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Santiago, Chile, Dec 2015.

Model-Based Tracking at 300Hz using Raw Time-of-Flight Observations,
Santiago, Chile, 2015.

Novel Acquisition Scheme for Diffusion Kurtosis Imaging Based on Compressed-Sensing Accelerated DSI Yielding Superior Image Quality,
2014.

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2014.

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2014.

Semi-Joint Reconstruction for Diffusion MRI Denoising Imposing Similarity of Edges in Similar Diffusion-Weighted Images,
2014.


[C77] Y. Kee, M. Souiai, D. Cremers and J. Kim, Sequential Convex Relaxation for Mutual-Information-Based Unsupervised Figure-Ground Segmentation, 2014.


[C82] M. Strobel, J. Diebold and D. Cremers, Flow and Color Inpainting for Video Completion, German Conference on Pattern Recognition (GCPR), Münster, Germany, September 2014, Oral Presentation.

[C83] R. Maier, J. Sturm and D. Cremers, Submap-based Bundle Adjustment for 3D Reconstruction from RGB-D Data, German Conference on Pattern Recognition (GCPR), Münster, Germany, September 2014.


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[C86] C. Nieuwenhuis, S. Hawe, M. Kleinsteuber and D. Cremers,
Co-Sparse Textural Similarity for Interactive Segmentation,
2014.

[C87] M. R. Oswald, J. Stühmer and D. Cremers,
Generalized Connectivity Constraints for Spatio-temporal 3D Reconstruction,

[C88] E. Strekalovskiy and D. Cremers,
Real-Time Minimization of the Piecewise Smooth Mumford-Shah Functional,

[C89] A. Kanezaki, E. Rodola and T. Harada,
RGB-D [RGB-D gazou kara no buttai kenshitsu ni okeru taisou tenshuugou ruijidou no gakushuu],

[C90] A. Kanezaki, E. Rodola, D. Cremers and T. Harada,
[Taiou tenshuugou ruijido gakushuu wo mochita goutai-higoutai buttai kenshitsu],

[C91] M. Andreux, E. Rodola, M. Aubry and D. Cremers,
Anisotropic Laplace-Beltrami Operators for Shape Analysis,
Sixth Workshop on Non-Rigid Shape Analysis and Deformable Image Alignment (NORDIA), 2014.

[C92] O. Dunkley, J. Engel, J. Sturm and D. Cremers,
Visual-Inertial Navigation for a Camera-Equipped 25g Nano-Quadrotor,

[C93] R. Triebel, J. Stühmer, M. Souiai and D. Cremers,
Active Online Learning for Interactive Segmentation Using Sparse Gaussian Processes,
German Conference on Pattern Recognition, 2014.

[C94] S. Debnath, S. S. Baishya, R. Triebel, V. Dutt and D. Cremers,
Environment-adaptive Learning: How Clustering Helps to Obtain Good Training Data,

[C95] A. Kanezaki, E. Rodola, D. Cremers and T. Harada,
Learning Similarities for Rigid and Non-Rigid Object Detection,
International Conference on 3D Vision (3DV), 2014.

[C96] D. Bender, M. Schikora, J. Sturm and D. Cremers,
INS-Camera Calibration without Ground Control Points,
9th IEEE ISIF Workshop on Sensor Data Fusion: Trends, Solutions, Applications (SDF), 2014.

[C97] C. Kerl, M. Souiai, J. Sturm and D. Cremers,
Towards Illumination-invariant 3D Reconstruction using ToF RGB-D Cameras,
International Conference on 3D Vision (3DV), 2014.
[C98] J. Stueckler and S. Behnke,  
Adaptive Tool-Use Strategies for Anthropomorphic Service Robots,  

[C99] D. Droeschel, J. Stueckler and S. Behnke,  
Local Multi-Resolution Surfel Grids for MAV Motion Estimation and 3D Mapping,  

[C100] J. Stueckler, A. Gutt and S. Behnke,  
Combining the Strengths of Sparse Interest Point and Dense Image Registration for RGB-D Odometry,  
Proc. of the Joint 45th International Symposium on Robotics (ISR) and 8th German Conference on Robotics (ROBOTIK), to appear, June 2014.

