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[C44] V. Usenko, N. Demmel and D. Cremers, 
The Double Sphere Camera Model, 

[C45] I. Chiotellis, F. Zimmermann, D. Cremers and R. Triebel, 
Incremental Semi-Supervised Learning from Streams for Object Classification, 

6DoF Pose Estimation for Industrial Manipulation based on Synthetic Data, 
International Symposium on Experimental Robotics (ISER), Buenos Aires, Argentina, 
Nov. 2018.

[C47] C. Nissler, M. Durner, Z.-C. Marton and R. Triebel, 
Simultaneous Calibration and Mapping, 
International Symposium on Experimental Robotics (ISER), Buenos Aires, Argentina, 
Nov. 2018.

[C48] P. Wenzel, Q. Khan, D. Cremers and L. Leal-Taixe, 
Modular Vehicle Control for Transferring Semantic Information Between Weather Conditions Using GANs, 
Conference on Robot Learning (CoRL), 2018.

[C49] Haefner, B., Queau, Y., Möllenhoff, T., Cremers and D., 
Fight ill-posedness with ill-posedness: Single-shot variational depth super-resolution from shading, 

[C50] I. Grixa, P. Schulz, W. Stürzl and R. Triebel, 
Appearance-Based Along-Route Localization for Planetary Missions, 

[C51] M. Sundermeyer, Z. Marton, M. Durner, M. Brucker and R. Triebel, 
Implicit 3D Orientation Learning for 6D Object Detection from RGB Images, 
September 2018, Best Paper Award.

[C52] M. Denninger and R. Triebel, 
Persistent Anytime Learning of Objects from Unseen Classes, 
[C53] M. Jaimez, C. Kerl, J. Gonzalez-Jimenez and D. Cremers,
Fast Odometry and Scene Flow from RGB-D Cameras based on Geometric Clustering,
Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA), 2017.

[C54] M. Jaimez, T. J. Cashman, A. Fitzgibbon, J. Gonzalez-Jimenez and D. Cremers,
An Efficient Background Term for 3D Reconstruction and Tracking with Smooth Subdivision Surface Models,
2017.

[C55] L. Ma, J. Stueckler, C. Kerl and D. Cremers,
Multi-View Deep Learning for Consistent Semantic Mapping with RGB-D Cameras,
Vancouver, Canada, Sep 2017.

[C56] Vestner, M., Litman, R., Rodola, E., Bronstein, A., Cremers and D.,
Product Manifold Filter: Non-Rigid Shape Correspondence via Kernel Density Estimation in the Product Space,
2017.

[C57] M. Dzitsiuk, J. Sturm, R. Maier, L. Ma and D. Cremers,
De-noising, Stabilizing and Completing 3D Reconstructions On-the-go using Plane Priors,

[C58] L. von Stumberg, V. Usenko, J. Engel, J. Stueckler and D. Cremers,
From Monocular SLAM to Autonomous Drone Exploration,
European Conference on Mobile Robots (ECMR), September 2017.

[C59] Florian Walch, Caner Hazirbas, Laura Leal-Taixe, Torsten Sattler, Sebastian Hilsenbeck and Daniel Cremers,
Image-based localization using LSTMs for structured feature correlation,
October 2017.

Establishment of an interdisciplinary workflow of machine learning-based Radiomics in sarcoma patients,

[C61] Queau, Y., Pizenberg, M., Durou, J.-D., Cremers and D.,
Microgeometry capture and RGB albedo estimation by photometric stereo without demosaicing,
International Conference on Quality Control by Artificial Vision (QCAV), 2017.

[C62] P. Haeusser, A. Mordvintsev and D. Cremers,
Learning by Association - A versatile semi-supervised training method for neural networks,
2017.

[C63] V. Usenko, L. von Stumberg, A. Pangeric and D. Cremers,
Real-Time Trajectory Replanning for MAVs using Uniform B-splines and a 3D Circular Buffer,
Vancouver, Canada, Sep 2017.
All: 1

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[C64] Tim Meinhardt, Michael Moeller, Caner Hazirbas and Daniel Cremers,
Learning Proximal Operators: Using Denoising Networks for Regularizing Inverse Imaging Problems,
October 2017.

One-Shot Video Object Segmentation,
Honolulu, USA, 2017.

