

## Conference and Workshop Papers

- [C1] D. Droeschel, J. Stueckler and S. Behnke,  
**Local multi-resolution representation for 6D motion estimation and mapping  
with a continuously rotating 3D laser scanner,**  
*Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA)*, 5221-5226, May 2014.