturm and D. Cremers,
Camera-Based Navigation of a Low-Cost Quadrocopter,

[C211] J. Sturm, N. Engelhard, F. Endres, W. Burgard and D. Cremers,
A Benchmark for the Evaluation of RGB-D SLAM Systems,

[C212] J. Engel, J. Sturm and D. Cremers,
Accurate Figure Flying with a Quadrocopter Using Onboard Visual and Inertial Sensing,

[C213] J. Sturm, W. Burgard and D. Cremers,
Evaluating Egomotion and Structure-from-Motion Approaches Using the TUM RGB-D Benchmark,

Evaluation of DSI Imaging with Compressed Sensing under the Presence of Different Noise Levels on a Diffusion Phantom, 2012.


[C216] N. Ufer, M. Souiai and D. Cremers,
Wehrli 2.0: An Algorithm for Tidying up Art,

Semantic Categorization of Outdoor Scenes with Uncertainty Estimates using Multi-Class Gaussian Process Classification,

Parsing Outdoor Scenes from Streamed 3D Laser Data Using Online Clustering and Incremental Belief Updates,

[C219] U. Hubert, J. Stueckler and S. Behnke,
Bayesian calibration of the hand-eye kinematics of an anthropomorphic robot,
Proc. of the 12th IEEE-RAS Int. Conf. on Humanoid Robots (Humanoids), 618-624, November 2012.
[C220] J. Stueckler, N. Biresev and S. Behnke,
Semantic mapping using object-class segmentation of RGB-D images,
Proc. of the IEEE/RSJ Int. Conf. on Intelligent Robots and Systems (IROS), 3005-3010, October 2012.

[C221] J. Stueckler and S. Behnke,
Integrating depth and color cues for dense multi-resolution scene mapping using RGB-D cameras,
Proc. of the IEEE Int. Conf. on Multisensor Fusion and Integration for Intelligent Systems (MFI), 162-167, September 2012.

[C222] S. Muszynski, J. Stueckler and S. Behnke,
Adjustable autonomy for mobile teleoperation of personal service robots,
Proc. of the IEEE Int. Symp. on Robot and Human Interactive Communication, 933-940, September 2012.

[C223] T. Fiolk, J. Stueckler, D. A. Klein, D. Schulz and S. Behnke,
SURE: Surface Entropy for Distinctive 3D Features,

[C224] G. M. Garcia, D. A. Klein, J. Stueckler, S. Frintrop and A. B. Cremers,
Adaptive Multi-cue 3D Tracking of Arbitrary Objects,

[C225] J. Stueckler and S. Behnke,

[C226] M. Nieuwenhuisen, J. Stueckler, A. Berner, R. Klein and S. Behnke,
Shape-Primitive Based Object Recognition and Grasping,

[C227] J. Kläss, J. Stueckler and S. Behnke,
Efficient Mobile Robot Navigation using 3D Surfel Grid Maps,

[C228] J. Stueckler and S. Behnke,
Robust Real-Time Registration of RGB-D Images using Multi-Resolution Surfel Representations,

[C229] V. Usenko, F. Seidel, Z. Marton, D. Pangercic and M. Beetz,
Furniture Classification using WWW CAD Models,

[C230] F. R. Schmidt and Y. Boykov,
Hausdorff Distance Constraint for Multi-Surface Segmentation,

[C231] L. Gorelick, F. R. Schmidt, Y. Boykov, A. Delong and A. Ward,
Segmentation with non-linear regional constraints via line-search cuts,
All: 1

List of Publications

[C232] A. Torsello, E. Rodola and A. Albarelli,  
Multiview Registration via Graph Diffusion of Dual Quaternions,  
2441-2448, 2011.

[C233] F. Bergamasco, A. Albarelli, E. Rodola and A. Torsello,  
RUNE-Tag: a High Accuracy Fiducial Marker with Strong Occlusion Resilience,  
113-120, 2011.

[C234] A. Albarelli, E. Rodola and A. Torsello,  
A Non-Cooperative Game for 3D Object Recognition in Cluttered Scenes,  
International Conference on 3D Imaging, Modeling, Processing, Visualization and Transmission (3DIMPVT), 252-259, 2011.

[C235] A. Torsello, E. Rodola and A. Albarelli,  
Sampling Relevant Points for Surface Registration,  
International Conference on 3D Imaging, Modeling, Processing, Visualization and Transmission (3DIMPVT), 290-295, 2011.

[C236] T. Windheuser, U. Schlickewei, F. R. Schmidt and D. Cremers,  
Geometrically Consistent Elastic Matching of 3D Shapes: A Linear Programming Solution,  
2011.

[C237] M. Aubry, U. Schlickewei and D. Cremers,  
Pose-Consistent 3D Shape Segmentation Based on a Quantum Mechanical Feature Descriptor,  
Frankfurt, Germany, Springer, 2011.

[C238] T. Schoenemann, S. Masnou and D. Cremers,  
On a linear programming approach to the discrete Willmore boundary value problem and generalizations,  

[C239] E. Strekalovskiy and D. Cremers,  
Total Variation for Cyclic Structures: Convex Relaxation and Efficient Minimization,  

[C240] B. Goldluecke and D. Cremers,  
Introducing Total Curvature for Image Processing,  
2011.

[C241] E. Strekalovskiy, B. Goldluecke and D. Cremers,  
Tight Convex Relaxations for Vector-Valued Labeling Problems,  
2011.

[C242] M. Aubry, K. Kolev, B. Goldluecke and D. Cremers,  
Decoupling Photometry and Geometry in Dense Variational Camera Calibration,  
2011.

