

Journal Articles

- [J1] L. von Stumberg and D. Cremers,
DM-VIO: Delayed Marginalization Visual-Inertial Odometry,
IEEE Robotics and Automation Letters (RA-L) 38; *International Conference on Robotics and Automation (ICRA)*, 7(2): 1408-1415, 2022.

Conference and Workshop Papers

- [C1] L. von Stumberg, V. Usenko and D. Cremers,
Direct Sparse Visual-Inertial Odometry using Dynamic Marginalization,
International Conference on Robotics and Automation (ICRA), May 2018.