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[C15] C. Sommer, V. Usenko, D. Schubert, N. Demmel and D. Cremers, 
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[C16] P. Brechet, T. Wu, T. Möllenhoff and D. Cremers, 
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Discrete-Continuous ADMM for Transductive Inference in Higher-Order MRFs,
2018.

[C27] L. von Stumberg, V. Usenko and D. Cremers,
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The TUM VI Benchmark for Evaluating Visual-Inertial Odometry,
October 2018.

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[C31] D. Schubert, N. Demmel, V. Usenko, J. Stueckler and D. Cremers,
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September 2018, Oral Presentation.

[C32] V. Usenko, N. Demmel and D. Cremers,
The Double Sphere Camera Model,

[C33] I. Chiotellis, F. Zimmermann, D. Cremers and R. Triebel,
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[C34] M. Brucker, M. Durner, Z.-C. Marton, F. Balint-Benczéd, M. Sundermeyer and R. Triebel,
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[C59] T. Möllenhoff and D. Cremers,
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[C65] A. Kasyanov, F. Engelmann, J. Stueckler and B. Leibe,
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[C66] F. Engelmann, J. Stueckler and B. Leibe,
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[C67] Peng, S., Haefner, B., Queau, Y., Cremers and D.,
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[C72] A. Narr, R. Triebel and D. Cremers,
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A. Kanezaki, E. Rodola and T. Harada,
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2015.

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M. Jaimez, M. Souiai, J. Stueckler, J. Gonzalez-Jimenez and D. Cremers, 
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Improved Diffusion Kurtosis Imaging and Direct Propagator Estimation Using 
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Figure-Ground Segmentation, 
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[C123] J. Engel, T. Schöps and D. Cremers, 
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[C135] M. Andreux, E. Rodola, M. Aubry and D. Cremers,
Anisotropic Laplace-Beltrami Operators for Shape Analysis,
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[C142] J. Stueckler and S. Behnke,
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ference on Robotics (ROBOTIK), to appear, June 2014.

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[C155] V. Golkov, T. Sprenger, M.I. Menzel, D. Cremers and J.I. Sperl,
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[C162] E. Toeppe, C. Nieuwenhuis and D. Cremers,
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Portland, USA, 2013.

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[C179] J. Sturm, E. Bylow, F. Kahl and D. Cremers, 
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