[C243] E. Strekalovskiy and D. Cremers,  
Generalized Ordering Constraints for Multilabel Optimization,  
2011.
All: 1

List of Publications

[C244] J. Hess, J. Sturm and W. Burgard,
Learning the State Transition Model to Efficiently Clean Surfaces with Mobile Manipulation Robots,
Proc. of the Workshop on Manipulation under Uncertainty at the IEEE Int. Conf. on Robotics and Automation (ICRA), Shanghai, China, May 2011.

[C245] N. Engelhard, F. Endres, J. Hess, J. Sturm and W. Burgard,
Real-time 3D visual SLAM with a hand-held camera,

Towards a benchmark for RGB-D SLAM evaluation,

[C247] C. Nieuwenhuis, E. Toeppe and D. Cremers,
Space-Varying Color Distributions for Interactive Multiregion Segmentation: Discrete versus Continuous Approaches,
177-190, 2011.

[C248] M. Klodt and D. Cremers,

[C249] M. Aubry, U. Schlickewei and D. Cremers,
The Wave Kernel Signature: A Quantum Mechanical Approach To Shape Analysis,
IEEE International Conference on Computer Vision (ICCV) - Workshop on Dynamic Shape Capture and Analysis (4DMOD), 2011.

[C250] F. Steinbruecker, J. Sturm and D. Cremers,
Real-Time Visual Odometry from Dense RGB-D Images,
Workshop on Live Dense Reconstruction with Moving Cameras at the Intl. Conf. on Computer Vision (ICCV), 2011.

Mobile Manipulation of Kitchen Containers,
Proc. of the IROS’11 Workshop on Results, Challenges and Lessons Learned in Advancing Robots with a Common Platform, San Francisco, CA, USA, 2011.

[C252] M. Schikora, M.Oispuu, W. Koch and D. Cremers,
Multiple Source Localization Based on Biased Bearings Using the Intensity Filter - Approach and Experimental Results,

[C253] S. Madhogaria, M. Schikora, W. Koch and D. Cremers,
Pixel-based Classification Method for Detecting Unhealthy Regions in Leaf Images,
6th IEEE ISIF Workshop on Sensor Data Fusion: Trends, Solutions, Applications (SDF), Berlin, Germany, September 2011.
[C254] M. Schikora, W. Koch, R.L. Streit and D. Cremers,
Sequential Monte Carlo Method for the iFilter,
14th International Conference on Information Fusion (FUSION), Chicago, IL, USA, July
2011.

[C255] M. Oispuu and M. Schikora,
Multiple Emitter Localization Using a Realistic Airborne Array Sensor,
14th International Conference on Information Fusion (FUSION), Chicago, IL, USA, July
2011.

[C256] M. Schikora, W. Koch and D. Cremers,
Multi-object tracking via high accuracy optical flow and finite set statistics,
International Conference on Acoustics, Speech and Signal Processing (ICASSP), Prag,
Czech Republic, Mai 2011.

[C257] E. Toeppe, M. R. Oswald, D. Cremers and C. Rother,
Silhouette-Based Variational Methods for Single View Reconstruction,
D. Cremers, M. A. Magnor, M. R. Oswald and L. Zelnik-Manor(Eds.), Proceedings of
the 2010 international conference on Video Processing and Computational Video, Berlin,

[C258] M. R. Oswald, E. Toeppe, C. Nieuwenhuis and D. Cremers,
A Survey on Geometry Recovery from a Single Image with Focus on Curved
Object Reconstruction,
Proceedings of the 2011 Conference on Innovations for Shape Analysis: Models and Algo-
rithms, Springer-Verlag, 2011.

[C259] J. Shin, R. Triebel and R. Siegwart,
Unsupervised 3D Object Discovery and Categorization for Mobile Robots,

[C260] J. Maye, R. Triebel, L. Spinello and R. Siegwart,
Bayesian On-line Learning of Driving Behaviors,
2011.

[C261] B. Oehler, J. Stueckler, J. Welle, D. Schulz and S. Behnke,
Efficient Multi-resolution Plane Segmentation of 3D Point Clouds,
Jeschke, Sabina, Liu, Honghai, Schilberg and Daniel(Eds.), Proc. of the Int. Conf. on
Intelligent Robotics and Applications (ICIRA), Springer Berlin Heidelberg, Lecture Notes

[C262] J. Stueckler and S. Behnke,
Following human guidance to cooperatively carry a large object,
Proc. of the 11th IEEE-RAS Int. Conf. on Humanoid Robots (Humanoids), 218-223, Oc-
tober 2011.

[C263] J. Stueckler, R. Steffens, D. Holz and S. Behnke,
Real-Time 3D Perception and Efficient Grasp Planning for Everyday Manipu-
lation Tasks.,
Proc. of the European Conf. on Mobile Robots (ECMR), 177-182, 2011.

[C264] J. Stueckler and S. Behnke,
Compliant Task-Space Control with Back-Drivable Servo Actuators,
Röfer, Thomas, Mayer, Norbert Michael, Savage, Jesus, Saranli and Uluc(Eds.), RoboCup,
[C265] D. Droeschel, J. Stueckler, D. Holz and S. Behnke,
Towards joint attention for a domestic service robot - person awareness and
gesture recognition using Time-of-Flight cameras,
*Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA)*, 1205-1210, May 2011.

[C266] J. Stueckler and S. Behnke,
Interest point detection in depth images through scale-space surface analysis,
*Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA)*, 3568-3574, May 2011.