[C66] Queau, Y., Melou, J., Durou, J.-D., Cremers and D.,
Dense Multi-view 3D-reconstruction Without Dense Correspondences,

[C67] K. Kurach, S. Gelly, M. Jastrzebski, P. Haeusser, O. Teytaud, D. Vincent and O. Bousquet,
Better Text Understanding Through Image-To-Text Transfer,

[C68] P. Haeusser, T. Frerix, A. Mordvintsev and D. Cremers,
Associative Domain Adaptation,
2017.

Efficient Deformable Shape Correspondence via Kernel Matching,
International Conference on 3D Vision (3DV), Qingdao, China, October 2017, Oral Presentation.

[C70] V. Golyanik, K. Kim, R. Maier, M. Niessner, D. Stricker and J. Kautz,
Multiframe Scene Flow with Piecewise Rigid Motion,
International Conference on 3D Vision (3DV), Qingdao, China, October 2017, Spotlight Presentation.

[C71] T. Möllenhoff and D. Cremers,
Sublabel-Accurate Discretization of Nonconvex Free-Discontinuity Problems,
International Conference on Computer Vision (ICCV), Venice, Italy, October 2017.

[C72] Christian Nissler, Zoltan-Csaba Marton, Hannes Kisner, Ulrike Thomas and Rudolph Triebel,
A Method for Hand-Eye and Camera-to-Camera Calibration for Limited Fields of View,
2017.

[C73] Tick Son Wang, Zoltan-Csaba Marton, Manuel Brucker and Rudolph Triebel,
How Robots Learn to Classify New Objects Trained from Small Data Sets,
Conference on Robot Learning (CoRL), 2017.

[C74] Maximilian Durner, Simon Kriegel, Sebastian Riedel, Manuel Brucker, Zoltan-Csaba Marton, Ferenc Balint-Benzedi and Rudolph Triebel,
Experience-based Optimization of Robotic Perception,
International Conference on Advanced Robotics (ICAR), 2017.

[C75] Queau, Y., Melou, J., Castan, F., Cremers, D., Durou and J.-D.,
A Variational Approach to Shape-from-shading Under Natural Illumination,
[C76] F. Bernard, F. R. Schmidt, J. Thunberg and D. Cremers,
A Combinatorial Solution to Non-Rigid 3D Shape-to-Image Matching,

[C77] A. Kasyanov, F. Engelmann, J. Stueckler and B. Leibe,
Keyframe-Based Visual-Inertial Online SLAM with Relocalization,

[C78] F. Engelmann, J. Stueckler and B. Leibe,
SAMP: Shape and Motion Priors for 4D Vehicle Reconstruction,

[C79] Peng, S., Haefner, B., Queau, Y., Cremers and D.,
Depth Super-Resolution Meets Uncalibrated Photometric Stereo,
International Conference on Computer Vision Workshops (ICCVW), 2017, Oral Pre-
sentation at ICCV Workshop on Color and Photometry in Computer Vision.

[C80] N. Mayer, E. Ilg, P. Haessser, P. Fischer, D. Cremers, A. Dosovitskiy and T. Brox,
A Large Dataset to Train Convolutional Networks for Disparity, Optical Flow, and Scene Flow Estimation,
IEEE International Conference on Computer Vision and Pattern Recognition (CVPR), 2016.

[C81] V. Golkov, T. Sprenger, J. I. Sperl, M. I. Menzel, M. Czisch, P. Sämann and D. Cremers,
Model-Free Novelty-Based Diffusion MRI,
Prague, Czech Republic, April 2016.

[C82] V. Golkov, M. J. Skwark, A. Golkov, A. Dosovitskiy, T. Brox, J. Meiler and D. Cremers,
Protein Contact Prediction from Amino Acid Co-Evolution Using Convolutio-
nal Networks for Graph-Valued Images,
Barcelona, Spain, December 2016.

[C83] Z. Lähner, E. Rodola, F. R. Schmidt, M. M. Bronstein and D. Cremers,
Efficient Globally Optimal 2D-to-3D Deformable Shape Matching,
May 2016.

[C84] A. Narr, R. Triebel and D. Cremers,
Stream-based Active Learning for Efficient and Adaptive Classification of 3D
Objects,
May 2016.