[C101] J. Stueckler and S. Behnke,  
Efficient deformable registration of multi-resolution surfel maps for object manipulation skill transfer,  

[C102] D. Droeschel, J. Stueckler and S. Behnke,  
Local multi-resolution representation for 6D motion estimation and mapping with a continuously rotating 3D laser scanner,  
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[C103] M. Schwarz, J. Stueckler and S. Behnke,  
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[C104] F. R. Schmidt, T. Windheuser, U. Schlickewei and D. Cremers,  
Dense Elastic 3D Shape Matching,  

[C105] Bergbauer, Julia, Tari and Sibiel,  
Wimmelbild Analysis with Approximate Curvature Coding Distance Images,  

[C106] Bergbauer, Julia, Tari and Sibiel,  
Top-down visual search in Wimmelbild,  

[C107] F. Bergamasco, A. Albarelli, E. Rodola and A. Torsello,  
Can a fully unconstrained imaging model be applied effectively to central cameras?,  
2013.
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[C118] E. Toeppe, C. Nieuwenhuis and D. Cremers,
Volume Constraints for Single View Reconstruction,
Portland, USA, 2013.

Toward Automated Driving in Cities using Close-to-Market Sensors,

[C120] H. Grimmett, R. Paul, R. Triebel and I. Posner,
Knowing When We Dont Know: Introspective Classification for Mission-Critical Decision Making,

[C121] D. Weikersdorfer, A. Schick and D. Cremers,

[C122] R. Triebel, H. Grimmett and I. Posner,
Confidence Boosting: Improving the Introspectiveness of a Boosted Classifier for Efficient Learning,

Introspective Active Learning for Scalable Semantic Mapping,

[C124] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers,
Real-Time Camera Tracking and 3D Reconstruction Using Signed Distance Functions,

[C125] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers,
Direct Camera Pose Tracking and Mapping With Signed Distance Functions,
Demo Track of the RGB-D Workshop on Advanced Reasoning with Depth Cameras at the Robotics: Science and Systems Conference (RSS), June 2013.

[C126] J. Sturm and W. Burgard,
Learning Probabilistic Models for Mobile Manipulation Robots,
Proc. of the International Joint Conference on Artificial Intelligence (IJCAI), Track on Best papers in Sister Conferences, 2013.

[C127] M. Souiai, E. Strekalovskiy, C. Nieuwenhuis and D. Cremers,
A Co-occurrence Prior for Continuous Multi-Label Optimization,
2013.

[C128] F. Stangl, M. Souiai and D. Cremers,
Performance Evaluation of Narrow Band Methods for Variational Stereo,
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[C129] T. Möllenhoff, C. Nieuwenhuis, E. Toeppe and D. Cremers,
Efficient Convex Optimization for Minimal Partition Problems with Volume
Constraints,
2013.

[C130] C. Kerl, J. Sturm and D. Cremers,
Dense Visual SLAM for RGB-D Cameras,

[C131] T. Naseer, J. Sturm and D. Cremers,
FollowMe: Person Following and Gesture Recognition with a Quadrocopter,

[C132] M. Klodt, J. Sturm and D. Cremers,
Scale-Aware Object Tracking with Convex Shape Constraints on RGB-D
Images,
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2013.

[C133] J. Sturm, E. Bylow, F. Kahl and D. Cremers,
Dense Tracking and Mapping with a Quadrocopter,
Unmanned Aerial Vehicle in Geomatics (UAV-g), Rostock, Germany, September 2013.

[C134] D. Bender, M. Schikora, J. Sturm and D. Cremers,
Graph-based bundle adjustment for INS-camera calibration,
Unmanned Aerial Vehicle in Geomatics (UAV-g), Rostock, Germany, September 2013,
Best research paper award.

[C135] J. Sturm, E. Bylow, F. Kahl and D. Cremers,
CopyMe3D: Scanning and Printing Persons in 3D,
German Conference on Pattern Recognition (GCPR), Saarbrücken, Germany, September
2013.

[C136] E. Rodola, T. Harada, Y. Kuniyoshi and D. Cremers,
Efficient Shape Matching using Vector Extrapolation,
2013.

[C137] J. Engel, J. Sturm and D. Cremers,
Semi-Dense Visual Odometry for a Monocular Camera,
Sydney, Australia, December 2013.

