

Conference and Workshop Papers

- [C1] O. Dunkley, J. Engel, J. Sturm and D. Cremers,
Visual-Inertial Navigation for a Camera-Equipped 25g Nano-Quadrotor,
IROS2014 Aerial Open Source Robotics Workshop, 2014.

MastersThesis

- [M1] OMW Dunkley,
Visual Inertial Control of a Nano-Quadrotor,
Technical University Munich, Germany, Sept. 2014.