[C85] Z. Lähner, E. Rodola, M. M. Bronstein, D. Cremers, O. Burghard, L. Cosmo, A. Dieck-
mann, R. Klein and Y. Sahillioğlu,
SHREC16: Matching of Deformable Shapes with Topological Noise,
May 2016.

[C86] L. Cosmo, E. Rodola, M. M. Bronstein, A. Torsello, D. Cremers and Y. Sahillioğlu,
SHREC16: Partial Matching of Deformable Shapes,
May 2016.

[C87] T. Möllenhoff, E. Laude, M. Moeller, J. Lellmann and D. Cremers,
Sublabel-Accurate Relaxation of Nonconvex Energies,
2016.
[C88] L. Ma, C. Kerl, J. Stueckler and D. Cremers, 

[C89] J. Engel, V. Usenko and D. Cremers, 
**A Photometrically Calibrated Benchmark For Monocular Visual Odometry**, 

[C90] J. Engel, V. Koltun and D. Cremers, 
**Direct Sparse Odometry**, 

[C91] E. Laude, T. Möllenhoff, M. Moeller, J. Lellmann and D. Cremers, 
**Sublabel-Accurate Convex Relaxation of Vectorial Multilabel Energies**, 
October 2016.

[C92] T. Windheuser and D. Cremers, 
**A Convex Solution to Spatially-Regularized Correspondence Problems**, 
October 2016.

[C93] S. Sharifzadeh, I. Chiotellis, R. Triebel and D. Cremers, 
**Learning to Drive using Inverse Reinforcement Learning and Deep Q-Networks**, 
NIPS Workshops, December 2016.

[C94] D. Klostermann, A. Osep, J. Stueckler and B. Leibe, 
**Unsupervised Learning of Shape-Motion Patterns for Objects in Urban Street Scenes**, 

[C95] D. Kochanov, A. Osep, J. Stueckler and B. Leibe, 
**Scene Flow Propagation for Semantic Mapping and Object Discovery in Dynamic Street Scenes**, 

[C96] F. Engelmann, J. Stueckler and B. Leibe, 
**Joint Object Pose Estimation and Shape Reconstruction in Urban Street Scenes Using 3D Shape Priors**, 

[C97] M. Moeller, J. Diebold, G. Gilboa and D. Cremers, 

[C98] J. Diebold, N. Demmel, C. Hazirbas, M. Möller and D. Cremers, 
**Interactive Multi-label Segmentation of RGB-D Images**, 2015.

[C99] C. Hazirbas, J. Diebold and D. Cremers, 
[C100] A. Kanezaki, E. Rodola and T. Harada, 
RGB-D Graph matching wo mochita RGB-D gazou kara no butai kenshutsu - Learning graph matching for object detection from RGB-D images, 
20 Robotics Symposia (RS), Karuizawa, Japan, March 2015.

[C101] T. Möllenhoff, E. Strekalovskiy, M. Möller and D. Cremers, 
Low Rank Priors for Color Image Regularization, 
2015.

[C102] M. Jaimez, M. Souiai, J. Gonzalez-Jimenez and D. Cremers, 
A Primal-Dual Framework for Real-Time Dense RGB-D Scene Flow, 
Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA), 2015.

[C103] J. Stühmer and D. Cremers, 
A Fast Projection Method for Connectivity Constraints in Image Segmentation, 
X.-C. Tai, E. Bae, T. F. Chan and M. Lysaker (Eds.), , 2015.

[C104] R. Mecca, E. Rodola and D. Cremers, 
Analysis of Surface Parametrizations for Modern Photometric Stereo Modeling, 
International Conference on Quality Control by Artificial Vision (QCAV), 2015.

[C105] F. Bergamasco, A. Albarelli, L. Cosmo, A. Torsello, E. Rodola and D. Cremers, 
Adopting an Unconstrained Ray Model in Light-field Cameras for 3D Shape Reconstruction, 
2015.

[C106] D. Mund, R. Triebel and D. Cremers, 
Active Online Confidence Boosting for Efficient Object Classification, 

Using Diffusion and Structural MRI for the Automated Segmentation of Multiple Sclerosis Lesions, 
2015.