[C267] D. Droeschel, J. Stueckler and S. Behnke,
Learning to Interpret Pointing Gestures with a Time-of-flight Camera,

[C268] F. R. Schmidt, H. Ackermann and B. Rosenhahn,
Multilinear Model Estimation with L2-Regularization,

[C269] A. Delong, L. Gorelick, F. R. Schmidt, O. Veksler and Y. Boykov,
Interactive Segmentation with Super-Labels,

[C270] A. Albarelli, E. Rodola and A. Torsello,
Robust Camera Calibration using Inaccurate Targets, 2010.

[C271] E. Rodola, A. Albarelli and A. Torsello,
A Game-Theoretic Approach to Robust Selection of Multi-View Point Correspondence,
*20th International Conference on Pattern Recognition (ICPR)*, 57-60, 2010.

[C272] A. Albarelli, E. Rodola, A. Cavallarin and A. Torsello,
Robust Figure Extraction on Textured Background: a Game-Theoretic Approach,

[C273] E. Rodola, A. Albarelli and A. Torsello,
A Game-Theoretic Approach to the Enforcement of Global Consistency in Multi-View Feature Matching,

[C274] A. Albarelli, E. Rodola and A. Torsello,
A Game-Theoretic Approach to Fine Surface Registration without Initial Motion Estimation,

[C275] A. Albarelli, E. Rodola and A. Torsello,
Robust Game-Theoretic Inlier Selection for Bundle Adjustment,
*5th International Symposium on 3D Data Processing, Visualization and Transmission (3DPVT)*, 2010, Best Student Paper Award.

[C276] A. Albarelli, E. Rodola and A. Torsello,
Loosely Distinctive Features for Robust Surface Alignment, 519-532, 2010.
List of Publications

[C277] M. Schikora, A. Schikora, K.-H. Kogel, W. Koch and D. Cremers,
Probabilistic Classification of Disease Symptoms caused by Salmonella on Arabidopsis Plants,
5th IEEE ISIF Workshop on Sensor Data Fusion: Trends, Solutions, Applications (SDF), Leipzig, Germany, September 2010.

[C278] M. Schikora, D. Bender, D. Cremers and W. Koch,
Passive Multi-Object Localization and Tracking Using Bearing Data,

[C279] M. Schikora, D. Bender, W. Koch and D. Cremers,
Multi-target multi-sensor localization and tracking using passive antenna and optical sensors on UAVs,

[C280] E. Toeppe, M. R. Oswald, D. Cremers and C. Rother,
Image-based 3D Modeling via Cheeger Sets,
Queenstown, New Zealand, 53-64, November 2010, Received Honorable Mention Award.

[C281] J. Stühmer, S. Gumhold and D. Cremers,
Real-Time Dense Geometry from a Handheld Camera,
Darmstadt, Germany, 11-20, September 2010.

[C282] J. Stühmer, S. Gumhold and D. Cremers,
Parallel Generalized Thresholding Scheme for Live Dense Geometry from a Handheld Camera,
ECCV Workshop on Computer Vision on GPUs (CVGPU), Heraklion, Greece, September 2010.

[C283] B. Goldluecke and D. Cremers,
An Approach to Vectorial Total Variation based on Geometric Measure Theory,
2010.

[C284] B. Goldluecke and D. Cremers,
Convex Relaxation for Multilabel Problems with Product Label Spaces,
2010.

[C285] C. Nieuwenhuis and D. Kondermann,
Complex Motion Models for Simple Optical Flow Estimation,

[C286] C. Nieuwenhuis, B. Berkels and M. Rumpf,
Interactive Motion Segmentation,

[C287] J. Sturm, K. Konolige, C. Stachniss and W. Burgard,
3D Pose Estimation, Tracking and Model Learning of Articulated Objects from Dense Depth Video using Projected Texture Stereo,
[C288] J. Sturm, K. Konolige, C. Stachniss and W. Burgard, 
Vision-based Detection for Learning Articulation Models of Cabinet Doors and Drawers in Household Environments, 

[C289] S. Chitta, M. Piccoli and J. Sturm, 
Tactile Object Class and Internal State Recognition for Mobile Manipulation, 

[C290] J. Sturm, A. Jain, C. Stachniss, C. C. Kemp and W. Burgard, 
Operating Articulated Objects Based on Experience, 

[C291] R. Kaestner, N. Engelhard, R. Triebel and R. Siegwart, 
A Bayesian Approach to Learning 3D Representations of Dynamic Environments, 

[C292] L. Spinello, R. Triebel, D. Vasquez, K. Arras and R. Siegwart, 
Exploiting Repetitive Object Patterns for Model Compression and Completion, 

[C293] R. Triebel, J. Shin and R. Siegwart, 
Segmentation and Unsupervised Part-based Discovery of Repetitive Objects, 

[C294] L. Spinello, K. O. Arras, R. Triebel and R. Siegwart, 
A Layered Approach to People Detection in 3D Range Data, 
special track on Physically Grounded AI of AAAI, 2010.

[C295] J. Shin, R. Triebel and R. Siegwart, 
Unsupervised Discovery of Repetitive Objects, 
2010.

[C296] J. Maye, L. Spinello, R. Triebel and R. Siegwart, 
Inferring the Semantics of Direction Signs in Public Places, 
2010.

[C297] K. Gräve, J. Stueckler and S. Behnke, 
Improving imitated grasping motions through interactive expected deviation learning, 
Proc. of the 10th IEEE-RAS Int. Conf. on Humanoid Robots (Humanoids), 397-404, December 2010.

