Journal Articles


Conference and Workshop Papers


Keywords: Rgb-d

List of Publications

[C7] R. Maier, R. Schaller and D. Cremers,
Efficient Online Surface Correction for Real-time Large-Scale 3D Reconstruction,
British Machine Vision Conference (BMVC), London, United Kingdom, September 2017.

[C8] V. Golyanik, K. Kim, R. Maier, M. Niessner, D. Stricker and J. Kautz,
Multiframe Scene Flow with Piecewise Rigid Motion,
International Conference on 3D Vision (3DV), Qingdao, China, October 2017, Spotlight Presentation.

[C9] R. Maier, K. Kim, D. Cremers, J. Kautz and M. Niessner,
Intrinsic3D: High-Quality 3D Reconstruction by Joint Appearance and Geometry Optimization with Spatially-Varying Lighting,
International Conference on Computer Vision (ICCV), Venice, Italy, October 2017.

[C10] S. Peng, B. Haefner, Y. Queau and D. Cremers,
Depth Super-Resolution Meets Uncalibrated Photometric Stereo,
International Conference on Computer Vision Workshops (ICCVW), 2017, Oral Presentation at ICCV Workshop on Color and Photometry in Computer Vision.

[C11] L. Ma, C. Kerl, J. Stueckler and D. Cremers,
CPA-SLAM: Consistent Plane-Model Alignment for Direct RGB-D SLAM,
International Conference on Robotics and Automation (ICRA), May 2016.

[C12] M. Jaimez, M. Souiai, J. Gonzalez-Jimenez and D. Cremers,
A Primal-Dual Framework for Real-Time Dense RGB-D Scene Flow,
Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA), 2015.

[C13] R. Maier, J. Stueckler and D. Cremers,
Super-Resolution Keyframe Fusion for 3D Modeling with High-Quality Textures,
International Conference on 3D Vision (3DV), October 2015.

[C14] M. Jaimez, M. Souiai, J. Stueckler, J. Gonzalez-Jimenez and D. Cremers,
Motion Cooperation: Smooth Piece-Wise Rigid Scene Flow from RGB-D Images,

[C15] C. Kerl, J. Stueckler and D. Cremers,
Dense Continuous-Time Tracking and Mapping with Rolling Shutter RGB-D Cameras,
IEEE International Conference on Computer Vision (ICCV), Santiago, Chile, 2015.

Model-Based Tracking at 300Hz using Raw Time-of-Flight Observations,
IEEE International Conference on Computer Vision (ICCV), Santiago, Chile, 2015.

[C17] F. Steinbruecker, J. Sturm and D. Cremers,
Volumetric 3D Mapping in Real-Time on a CPU,
International Conference on Robotics and Automation (ICRA), Hongkong, China, 2014.

[C18] J. Engel, T. Schöps and D. Cremers,
LSD-SLAM: Large-Scale Direct Monocular SLAM,
European Conference on Computer Vision (ECCV), September 2014, Oral Presentation.
[C19] T. Schöps, J. Engel and D. Cremers,  
Semi-Dense Visual Odometry for AR on a Smartphone,  

[C20] R. Maier, J. Sturm and D. Cremers,  
Submap-based Bundle Adjustment for 3D Reconstruction from RGB-D Data,  
*German Conference on Pattern Recognition (GCPR)*, Münster, Germany, September 2014, Oral Presentation.

[C21] C. Kerl, M. Souiai, J. Sturm and D. Cremers,  
Towards Illumination-invariant 3D Reconstruction using ToF RGB-D Cameras,  

[C22] C. Kerl, J. Sturm and D. Cremers,  
Robust Odometry Estimation for RGB-D Cameras,  

[C23] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers,  
Real-Time Camera Tracking and 3D Reconstruction Using Signed Distance Functions,  

[C24] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers,  
Direct Camera Pose Tracking and Mapping With Signed Distance Functions,  
Demo Track of the RGB-D Workshop on Advanced Reasoning with Depth Cameras at the Robotics: Science and Systems Conference (RSS), June 2013.