Robustness of Phase Sensitive Reconstruction in Diffusion Spectrum Imaging, 
2015.

[C109] A. Menini, V. Golkov and F. Wiesinger, 
Free-Breathing, Self-Navigated RUFIS Lung Imaging with Motion Compensated Image Reconstruction, 
2015.

q-Space Deep Learning for Twelve-Fold Shorter and Model-Free Diffusion MRI Scans, 
Munich, Germany, October 2015.
All: 1

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[C111] A. Dosovitskiy, P. Fischer, E. Ilg, P. Haeusser, C. Hazirbas, V. Golkov, P. van der Smagt, D. Cremers and T. Brox,
**FlowNet: Learning Optical Flow with Convolutional Networks,**
December 2015.

**SPENCER: A Socially Aware Service Robot for Passenger Guidance and Help in Busy Airports,**
*Proc. Field and Service Robotics (FSR),* 2015.

[C113] D. Holz, A. Topalidou-Kyniazopoulou, J. Stueckler and S. Behnke,
**Real-Time Object Detection, Localization and Verification for Fast Robotic Depalletizing,**
2015.

[C114] J. Engel, J. Stueckler and D. Cremers,
**Large-Scale Direct SLAM with Stereo Cameras,**
2015.

[C115] D. Caruso, J. Engel and D. Cremers,
**Large-Scale Direct SLAM for Omnidirectional Cameras,**
2015.

[C116] Y. Tao, R. Triebel and D. Cremers,
**Semi-supervised Online Learning for Efficient Classification of Objects in 3D Data Streams,**
2015.

[C117] R. Maier, J. Stueckler and D. Cremers,
**Super-Resolution Keyframe Fusion for 3D Modeling with High-Quality Textures,**

[C118] M. Jaimez, M. Souiai, J. Stueckler, J. Gonzalez-Jimenez and D. Cremers,
**Motion Cooperation: Smooth Piece-Wise Rigid Scene Flow from RGB-D Images,**

[C119] E. Rodola, M. Moeller and D. Cremers,
**Point-wise Map Recovery and Refinement from Functional Correspondence,**
Aachen, Germany, 2015, *Received the Best Paper Award.*

[C120] C. Kerl, J. Stueckler and D. Cremers,
**Dense Continuous-Time Tracking and Mapping with Rolling Shutter RGB-D Cameras,**
Santiago, Chile, 2015.

[C121] M. Souiai, M. R. Oswald, Y. Kee, J. Kim, M. Pollefeys and D. Cremers,
**Entropy Minimization for Convex Relaxation Approaches,**
Santiago, Chile, 2015.
[C122] F. Stark, C. Hazirbas, R. Triebel and D. Cremers, 
**CAPTCHA Recognition with Active Deep Learning**, 
*GCPR Workshop on New Challenges in Neural Computation*, Aachen, Germany, 2015.

[C123] N. Nagaraja, F. R. Schmidt and T. Brox, 
**Video Segmentation with Just a Few Strokes**, 
Santiago, Chile, Dec 2015.

**Model-Based Tracking at 300Hz using Raw Time-of-Flight Observations**, 
Santiago, Chile, 2015.

**Novel Acquisition Scheme for Diffusion Kurtosis Imaging Based on Compressed-Sensing Accelerated DSI Yielding Superior Image Quality**, 
2014.

**Total Variation-Regularized Compressed Sensing Reconstruction for Multi-Shell Diffusion Kurtosis Imaging**, 
2014.

**Direct Reconstruction of the Average Diffusion Propagator with Simultaneous Compressed-Sensing-Accelerated Diffusion Spectrum Imaging and Image Denoising by Means of Total Generalized Variation Regularization**, 
2014.

**Semi-Joint Reconstruction for Diffusion MRI Denoising Imposing Similarity of Edges in Similar Diffusion-Weighted Images**, 
2014.

**Improved Diffusion Kurtosis Imaging and Direct Propagator Estimation Using 6-D Compressed Sensing**, 
2014.

[C130] D. Weikersdorfer, D. B. Adrian, D. Cremers and J. Conrad, 
**Event-based 3D SLAM with a depth-augmented dynamic vision sensor**, 
2014.