[C298] J. Stueckler and S. Behnke, 
Combining depth and color cues for scale- and viewpoint-invariant object segmentation and recognition using Random Forests, 
Proc. of the IEEE/RSJ Int. Conf. on Intelligent Robots and Systems (IROS), 4566-4571, October 2010.
J. Stueckler and S. Behnke, 

D. Holz, R. Schnabel, D. Droeschel, J. Stueckler and S. Behnke, 

H. Schulz, W. Liu, J. Stueckler and S. Behnke, 

K. Gräve, J. Stueckler and S. Behnke, 

M. Nieuwenhuisen, J. Stueckler and S. Behnke, 

M. Nieuwenhuisen, J. Stueckler and S. Behnke, 
*Improving indoor navigation of autonomous robots by an explicit representation of doors*, *Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA)*, 4895-4901, May 2010.

D. Droeschel, D. Holz, J. Stueckler and S. Behnke, 

Mösenlechner, Lorenz, Demmel, Nikolaus, Beetz and Michael, 
*Becoming action-aware through reasoning about logged plan execution traces*, 2231-2236, 2010.

A. Albarelli, E. Rodola, S. Rota Bulo and A. Torsello, 

M. R. Oswald, E. Toeppe, K. Kolev and D. Cremers, 
*Non-Parametric Single View Reconstruction of Curved Objects using Convex Optimization*, Jena, Germany, 171-180, September 2009, Received a DAGM Paper Award.

F. R. Schmidt and D. Cremers, 
*A Closed-Form Solution for Image Sequence Segmentation with Dynamical Shape Priors*, Jena, Germany, September 2009.
**List of Publications**


[C323] C. Eppner, J. Sturm, M. Bennewitz, C. Stachniss and W. Burgard, 
Imitation Learning with Generalized Task Descriptions, 
Kobe, Japan, May 2009.

[C324] H. Schulz, L. Ott, J. Sturm and W. Burgard, 
Learning Kinematics from Direct Self-Observation Using Nearest-Neighbor Methods, 

[C325] J. Sturm, C. Stachniss, V. Pradeep, C. Plagemann, K. Konolige and W. Burgard, 
Towards Understanding Articulated Objects, 

[C326] J. Sturm, V. Pradeep, C. Stachniss, C. Plagemann, K. Konolige and W. Burgard, 
Learning Kinematic Models for Articulated Objects, 
Proc. of the International Joint Conference on Artificial Intelligence (IJCAI), July 2009.

[C327] D. Meyer-Delius, J. Sturm and W. Burgard, 
Regression-Based Online Situation Recognition for Vehicular Traffic Scenarios, 

[C328] A. Schneider, J. Sturm, C. Stachniss, M. Reisert, H. Burkhardt and W. Burgard, 
Object Identification with Tactile Sensors Using Bag-of-Features, 

[C329] F. Steinbruecker, T. Pock and D. Cremers, 
Advanced Data Terms for Variational Optic Flow Estimation, 
Braunschweig, Germany, 2009.

[C330] M. Schikora and B. Romba, 
A Framework for Multiple Radar and Multiple 2D/3D Camera Fusion, 
4th IEEE ISIF Workshop on Sensor Data Fusion: Trends, Solutions, Applications (SDF), Luebeck, Germany, October 2009.

[C331] M. Schikora, 
Global Optimal Multiple Object Detection using the Fusion of Shape and Color Information, 
7th International Conference on Energy Minimization Methods in Computer Vision and Pattern Recognition (EMMCVPR), Bonn, Germany, August 2009.

[C332] M. Schikora, M. Häge, E. Ruthotto and K. Wild, 
A Convex Formulation for Color Image Segmentation in the Context of Passive Emitter Localization, 
12th International Conference on Information Fusion (FUSION), Seattle, WA, USA, July 2009.

[C333] L. Spinello, A. Macho, R. Triebel and R. Siegwart, 
Detecting Pedestrians at Very Small Scales, 

[C334] L. Spinello, R. Triebel and R. Siegwart, 
Multiclass Multimodal Detection and Tracking in Urban Environments, 
Proc. of Field and Service Robotics (FSR), 2009.
All: 1

List of Publications

[C335] D. Engel, L. Spinello, R. Triebel, C. Curio, R. Siegwart and H. Bülthoff,
Medial Features for Superpixel Segmentation,

[C336] J. Stueckler and S. Behnke,
Integrating indoor mobility, object manipulation, and intuitive interaction for
domestic service tasks,
Proc. of the IEEE-RAS Int. Conf. on Humanoid Robots (Humanoids), 506-513, December
2009.

[C337] J. Stueckler, M. Schreiber and S. Behnke,
Dynamaid, an Anthropomorphic Robot for Research on Domestic Service Ap-
plications,

[C338] T. Schoenemann, F. R. Schmidt and D. Cremers,
Image Segmentation with Elastic Shape Priors via Global Geodesics in Product
Spaces,

[C339] T. Pock, T. Schoenemann, G. Graber, H. Bischof and D. Cremers,
A Convex Formulation of Continuous Multi-Label Problems,
Marseille, France, October 2008.

Efficient Dense Scene Flow from Sparse or Dense Stereo Data,
Marseille, France, October 2008.

[C341] A. Wedel, T. Pock, J. Braun, U. Franke and D. Cremers,
Duality TV-L1 Flow with Fundamental Matrix Prior,

[C342] M. Klodt, T. Schoenemann, K. Kolev, M. Schikora and D. Cremers,
An Experimental Comparison of Discrete and Continuous Shape Optimization
Methods,
European Conference on Computer Vision (ECCV), Marseille, France, October 2008.

[C343] A. Wedel, T. Pock, C. Zach, D. Cremers and H. Bischof,
An Improved Algorithm for TV-L1 Optical Flow,

[C344] W. Trobin, T. Pock, D. Cremers and H. Bischof,
An Unbiased Second-Order Prior for High-Accuracy Motion Estimation,
Munich, Germany, Springer, , June 2008.