[C25] C. Kerl, J. Sturm and D. Cremers,  
Dense Visual SLAM for RGB-D Cameras,  

[C26] T. Naseer, J. Sturm and D. Cremers,  
FollowMe: Person Following and Gesture Recognition with a Quadrocopter,  

[C27] M. Klodt, J. Sturm and D. Cremers,  
Scale-Aware Object Tracking with Convex Shape Constraints on RGB-D Images,  
*German Conference on Pattern Recognition (GCPR)*, Saarbrücken, Germany, September 2013.

[C28] J. Sturm, E. Bylow, F. Kahl and D. Cremers,  
Dense Tracking and Mapping with a Quadrocopter,  
*Unmanned Aerial Vehicle in Geomatics (UAV-g)*, Rostock, Germany, September 2013.

[C29] J. Sturm, E. Bylow, F. Kahl and D. Cremers,  
CopyMe3D: Scanning and Printing Persons in 3D,  
*German Conference on Pattern Recognition (GCPR)*, Saarbrücken, Germany, September 2013.
Keywords: Rgb-d

List of Publications

[C30] J. Engel, J. Sturm and D. Cremers, 
Semi-Dense Visual Odometry for a Monocular Camera, 
*IEEE International Conference on Computer Vision (ICCV)*, Sydney, Australia, December 2013.

[C31] F. Steinbruecker, C. Kerl, J. Sturm and D. Cremers, 
Large-Scale Multi-Resolution Surface Reconstruction from RGB-D Sequences, 
*IEEE International Conference on Computer Vision (ICCV)*, Sydney, Australia, 2013.

[C32] F. Endres, J. Hess, N. Engelhard, J. Sturm, D. Cremers and W. Burgard, 
An Evaluation of the RGB-D SLAM System, 

[C33] L. Zhang, J. Sturm, D. Cremers and D. Lee, 
Real-Time Human Motion Tracking using Multiple Depth Cameras, 

[C34] J. Sturm, N. Engelhard, F. Endres, W. Burgard and D. Cremers, 
A Benchmark for the Evaluation of RGB-D SLAM Systems, 

[C35] J. Sturm, W. Burgard and D. Cremers, 
Evaluating Egomotion and Structure-from-Motion Approaches Using the TUM RGB-D Benchmark, 

[C36] N. Engelhard, F. Endres, J. Hess, J. Sturm and W. Burgard, 
Real-time 3D visual SLAM with a hand-held camera, 

[C37] J. Stührer, S. Magnenat, N. Engelhard, F. Pomerleau, F. Colas, W. Burgard, D. Cremers and R. Siegwart, 
Towards a benchmark for RGB-D SLAM evaluation, 

[C38] F. Steinbruecker, J. Sturm and D. Cremers, 
Real-Time Visual Odometry from Dense RGB-D Images, 
*Workshop on Live Dense Reconstruction with Moving Cameras at the Intl. Conf. on Computer Vision (ICCV)*, 2011.

[C39] J. Stührer, S. Gumhold and D. Cremers, 
Real-Time Dense Geometry from a Handheld Camera, 
*Pattern Recognition (Proc. DAGM)*, Darmstadt, Germany, 11-20, September 2010.

[C40] J. Stührer, S. Gumhold and D. Cremers, 
Parallel Generalized Thresholding Scheme for Live Dense Geometry from a Handheld Camera, 
*ECCV Workshop on Computer Vision on GPUs (CVGPU)*, Heraklion, Greece, September 2010.
MastersThesis

[M1] R. Maier,
Out-of-Core Bundle Adjustment for 3D Workpiece Reconstruction,
Technische Universität München, Germany, September 2013.

[M2] C. Kerl,
Odometry from RGB-D Cameras for Autonomous Quadrocopters,
Technical University Munich, Germany, Nov. 2012.