Conference and Workshop Papers

[C1] F. Wimbauer, N. Yang, L. von Stumberg, N. Zeller and D Cremers,
MonoRec: Semi-Supervised Dense Reconstruction in Dynamic Environments from a Single Moving Camera,

[C2] N. Yang, L. von Stumberg, R. Wang and D. Cremers,
D3VO: Deep Depth, Deep Pose and Deep Uncertainty for Monocular Visual Odometry,

[C3] N. Yang, R. Wang, J. Stueckler and D. Cremers,
Deep Virtual Stereo Odometry: Leveraging Deep Depth Prediction for Monocular Direct Sparse Odometry,
European Conference on Computer Vision (ECCV), September 2018, Oral Presentation.