Markerless Motion Capture of Man-Machine Interaction,
Anchorage, Alaska, June 2008.

[C346] T. Schoenemann and D. Cremers,
Matching Non-rigidly Deformable Shapes Across Images: A Globally Optimal
Solution,
Anchorage, Alaska, June 2008.
All: 1  List of Publications

[C347] T. Schoenemann and D. Cremers,
Globally Optimal Shape-based Tracking in Real-time,
Anchorage, Alaska, June 2008.

[C348] T. Schoenemann and D. Cremers,
High Resolution Motion Layer Decomposition using Dual-space Graph Cuts,
Anchorage, Alaska, June 2008.

[C349] B. Rosenhahn, T. Brox, D. Cremers and H.-P. Seidel,
Modeling and Tracking Line-Constrained Mechanical Systems,

[C350] O. Kleinschmidt, T. Brox and D. Cremers,
Nonlocal texture filtering with efficient tree structures and invariant patch similarity measures,
Int. Workshop on Local and Nonlocal Approximation, Lausanne, Switzerland, August 2008.

[C351] C. Nieuwenhuis, R. Mester and C. Garbe,
A Statistical Confidence Measure for Optical Flows,
Marseille, France, 290-301, October 2008.

[C352] B. Andres, C. Nieuwenhuis, D. Kondermann, U. Köthe and R. Hamprecht,
On Errors-In-Variables Regression with Arbitrary Covariance and its Application to Optical Flow Estimation,
Anchorage, Alaska, 1-6, June 2008.

[C353] C. Nieuwenhuis, D. Kondermann and C. Garbe,
Postprocessing of Optical Flows via Surface Measures and Motion Inpainting,

[C354] J. Sturm, C. Plagemann and W. Burgard,
Unsupervised Body Scheme Learning through Self-Perception,

[C355] J. Sturm, C. Plagemann and W. Burgard,
Adaptive Body Scheme Models for Robust Robotic Manipulation,
Robotics: Science and Systems Conference (RSS), Zurich, Switzerland, June 2008.

[C356] J. Sturm, C. Plagemann and W. Burgard,
Body Scheme Learning and Life-Long Adaptation for Robotic Manipulation,

[C357] Kondermann, D., Nieuwenhuis, C., Berthe, A., Kertzschger, U., Garbe and C.,
Motion Estimation Based on a Temporal Model of Fluid Flows,

[C358] L. Spinello, R. Triebel and R. Siegwart,
Multimodal Detection and Tracking of Pedestrians in Urban Environments with Explicit Ground Plane Extraction,

[C359] L. Spinello, R. Triebel and R. Siegwart,
Multimodal People Detection and Tracking in Crowded Scenes,
[C360] J. Stueckler, H. Schulz and S. Behnke,
**In-lane Localization in Road Networks using Curbs Detected in Omnidirectional Height Images,**

[C361] J. Stueckler and S. Behnke,
**Orthogonal wall correction for visual motion estimation,**
*Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA)*, 1-6, May 2008.

[C362] S. Frintrop, M. Klodt and E. Rome,
**A Real-time Visual Attention System Using Integral Images,**
5th International Conference on Computer Vision Systems (ICVS 2007), Bielefeld, Germany, March 2007.

[C363] S. May, M. Klodt, E. Rome and R. Breithaupt,
**GPU-accelerated Affordance Cueing based on Visual Attention,**

[C364] K. Kolev, M. Klodt, T. Brox and D. Cremers,
**Propagated Photoconsistency and Convexity in Variational Multiview 3D Reconstruction,**

[C365] K. Kolev, M. Klodt, T. Brox, S. Esedoglu and D. Cremers,
**Continuous Global Optimization in Multiview 3D Reconstruction,**

[C366] T. Brox, B. Rosenhahn, D. Cremers and H.-P. Seidel,
**Nonparametric density estimation with adaptive anisotropic kernels for human motion tracking,**

[C367] T. Schoenemann and D. Cremers,
**Globally Optimal Image Segmentation with an Elastic Shape Prior,**
Rio de Janeiro, Brazil, October 2007.

[C368] T. Schoenemann and D. Cremers,
**Introducing Curvature into Globally Optimal Image Segmentation: Minimum Ratio Cycles on Product Graphs,**
Rio de Janeiro, Brazil, October 2007.

[C369] F. R. Schmidt, Dirk Farin and D. Cremers,
**Fast Matching of Planar Shapes in Sub-cubic Runtime,**
Rio de Janeiro, Brazil, October 2007.

[C370] F. R. Schmidt, E. Toeppe, D. Cremers and Y. Boykov,
**Intrinsic Mean for Semimetrical Shape Retrieval via Graph Cuts,**

[C371] A. Wedel and U. Franke,
**Monocular Video Serves RADAR-based Emergency Braking,**
*Intelligent Vehicles*, Istanbul, Turkey, June 2007.
A. Wedel, T. Schoenemann, T. Brox and D. Cremers, 
WarpCut - Fast obstacle segmentation in monocular video, 

B. Rosenhahn, T. Brox, D. Cremers and H.-P. Seidel, 
Online smoothing for markerless motion capture, 

F. R. Schmidt, E. Toeppe, D. Cremers and Y. Boykov, 
Efficient Shape Matching via Graph Cuts, 

B. Rosenhahn, T. Brox and H.-P. Seidel, 
Scaled motion dynamics for markerless motion capture, 
2007.

D. Cremers, 
Nonlinear Dynamical Shape Priors for Level Set Segmentation, 
2007.

T. Brox and D. Cremers, 
On the Statistical Interpretation of the Piecewise Smooth Mumford-Shah Functional, 

C. Schmaltz, B. Rosenhahn, T. Brox, D. Cremers, J. Weickert, L. Wietzke and G. Sommer, 
Region-based Pose Tracking, 

D. Cremers, O. Fluck, M. Rousson and S. Aharon, 
A probabilistic level set formulation for interactive organ segmentation, 