[C138] E. Rodola, A. Torsello, T. Harada, Y. Kuniyoshi and D. Cremers,
Elastic Net Constraints for Shape Matching,
Sydney, Australia, December 2013.

[C139] J. Lellmann, E. Strekalovskiy, S. Koetter and D. Cremers,
Total Variation Regularization for Functions with Values in a Manifold,
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[C140] C. Nieuwenhuis, E. Strekalovskiy and D. Cremers,
Proportion Priors for Image Sequence Segmentation,
Sydney, Australia, December 2013.
[C141] J. Stühmer, P. Schröder and D. Cremers,
Tree Shape Priors with Connectivity Constraints using Convex Relaxation on General Graphs,
Sydney, Australia, December 2013, Oral Presentation.

[C142] G. Kuschk and D. Cremers,
Fast and Accurate Large-scale Stereo Reconstruction using Variational Methods,
ICCV Workshop on Big Data in 3D Computer Vision, Sydney, Australia, December 2013.

[C143] M. R. Oswald and D. Cremers,
A Convex Relaxation Approach to Space Time Multi-view 3D Reconstruction,
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[C144] F. Steinbruecker, C. Kerl, J. Sturm and D. Cremers,
Large-Scale Multi-Resolution Surface Reconstruction from RGB-D Sequences,
Sydney, Australia, 2013.

[C145] T. Naseer, J. Sturm and D. Cremers,
Interactive Person Following and Gesture Recognition with a Flying Robot,
Proc. of the Assistance and Service Robotics Workshop (ASROB) at the IEEE Int. Conf. on Intelligent Robots and Systems (IROS), Nov. 2013.

[C146] R. Triebel, H. Grimmert, R. Paul and I. Posner,
Driven Learning for Driving: How Introspection Improves Semantic Mapping,
The International Symposium on Robotics Research (ISRR), 2013.

[C147] D. Cremers, E. Rodola and T. Windheuser,
Relaxations for Minimizing Metric Distortion and Elastic Energies for 3D Shape Matching,

[C148] M. Schadler, J. Stueckler and S. Behnke,
Multi-resolution surfel mapping and real-time pose tracking using a continuously rotating 2D laser scanner,

[C149] J. Stueckler and S. Behnke,
Efficient Dense 3D Rigid-Body Motion Segmentation in RGB-D Video,

[C150] M. McElhone, J. Stueckler and S. Behnke,
Joint detection and pose tracking of multi-resolution surfel models in RGB-D,

[C151] T. Fiolka, J. Stueckler, D. A. Klein, D. Schulz and S. Behnke,
Distinctive 3D surface entropy features for place recognition.,
[C152] A. Berner, Jun Li, D. Holz, J. Stueckler, S. Behnke and R. Klein,
Combining contour and shape primitives for object detection and pose estimation of prefabricated parts,

[C153] J. Stueckler and S. Behnke,
Hierarchical Object Discovery and Dense Modelling From Motion Cues in RGB-D Video,

[C154] M. Nieuwenhuisen, D. Droeschel, D. Holz, J. Stueckler, A. Berner, Jun Li, R. Klein and S. Behnke,
Mobile bin picking with an anthropomorphic service robot,

[C155] L. Gorelick, F. R. Schmidt and Y. Boykov,
Fast Trust Region for Segmentation,
Portland, Oregon, Jun 2013.

[C156] L. Ma, T. Whelan, E. Bondarev, P. H. N. de With and J. McDonald,
Planar simplification and texturing of dense point cloud maps,

[C157] E. Rodola, A.M. Bronstein, A. Albarelli, F. Bergamasco and A. Torsello,
A game-theoretic approach to deformable shape matching,

[C158] F. Endres, J. Hess, N. Engelhard, J. Sturm, D. Cremers and W. Burgard,
An Evaluation of the RGB-D SLAM System,

[C159] T. Ruehr, J. Sturm, D. Pangercic, M. Beetz and D. Cremers,
A Generalized Framework for Opening Doors and Drawers in Kitchen Environments,

[C160] Dominik Joho AND Gian Diego Tipaldi AND Nikolas Engelhard AND Cyrill Stachniss AND Wolfram Burgard,
Nonparametric Bayesian Models for Unsupervised Scene Analysis and Reconstruction,

[C161] M. Schikora, A. Gning, L. Mihaylova, D. Cremers, W. Koch and R. Streit,
Box-Particle Intensity Filter,