[C131] F. Steinbruecker, J. Sturm and D. Cremers, 
**Volumetric 3D Mapping in Real-Time on a CPU**, 
Hongkong, China, 2014.

[C132] E. Rodola, S. Rota Bulo, T. Windheuser, M. Vestner and D. Cremers, 
**Dense Non-Rigid Shape Correspondence Using Random Forests**, 
2014.

[C133] Y. Kee, M. Souiai, D. Cremers and J. Kim, 
**Sequential Convex Relaxation for Mutual-Information-Based Unsupervised Figure-Ground Segmentation**, 
2014.
[C134] H. Alvarez, L.M. Paz, J. Sturm and D. Cremers,
Collision Avoidance for Quadrotors with a Monocular Camera,

[C135] J. Engel, T. Schöps and D. Cremers,
LSD-SLAM: Large-Scale Direct Monocular SLAM,
September 2014, Oral Presentation.

[C136] T. Schöps, J. Engel and D. Cremers,
Semi-Dense Visual Odometry for AR on a Smartphone,
September 2014, Best Short Paper Award.

[C137] T. Windheuser, M. Vestner, E. Rodola, R. Triebel and D. Cremers,
Optimal Intrinsic Descriptors for Non-Rigid Shape Analysis,
2014.

[C138] M. Strobel, J. Diebold and D. Cremers,
Flow and Color Inpainting for Video Completion,
German Conference on Pattern Recognition (GCPR), Münster, Germany, September 2014, Oral Presentation.

[C139] R. Maier, J. Sturm and D. Cremers,
Submap-based Bundle Adjustment for 3D Reconstruction from RGB-D Data,
German Conference on Pattern Recognition (GCPR), Münster, Germany, September 2014.

[C140] T. Gurdan, M. R. Oswald, D. Gurdan and D. Cremers,
Spatial and Temporal Interpolation of Multi-View Image Sequences,
Münster, Germany, Vol. 36, September 2014.

[C141] M. R. Oswald and D. Cremers,
Surface Normal Integration for Convex Space-time Multi-view Reconstruction,
2014.

[C142] C. Nieuwenhuis, S. Hawe, M. Kleinsteuber and D. Cremers,
Co-Sparse Textural Similarity for Interactive Segmentation,
2014.

[C143] M. R. Oswald, J. Stühmer and D. Cremers,
Generalized Connectivity Constraints for Spatio-temporal 3D Reconstruction,

[C144] E. Strekalovskiy and D. Cremers,
Real-Time Minimization of the Piecewise Smooth Mumford-Shah Functional,

[C145] A. Kanezaki, E. Rodola and T. Harada,
RGB-D [RGB-D gazou kara no buttai kenshatsu ni okeru taiou tenshuugou ruijido no gakushuu],

[C146] A. Kanezaki, E. Rodola, D. Cremers and T. Harada,
[Taiou tenshuugou ruijido gakushuu wo mochiita goutai-higoutai buttai kenshutsu],
[C147] M. Andreux, E. Rodola, M. Aubry and D. Cremers,
Anisotropic Laplace-Beltrami Operators for Shape Analysis,
Sixth Workshop on Non-Rigid Shape Analysis and Deformable Image Alignment (NOR-DIA), 2014.

[C148] O. Dunkley, J. Engel, J. Sturm and D. Cremers,
Visual-Inertial Navigation for a Camera-Equipped 25g Nano-Quadrotor,

[C149] R. Triebel, J. Stühmer, M. Souiai and D. Cremers,
Active Online Learning for Interactive Segmentation Using Sparse Gaussian Processes,
German Conference on Pattern Recognition, 2014.

[C150] S. Debnath, S. S. Baishya, R. Triebel, V. Dutt and D. Cremers,
Environment-adaptive Learning: How Clustering Helps to Obtain Good Training Data,

[C151] A. Kanezaki, E. Rodola, D. Cremers and T. Harada,
Learning Similarities for Rigid and Non-Rigid Object Detection,
International Conference on 3D Vision (3DV), 2014.

[C152] D. Bender, M. Schikora, J. Sturm and D. Cremers,
INS-Camera Calibration without Ground Control Points,
9th IEEE ISIF Workshop on Sensor Data Fusion: Trends, Solutions, Applications (SDF), 2014.