C. Nieuwenhuis, D. Kondermann and B. Jähne, 
An Adaptive Confidence Measure for Optical Flows Based on Linear Subspace Projections, 

C. Nieuwenhuis, D. Kondermann and M. Yan, 
Blood vessel classification into arteries and veins in retinal images, 

R. Triebel, O. Martinez Mozos and W. Burgard, 
Collective Classification for Labeling of Places and Objects in 2D and 3D Range Data, 

R. Kümmerle, P. Pfaff, R. Triebel and W. Burgard, 
Active Monte Carlo Localization in Outdoor Terrains using Multi-Level Surface Maps, 
Fachgespräche Autonome Mobile Systeme (AMS), 2007.
[C384] R. Triebel and W. Burgard,
Recovering the Shape of Objects in 3D Point Clouds with Partial Occlusions,

[C385] R. Kümmerle, R. Triebel, P. Pfaff, and W. Burgard,
Monte Carlo Localization in Outdoor Terrains using Multi-Level Surface Maps,

[C386] P. Pfaff, R. Triebel, C. Stachniss, P. Lamon, W. Burgard and R. Siegwart,
Towards Mapping of Cities,
2007.

[C387] R. Triebel, R. Schmidt, O. Martinez Mozos and W. Burgard,
Instance-based AMN Classification for Improved Object Recognition in 2D
and 3D Laser Range Data,

Hierarchical reactive control for a team of humanoid soccer robots,
Proc. of the IEEE-RAS Int. Conf. on Humanoid Robots (Humanoids), 622-629, November 2007.

Learning for multi-view 3D tracking in the context of particle filters,

[C390] F. R. Schmidt, M. Clausen and D. Cremers,
Shape Matching by Variational Computation of Geodesics on a Manifold,

[C391] T. Schoenemann and D. Cremers,
Near Real-time Motion Segmentation using Graph Cuts,

[C392] T. Brox, B. Rosenhahn, U. Kersting and D. Cremers,
Nonparametric density estimation for human pose tracking,

[C393] A. Wedel, U. Franke, J. Klappstein, T. Brox and D. Cremers,
Realtime depth estimation and obstacle detection from monocular video,

[C394] Y. Boykov, V. Kolmogorov, D. Cremers and A. Delong,
An integral solution to surface evolution PDEs via Geo-Cuts,

[C395] B. Rosenhahn, T. Brox, D. Cremers and H.-P. Seidel,
A comparison of shape matching methods for contour based pose estimation,
T. Brox, A. Bruhn and J. Weickert, 
Variational motion segmentation with level sets,

T. Brox, B. Rosenhahn, D. Cremers and H.-P. Seidel,
High accuracy optical flow serves 3-D pose tracking: exploiting contour and flow based constraints,

T. Brox, Y.-J. Kim, J. Weickert and W. Feiden,
Fully-automated analysis of muscle fiber images with combined region and edge based active contours,

D. Cremers and L. Grady,
Statistical priors for combinatorial optimization: efficient solutions via Graph Cuts,

D. Cremers, C. Guetter and C. Xu,
Nonparametric priors on the space of joint intensity distributions for non-rigid multi-modal image registration,

O. Fluck, S. Aharon, D. Cremers and M. Rousson,
GPU histogram computation,
2006.

T. Kohlberger, D. Cremers, M. Rousson and R. Ramaraj,
4D shape priors for level set segmentation of the left myocardium in SPECT sequences,
, Vol. 4190, 92-100, October 2006.

C. Nieuwenhuis and M. Yan,
Knowledge Based Image Enhancement Using Neural Networks,

D. A. van Soest, M. de Greef, J. Sturm and A. Visser,
Autonomous Color Learning in an Artificial Environment,

J. Sturm, P. van Rossum and A. Visser,
Panoramic Localization in the 4-Legged League,

A. Visser, J. Sturm and F.C.A. Groen,
Robot companion localization at home and in the office,


M. Welk, D. Theis, T. Brox and J. Weickert,
**PDE based deconvolution with forward-backward diffusivities and diffusion tensors**, 

B. Goldluecke and M. Magnor,
**Spacetime-Continous Geometry Meshes from Multi-View Video Sequences**, 

I. Ihrke, B. Goldluecke and M. Magnor,
**Reconstructing the Geometry of Flowing Water**, 

N. Wijngaards, F. Dignum, P. Jonker, T. de Ridder, A. Visser, S. Leijnen and J. Sturm,
**Dutch AIBO Team at RoboCup 2005**, 

H. Andreasson, R. Triebel and W. Burgard,
**Improving Plane Extraction from 3D Data by Fusing Laser Data and Vision**, 

R. Triebel and W. Burgard,
**Improving Simultaneous Localization and Mapping in 3D Using Global Constraints**, 
*Proc. of the Twentieth National Conference on Artificial Intelligence (AAAI)*, 2005.

