Conference and Workshop Papers

[C1] N. Yang, L. von Stumberg, R. Wang and D. Cremers,
Deep Depth, Deep Pose and Deep Uncertainty for Monocular Visual Odometry,
*IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2020, *Oral Presentation*.

[C2] N. Yang, R. Wang, J. Stueckler and D. Cremers,
Deep Virtual Stereo Odometry: Leveraging Deep Depth Prediction for Monocular Direct Sparse Odometry,