[C153] C. Kerl, M. Souiai, J. Sturm and D. Cremers,
Towards Illumination-invariant 3D Reconstruction using ToF RGB-D Cameras,
International Conference on 3D Vision (3DV), 2014.

[C154] J. Stueckler and S. Behnke,
Adaptive Tool-Use Strategies for Anthropomorphic Service Robots,
Proc. of the 14th IEEE-RAS International Conference on Humanoid Robots (Humanoids),
to appear, November 2014.

[C155] D. Droeschel, J. Stueckler and S. Behnke,
Local Multi-Resolution Surfel Grids for MAV Motion Estimation and 3D Mapping,
Proc. of the 13th International Conference on Intelligent Autonomous Systems (IAS),

[C156] J. Stueckler, A. Gutt and S. Behnke,
Combining the Strengths of Sparse Interest Point and Dense Image Registration for RGB-D Odometry,
Proc. of the Joint 45th International Symposium on Robotics (ISR) and 8th German Conference on Robotics (ROBOTIK), to appear, June 2014.
All: 1  

List of Publications

[C157] J. Stueckler and S. Behnke,  
Efficient deformable registration of multi-resolution surfel maps for object manipulation skill transfer,  

[C158] D. Droeschel, J. Stueckler and S. Behnke,  
Local multi-resolution representation for 6D motion estimation and mapping with a continuously rotating 3D laser scanner,  
Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA), 5221-5226, May 2014.

[C159] M. Schwarz, J. Stueckler and S. Behnke,  
Mobile Teleoperation Interfaces with Adjustable Autonomy for Personal Service Robots,  

[C160] F. R. Schmidt, T. Windheuser, U. Schlickewei and D. Cremers,  
Dense Elastic 3D Shape Matching,  

[C161] Bergbauer, Julia, Tari and Sibel,  
Wimmelbild Analysis with Approximate Curvature Coding Distance Images,  

[C162] Bergbauer, Julia, Tari and Sibel,  
Top-down visual search in Wimmelbild,  

[C163] F. Bergamasco, A. Albarelli, E. Rodola and A. Torsello,  
Can a fully unconstrained imaging model be applied effectively to central cameras?,  
2013.

[C164] M. Souiai, C. Nieuwenhuis, E. Strekalovskiy and D. Cremers,  
Convex Optimization for Scene Understanding,  
ICCV Workshop on Graphical Models for Scene Understanding, 2013.

[C165] J. Bergbauer, C. Nieuwenhuis, M. Souiai and D. Cremers,  
Proximity Priors for Variational Semantic Segmentation and Recognition,  
ICCV Workshop on Graphical Models for Scene Understanding, 2013.

[C166] V. Golkov, T. Sprenger, A. Menini, M.I. Menzel, D. Cremers and J.I. Sperl,  
Effects of Low-Rank Constraints, Line-Process Denoising, and q-Space Compressed Sensing on Diffusion MR Image Reconstruction and Kurtosis Tensor Estimation,  
2013, Oral Presentation.

[C167] V. Golkov, T. Sprenger, M.I. Menzel, D. Cremers and J.I. Sperl,  
Line-Process-Based Joint SENSE Reconstruction of Diffusion Images with Intensity Inhomogeneity Correction and Noise Non-Stationarity Correction,  
2013, Certificate of Merit Award.


[C173] C. Kerl, J. Sturm and D. Cremers, Robust Odometry Estimation for RGB-D Cameras, May 2013, **Best Vision Paper Award - Finalist**.


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[C178] R. Triebel, H. Grimmett and I. Posner,
Confidence Boosting: Improving the Introspectiveness of a Boosted Classifier for Efficient Learning,

Introspective Active Learning for Scalable Semantic Mapping,

[C180] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers,
Real-Time Camera Tracking and 3D Reconstruction Using Signed Distance Functions,

[C181] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers,
Direct Camera Pose Tracking and Mapping With Signed Distance Functions,
*Demo Track of the RGB-D Workshop on Advanced Reasoning with Depth Cameras at the Robotics: Science and Systems Conference (RSS)*, June 2013.

[C182] J. Sturm and W. Burgard,
Learning Probabilistic Models for Mobile Manipulation Robots,
*Proc. of the International Joint Conference on Artificial Intelligence (IJCAI)*, Track on Best papers in Sister Conferences, 2013.