R. Triebel, W. Burgard and F. Dellaert,
**Using Hierarchical EM to Extract Planes from 3D Range Scans**, 
2005.

T. Brox, A. Bruhn, N. Papenberg and J. Weickert,
**High accuracy optical flow estimation based on a theory for warping**, 

T. Brox and J. Weickert,
**A TV flow based local scale measure for texture discrimination**, 

T. Brox and J. Weickert,
**Level set based segmentation of multiple objects**, 

D. Cremers, S. J. Osher and S. Soatto,
**Kernel density estimation and intrinsic alignment for knowledge-driven segmentation: Teaching level sets to walk**, 
D. Cremers, N. Sochen and C. Schnörr,
Multiphase dynamic labeling for variational recognition-driven image segmentation,

H. Jin, D. Cremers, A. Yezzi and S. Soatto,
Shedding light on stereoscopic segmentation,

M. Magnor and B. Goldluecke,
Spacetime-coherent Geometry Reconstruction from Multiple Video Streams,

B. Goldluecke and M. Magnor,
Weighted Minimal Hypersurfaces and Their Applications in Computer Vision,

B. Goldluecke and M. Magnor,
Space-Time Isosurface Evolution for Temporally Coherent 3D Reconstruction,

R. Triebel, B. Frank, J. Meyer and W. Burgard,
First steps towards a robotic system for flexible volumetric mapping of indoor environments,

T. Brox, M. Rousson, R. Deriche and J. Weickert,
Unsupervised segmentation incorporating colour, texture, and motion,

T. Brox, M. Welk, G. Steidl and J. Weickert,
Equivalence results for TV diffusion and TV regularisation,

D. Cremers,
A variational framework for image segmentation combining motion estimation and shape regularization,

D. Cremers,
A multiphase level set framework for variational motion segmentation,

D. Cremers and S. Soatto,
A pseudo-distance for shape priors in level set segmentation,
[C440] D. Cremers and S. Soatto,
Variational space-time motion segmentation,

[C441] D. Cremers, N. Sochen and C. Schnörr,
Towards Recognition-based Variational Segmentation Using Shape Priors and Dynamic Labeling,

[C442] D. Cremers and A. L. Yuille,
A generative model based approach to motion segmentation,

[C443] G. Doretto, D. Cremers, P. Favaro and S. Soatto,
Dynamic texture segmentation,

[C444] M. Rousson, T. Brox and R. Deriche,

[C445] B. Goldluecke and M. Magnor,
Joint 3D Reconstruction and Background Separation in Multiple Views using Graph Cuts,

[C446] B. Goldluecke and M. Magnor,
Real-time Microfacet Billboarding for Free-viewpoint Video Rendering,

[C447] B. Goldluecke and M. Magnor,
Real-time, Free-viewpoint Video Rendering from Volumetric Geometry,

[C448] C. Petz, B. Goldluecke and M. Magnor,
Hardware-accelerated Autostereogram Rendering for Interactive 3D Visualization,

A system for volumetric robotic mapping of underground mines,

[C450] D. Hähnel, R. Triebel, W. Burgard and S. Thrun,
Map Building with Mobile Robots in Dynamic Environments,

[C451] T. Brox and J. Weickert,
Nonlinear matrix diffusion for optic flow estimation,
J. Keuchel, C. Schnörr, C. Schellewald and D. Cremers, 
**Unsupervised Image Partitioning with Semidefinite Programming**, 

D. Cremers, T. Kohlberger and C. Schnörr, 
**Nonlinear shape statistics in Mumford–Shah based segmentation**, 

D. Cremers and C. Schnörr, 
**Motion Competition: variational integration of motion segmentation and shape regularization**, 

D. Cremers and C. Schnörr, 
**Statistical shape knowledge in variational motion segmentation**, 
A. Pece, Y. N. Wu and R. Larsen(Eds.), *1st Internat. Workshop on Generative-Model-Based Vision*, Copenhagen, Univ. of Copenhagen, June, 2 2002.

D. Cremers and T. Brox, 
**Diffusion and regularization of vector- and matrix-valued images**, 

B. Goldluecke, M. Magnor and B. Wilburn, 

T. Brox, D. Farin and P. H. N. de With, 
**Multi-stage region merging for image segmentation**, 

D. Cremers, T. Kohlberger and C. Schnörr, 
**Nonlinear shape statistics via kernel spaces**, 

J. Keuchel, C. Schellewald, D. Cremers and C. Schnoerr, 
**Convex Relaxations for Binary Image Partitioning and Perceptual Grouping**, 
Radig, B., Florczyk and S.(Eds.), *Pattern Recognition*, Munich, Germany, Springer, , Vol. 2191, 353-360, Sept. 2001, Received a DAGM Paper Award.

D. Cremers, C. Schnörr and J. Weickert, 
**Diffusion Snakes: Combining statistical shape knowledge and image information in a variational framework**, 
N. Paragios(Ed.), *IEEE First Int. Workshop on Variational and Level Set Methods*, Vancouver, 137-144, 2001, Best Student Paper Award.

D. Cremers, C. Schnörr, J. Weickert and C. Schellewald, 
**Learning of translation invariant shape knowledge for steering diffusion snakes**, 
All: 1 List of Publications

[C463] D. Cremers, C. Schnörr, J. Weickert and C. Schellewald,
Diffusion Snakes using statistical shape knowledge,

PhDThesis

[PhD1] J. Stueckler,
Efficient Dense Registration, Segmentation, and Modeling Methods for RGB-D Environment Perception,
Faculty of Mathematics and Natural Sciences, University of Bonn, Germany, 2014.

[PhD2] K. Kolev,
Convexity in Image-Based 3D Surface Reconstruction,
Department of Computer Science, Technical University Munich, Germany, January 2012.

[PhD3] J. Sturm,
Approaches to Probabilistic Model Learning for Mobile Manipulation Robots,
University of Freiburg, Germany, May 2011, Received the Artificial Intelligence Dissertation Award 2011 (ECCAI) and the Wolfgang-Genter-Award 2011 (University of Freiburg); Finalist at the Georges-Giralt-Award 2012 (EURON); Selected for the Best Paper Track at IJCAI 2013.