[C162] M. Schikora, A. Gning, L. Mihaylova, D. Cremers and W. Koch,
Box-Particle PHD Filter for Multi-Target Tracking,
15th International Conference on Information Fusion (FUSION), Singapore, July 2012.
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[C163] L. Zhang, J. Sturm, D. Cremers and D. Lee,
Real-Time Human Motion Tracking using Multiple Depth Cameras,

[C164] E. Strekalovskiy, C. Nieuwenhuis and D. Cremers,
Nonmetric Priors for Continuous Multilabel Optimization,
Firenze, Italy, Springer, October 2012.

[C165] T. Windheuser, H. Ishikawa and D. Cremers,
Generalized Roof Duality for Multi-Label Optimization: Optimal Lower Bounds and Persistency,
Firenze, Italy, October 2012.

[C166] T. Windheuser, H. Ishikawa and D. Cremers,
QPBO [QPBO arugorizumu no tachika ni yoru hiretsu mojura enerugi saisho-ka],
Meeting on Image Recognition and Understanding, Fukuoka, Japan, August 2012.

[C167] M. R. Oswald, E. Toeppe and D. Cremers,
Fast and Globally Optimal Single View Reconstruction of Curved Objects,
Providence, Rhode Island, 534-541, June 2012.

[C168] E. Strekalovskiy, A. Chambolle and D. Cremers,
A Convex Representation for the Vectorial Mumford-Shah Functional,
Providence, Rhode Island, June 2012.

[C169] J. Engel, J. Sturm and D. Cremers,
Camera-Based Navigation of a Low-Cost Quadrocopter,

[C170] J. Sturm, N. Engelhard, F. Endres, W. Burgard and D. Cremers,
A Benchmark for the Evaluation of RGB-D SLAM Systems,

[C171] J. Engel, J. Sturm and D. Cremers,
Accurate Figure Flying with a Quadrocopter Using Onboard Visual and Inertial Sensing,

[C172] J. Sturm, W. Burgard and D. Cremers,
Evaluating Egomotion and Structure-from-Motion Approaches Using the TUM RGB-D Benchmark,

Evaluation of DSI Imaging with Compressed Sensing under the Presence of Different Noise Levels on a Diffusion Phantom, 2012.
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Comparison of Diffusion Kurtosis Tensor Estimation Methods in an Advanced Quality Assessment Framework,
2012.

[C175] N. Ufer, M. Souiai and D. Cremers,
Wehrli 2.0: An Algorithm for Tidying up Art,

Semantic Categorization of Outdoor Scenes with Uncertainty Estimates using Multi-Class Gaussian Process Classification,

[C177] R. Triebel, R. Paul, D. Rus and P. Newman,
Parsing Outdoor Scenes from Streamed 3D Laser Data Using Online Clustering and Incremental Belief Updates,

[C178] U. Hubert, J. Stueckler and S. Behnke,
Bayesian calibration of the hand-eye kinematics of an anthropomorphic robot,
Proc. of the 12th IEEE-RAS Int. Conf. on Humanoid Robots (Humanoids), 618-624, November 2012.

[C179] J. Stueckler, N. Biresev and S. Behnke,
Semantic mapping using object-class segmentation of RGB-D images,
Proc. of the IEEE/RSJ Int. Conf. on Intelligent Robots and Systems (IROS), 3005-3010, October 2012.

[C180] J. Stueckler and S. Behnke,
Integrating depth and color cues for dense multi-resolution scene mapping using RGB-D cameras,
Proc. of the IEEE Int. Conf. on Multisensor Fusion and Integration for Intelligent Systems (MFI), 162-167, September 2012.

[C181] S. Muszynski, J. Stueckler and S. Behnke,
Adjustable autonomy for mobile teleoperation of personal service robots,
Proc. of the IEEE Int. Symp. on Robot and Human Interactive Communication, 933-940, September 2012.

[C182] T. Fiolka, J. Stueckler, D. A. Klein, D. Schulz and S. Behnke,
SURE: Surface Entropy for Distinctive 3D Features,

[C183] G. M. Garcia, D. A. Klein, J. Stueckler, S. Frintrop and A. B. Cremers,
Adaptive Multi-cue 3D Tracking of Arbitrary Objects,

[C184] J. Stueckler and S. Behnke,
Model Learning and Real-Time Tracking Using Multi-Resolution Surfel Maps,
2012.