[C183] M. Souiai, E. Strekalovskiy, C. Nieuwenhuis and D. Cremers,
A Co-occurrence Prior for Continuous Multi-Label Optimization,
2013.

[C184] F. Stangl, M. Souiai and D. Cremers,
Performance Evaluation of Narrow Band Methods for Variational Stereo,
*35th German Conference on Pattern Recognition (GCPR)*, 2013.

[C185] T. Möllenhoff, C. Nieuwenhuis, E. Toepppe and D. Cremers,
Efficient Convex Optimization for Minimal Partition Problems with Volume Constraints,
2013.

[C186] C. Kerl, J. Sturm and D. Cremers,
Dense Visual SLAM for RGB-D Cameras,

[C187] T. Naseer, J. Sturm and D. Cremers,
FollowMe: Person Following and Gesture Recognition with a Quadrocopter,

[C188] M. Klodt, J. Sturm and D. Cremers,
Scale-Aware Object Tracking with Convex Shape Constraints on RGB-D Images,
*German Conference on Pattern Recognition (GCPR)*, Saarbrücken, Germany, September 2013.

[C189] J. Sturm, E. Bylow, F. Kahl and D. Cremers,
Dense Tracking and Mapping with a Quadrocopter,
*Unmanned Aerial Vehicle in Geomatics (UAV-g)*, Rostock, Germany, September 2013.
[C190] D. Bender, M. Schikora, J. Sturm and D. Cremers,
Graph-based bundle adjustment for INS-camera calibration,
*Unmanned Aerial Vehicle in Geomatics (UAV-g)*, Rostock, Germany, September 2013,
Best research paper award.

[C191] J. Sturm, E. Bylow, F. Kahl and D. Cremers,
CopyMe3D: Scanning and Printing Persons in 3D,
*German Conference on Pattern Recognition (GCPR)*, Saarbrücken, Germany, September 2013.

[C192] E. Rodola, T. Harada, Y. Kuniyoshi and D. Cremers,
Efficient Shape Matching using Vector Extrapolation,
2013.

[C193] J. Engel, J. Sturm and D. Cremers,
Semi-Dense Visual Odometry for a Monocular Camera,
Sydney, Australia, December 2013.

[C194] E. Rodola, A. Torsello, T. Harada, Y. Kuniyoshi and D. Cremers,
Elastic Net Constraints for Shape Matching,
Sydney, Australia, December 2013.

[C195] J. Lellmann, E. Strekalovskiy, S. Koetter and D. Cremers,
Total Variation Regularization for Functions with Values in a Manifold,
Sydney, Australia, December 2013.

[C196] C. Nieuwenhuis, E. Strekalovskiy and D. Cremers,
Proportion Priors for Image Sequence Segmentation,
Sydney, Australia, December 2013.

[C197] J. Stühmer, P. Schröder and D. Cremers,
Tree Shape Priors with Connectivity Constraints using Convex Relaxation on General Graphs,
Sydney, Australia, December 2013, Oral Presentation.

[C198] G. Kuschik and D. Cremers,
Fast and Accurate Large-scale Stereo Reconstruction using Variational Methods,
*ICCV Workshop on Big Data in 3D Computer Vision*, Sydney, Australia, December 2013.

[C199] M. R. Oswald and D. Cremers,
A Convex Relaxation Approach to Space Time Multi-view 3D Reconstruction,
*ICCV Workshop on Dynamic Shape Capture and Analysis (4DMOD)*, 2013.

[C200] F. Steinbruecker, C. Kerl, J. Sturm and D. Cremers,
Large-Scale Multi-Resolution Surface Reconstruction from RGB-D Sequences,
Sydney, Australia, 2013.

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An Evaluation of the RGB-D SLAM System,

[C215] T. Ruehr, J. Sturm, D. Pangercic, M. Beetz and D. Cremers,
A Generalized Framework for Opening Doors and Drawers in Kitchen Envi-
ronments,

[C216] Dominik Joho AND Gian Diego Tipaldi AND Nikolas Engelhard AND Cyrill Stachniss
AND Wolfram Burgard,
Nonparametric Bayesian Models for Unsupervised Scene Analysis and Recon-
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