[PhD4] C. Nieuwenhuis,
Restoration and Prostprocessing of Optical Flows,
Faculty of Mathematics and Computer Science, Heidelberg University, Germany, July 2009.

[PhD5] T. Schoenemann,
Combinatorial Solutions for Shape Optimization in Computer Vision,
Department of Computer Science, University of Bonn, Germany, 2008.

[PhD6] B. Goldluecke,
Multi-Camera Reconstruction and Rendering for Free-viewpoint Video,
Max-Planck-Institute for Computer Science, Saarbrücken, Germany, July 2006.

[PhD7] T. Brox,
From pixels to regions: partial differential equations in image analysis,
Faculty of Mathematics and Computer Science, Saarland University, Germany, April 2005.

[PhD8] D. Cremers,
Statistical shape knowledge in variational image segmentation,
Department of Mathematics and Computer Science, University of Mannheim, Germany, 2002.

MastersThesis

[M1] K. Knese,
Realizing Online (Self-)Collision Avoidance Based on Inequality Constraints with Hierarchical Inverse Kinematics,
Technical University of Munich, Germany, July 2014.
[M2] Caner Hazirbas,  
Feature Selection and Learning for Semantic Segmentation,  
Technical University Munich, Germany, June 2014.

[M3] Thomas Schöps,  
Semi-dense visual SLAM on mobile devices,  
Technical University Munich, Germany, May 2014.

[M4] M. Shelley,  
Monocular Visual Inertial Odometry on a Mobile Device,  
Technical University Munich, Germany, Aug. 2014.

[M5] Oliver Montague Welton Dunkley,  
Visual Inertial Control of a Nano-Quadrotor,  
Technical University Munich, Germany, Sept. 2014.

[M6] R. Maier,  
Out-of-Core Bundle Adjustment for 3D Workpiece Reconstruction,  
Technische Universität München, Germany, September 2013.

[M7] M. Brandl,  
Face recognition with wave kernel signatures using a depth camera,  
Technical University of Munich, Germany, Aug. 2012.

[M8] C. Kerl,  
Odometry from RGB-D Cameras for Autonomous Quadrocopters,  
Technical University Munich, Germany, Nov. 2012.

[M9] J. Engel,  
Autonomous Camera-Based Navigation of a Quadrocopter,  
Technical University Munich, Germany, Dec. 2011, Distinguished with the SIEMENS award for best Master’s Thesis 2012.

[M10] M. Souiai,  
Newton Methods for Total Variation Minimization,  
Computer Vision Group, TU Munich, Germany, June 2010.

[M11] J. Stühmer,  
Ein Variationsansatz zur Schätzung von dichten Tiefenkarten im Kontext des Structure-from-Motion,  
TU Dresden, Germany, July 2010.

[M12] E. Toeppe,  
Shape Matching mittels Graph Cuts,  
University of Bonn, 2008, Awarded Best Master Thesis of the Year (Bonn Society for Computer Science).

[M13] M. R. Oswald,  
Reliability Estimation Methods and their Efficient Implementation,  
Universidad Tecnica Federico Santa Maria, Valparaiso, Chile, June 2008.

[M14] M. R. Oswald,  
Concurrent Stereo Reconstruction,  
Technische Universität Dresden, Germany, June 2007.
[M15] A. Wedel, 
Detektion stationärer Hindernisse in monokularen Bildsequenzen, 
Computer Vision Group, University of Bonn, Germany, April 2006.

[M16] J. Sturm, 
An appearance-based Visual Compass for Mobile Robots, 
University of Amsterdam, the Netherlands, Dec. 2006.

[M17] T. Brox, 
Smoothing of matrix-valued data, 
Department of Mathematics and Computer Science, University of Mannheim, Germany, 
May 2002.

[M18] B. Goldhache, 
Nichtkonforme Finite Elemente und Kollokation für elliptische Randwertprobleme, 

Technical Reports

[R1] M. Souiai, E. Strekalovskiy, C. Nieuwenhuis and D. Cremers, 
Label Configuration Priors for Continuous Multi-Label Optimization, 

[R2] A. Chambolle, D. Cremers and T. Pock, 
A Convex Approach for Computing Minimal Partitions, 
Technical report TR-2008-05, Dept. of Computer Science, University of Bonn, Bonn, Germany, 
November 2008.

[R3] T. Brox, O. Kleinschmidt and D. Cremers, 
Iterated and Efficient Nonlocal Means for Denoising of Textural Patterns, 
Technical report TR-2007-04, Dept. of Computer Science, University of Bonn, Bonn, Germany, 
August 2007.

[R4] A. Visser, J. Sturm, P. van Rossum, J. Westra and T. Bink, 
Dutch Aibo Team: Technical Report RoboCup 2006, 

[R5] T. Brox, M. Rousson, R. Deriche and J. Weickert, 
Colour, texture, and motion in level set based segmentation and tracking, 
Technical report 147, Dept. of Mathematics, Saarland University, Saarbrücken, Germany, 
August 2005.

[R6] B. Rosenhahn, U. Kersting, L. He, A. Smith, T. Brox, R. Klette and H. P. Seidel, 
A silhouette based human motion tracking system, 

[R7] J. Sturm, A. Visser and N. Wijngaards, 
Dutch Aibo Team: Technical Report RoboCup 2005, 
[R8] D. Cremers, C. Schnörr, J. Weickert and C. Schellewald,
Diffusion Snakes using statistical shape knowledge,