[C197] T. Schoenemann, S. Masnou and D. Cremers,
On a linear programming approach to the discrete Willmore boundary value problem and generalizations,

[C198] E. Strekalovskiy and D. Cremers,
Total Variation for Cyclic Structures: Convex Relaxation and Efficient Minimization,

[C199] B. Goldluecke and D. Cremers,
Introducing Total Curvature for Image Processing,
2011.

[C200] E. Strekalovskiy, B. Goldluecke and D. Cremers,
Tight Convex Relaxations for Vector-Valued Labeling Problems,
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[C201] M. Aubry, K. Kolev, B. Goldluecke and D. Cremers,
Decoupling Photometry and Geometry in Dense Variational Camera Calibration,
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[C202] E. Strekalovskiy and D. Cremers,
Generalized Ordering Constraints for Multilabel Optimization,
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[C203] J. Hess, J. Sturm and W. Burgard,
Learning the State Transition Model to Efficiently Clean Surfaces with Mobile Manipulation Robots,
Proc. of the Workshop on Manipulation under Uncertainty at the IEEE Int. Conf. on Robotics and Automation (ICRA), Shanghai, China, May 2011.

[C204] N. Engelhard, F. Endres, J. Hess, J. Sturm and W. Burgard,
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Towards a benchmark for RGB-D SLAM evaluation,

[C206] C. Nieuwenhuis, E. Toeppe and D. Cremers,
Space-Varying Color Distributions for Interactive Multiregion Segmentation: Discrete versus Continuous Approaches,
177-190, 2011.

[C207] M. Klodt and D. Cremers,
A Convex Framework for Image Segmentation with Moment Constraints,
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[C208] M. Aubry, U. Schlickewei and D. Cremers,  
*The Wave Kernel Signature: A Quantum Mechanical Approach To Shape Analysis*,  
*IEEE International Conference on Computer Vision (ICCV) - Workshop on Dynamic Shape Capture and Analysis (4DMOD)*, 2011.

[C209] F. Steinbruecker, J. Sturm and D. Cremers,  
*Real-Time Visual Odometry from Dense RGB-D Images*,  
*Workshop on Live Dense Reconstruction with Moving Cameras at the Intl. Conf. on Computer Vision (ICCV)*, 2011.

*Mobile Manipulation of Kitchen Containers*,  
*Proc. of the IROS’11 Workshop on Results, Challenges and Lessons Learned in Advancing Robots with a Common Platform*, San Francisco, CA, USA, 2011.

[C211] M. Schikora, M.Oispuu, W. Koch and D. Cremers,  
*Multiple Source Localization Based on Biased Bearings Using the Intensity Filter - Approach and Experimental Results*,  

[C212] S. Madhogaria, M. Schikora, W. Koch and D. Cremers,  
*Pixel-based Classification Method for Detecting Unhealthy Regions in Leaf Images*,  
*6th IEEE ISIF Workshop on Sensor Data Fusion: Trends, Solutions, Applications (SDF)*, Berlin, Germany, September 2011.

[C213] M. Schikora, W. Koch, R.L. Streit and D. Cremers,  
*Sequential Monte Carlo Method for the iFilter*,  
*14th International Conference on Information Fusion (FUSION)*, Chicago, IL, USA, July 2011.

[C214] M. Oispuu and M. Schikora,  
*Multiple Emitter Localization Using a Realistic Airborne Array Sensor*,  
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[C215] M. Schikora, W. Koch and D. Cremers,  
*Multi-object tracking via high accuracy optical flow and finite set statistics*,  

[C216] E. Toepee, M. R. Oswald, D. Cremers and C. Rother,  
*Silhouette-Based Variational Methods for Single View Reconstruction*,  
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[C217] M. R. Oswald, E. Toeppe, C. Nieuwenhuis and D. Cremers, 
A Survey on Geometry Recovery from a Single Image with Focus on Curved Object Reconstruction, 

[C218] J. Shin, R. Triebel and R. Siegwart, 
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[C219] J. Maye, R. Triebel, L. Spinello and R. Siegwart, 
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2011.

[C220] B. Oehler, J. Stueckler, J. Welle, D. Schulz and S. Behnke, 
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[C221] J. Stueckler and S. Behnke, 
Following human guidance to cooperatively carry a large object, 
Proc. of the 11th IEEE-RAS Int. Conf. on Humanoid Robots (Humanoids), 218-223, October 2011.

[C222] J. Stueckler, R. Steffens, D. Holz and S. Behnke, 
Real-Time 3D Perception and Efficient Grasp Planning for Everyday Manipulation Tasks, 
Proc. of the European Conf. on Mobile Robots (ECMR), 177-182, 2011.

[C223] J. Stueckler and S. Behnke, 
Compliant Task-Space Control with Back-Drivable Servo Actuators, 

[C224] D. Droeschel, J. Stueckler, D. Holz and S. Behnke, 
Towards joint attention for a domestic service robot - person awareness and gesture recognition using Time-of-Flight cameras, 
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[C227] F. R. Schmidt, H. Ackermann and B. Rosenhahn, 
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[C231] A. Albarelli, E. Rodola, A. Cavallarin and A. Torsello, Robust Figure Extraction on Textured Background: a Game-Theoretic Approach, 20th International Conference on Pattern Recognition (ICPR), 360-363, 2010.


[C234] A. Albarelli, E. Rodola and A. Torsello, Robust Game-Theoretic Inlier Selection for Bundle Adjustment, 5th International Symposium on 3D Data Processing, Visualization and Transmission (3DPVT), 2010, Best Student Paper Award.


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Queenstown, New Zealand, 53-64, November 2010, Received Honorable Mention Award.

[C240] K. Kolev, T. Pock and D. Cremers,
Anisotropic Minimal Surfaces Integrating Photoconsistency and Normal Information for Multiview Stereo,
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[C241] J. Stühmer, S. Gumhold and D. Cremers,
Real-Time Dense Geometry from a Handheld Camera,
Darmstadt, Germany, 11-20, September 2010.

[C242] J. Stühmer, S. Gumhold and D. Cremers,
Parallel Generalized Thresholding Scheme for Live Dense Geometry from a Handheld Camera,
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[C243] B. Goldluecke and D. Cremers,
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[C244] B. Goldluecke and D. Cremers,
Convex Relaxation for Multilabel Problems with Product Label Spaces,
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[C245] C. Nieuwenhuis and D. Kondermann,
Complex Motion Models for Simple Optical Flow Estimation,

[C246] C. Nieuwenhuis, B. Berkels and M. Rumpf,
Interactive Motion Segmentation,

[C247] J. Sturm, K. Konolige, C. Stachniss and W. Burgard,
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[C248] J. Sturm, K. Konolige, C. Stachniss and W. Burgard,
Vision-based Detection for Learning Articulation Models of Cabinet Doors and Drawers in Household Environments,

[C249] S. Chitta, M. Piccoli and J. Sturm,
Tactile Object Class and Internal State Recognition for Mobile Manipulation,

[C250] J. Sturm, A. Jain, C. Stachniss, C. C. Kemp and W. Burgard,
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[C251] R. Kaestner, N. Engelhard, R. Triebel and R. Siegwart, 
A Bayesian Approach to Learning 3D Representations of Dynamic Environments, 

[C252] L. Spinello, R. Triebel, D. Vasquez, K. Arras and R Siegwart, 
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[C253] R. Triebel, J. Shin and R. Siegwart, 
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[C254] L. Spinello, K. O. Arras, R. Triebel and R. Siegwart, 
A Layered Approach to People Detection in 3D Range Data, 
special track on Physically Grounded AI of AAAI, 2010.

[C255] J. Shin, R. Triebel and R. Siegwart, 
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[C256] J. Maye, L. Spinello, R. Triebel and R. Siegwart, 

[C257] K. Gräve, J. Stueckler and S. Behnke, 
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Improving People Awareness of Service Robots by Semantic Scene Knowledge, 

[C260] D. Holz, R. Schnabel, D. Droeschel, J. Stueckler and S. Behnke, 
Towards Semantic Scene Analysis with Time-of-flight Cameras, 

[C261] H. Schulz, W. Liu, J. Stueckler and S. Behnke, 
Utilizing the Structure of Field Lines for Efficient Soccer Robot Localization, 
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