2020
Conference and Workshop Papers

[C1] Sang, L., Haefner, B., Cremers and D.,
Inferring Super-Resolution Depth from a Moving Light-Source Enhanced RGB-D Sensor: A Variational Approach,

2019
Journal Articles

[J1] F. Pasa, V. Golkov, F. Pfeiffer, D. Cremers and D. Pfeiffer,
Efficient Deep Network Architectures for Fast Chest X-Ray Tuberculosis Screening and Visualization,

[J2] R. Wang, N. Yang, J. Stueckler and D. Cremers,
DirectShape: Photometric Alignment of Shape Priors for Visual Vehicle Pose and Shape Estimation,

[J3] J. Schuchardt, V. Golkov and D. Cremers,
Learning to Evolve,

A Non-invasive 3D Body Scanner and Software Tool towards Analysis of Scoliosis,

[J5] L. von Stumberg, P. Wenzel, Q. Khan and D. Cremers,
GN-Net: The Gauss-Newton Loss for Multi-Weather Relocalization,

[J6] M. Eisenberger, Z. Lähner and D. Cremers,
Smooth Shells: Multi-Scale Shape Registration with Functional Maps,

[J7] Haefner, B., Peng, S., Verma, A., Queau, Y., Cremers and D.,
Photometric Depth Super-Resolution,

[J8] Brahimi, M., Queau, Y., Haefner, B., Cremers and D.,
On well-posedness of uncalibrated photometric stereo under general lighting,

Conference and Workshop Papers
Author: Cremers

List of Publications

[C1] A. Vasilev, V. Golkov, M. Meissner, I. Lipp, E. Sgarlata, V. Tomassini, D. K. Jones and D. Cremers,
q-Space Novelty Detection with Variational Autoencoders,
MICCAI 2019 International Workshop on Computational Diffusion MRI, 2019, Oral Presentation.

[C2] P. Swazinna, V. Golkov, I. Lipp, E. Sgarlata, V. Tomassini, D. K. Jones and D. Cremers,
Negative-Unlabeled Learning for Diffusion MRI, 2019.

[C3] T. Möllenhoff and D. Cremers,
Lifting Vectorial Variational Problems: A Natural Formulation based on Geometric Measure Theory and Discrete Exterior Calculus,
2019, Oral Presentation.

[C4] V. Usenko, N. Demmel, D. Schubert, J. Stueckler and D. Cremers,
Visual-Inertial Mapping with Non-Linear Factor Recovery,

[C5] Haefner, B., Ye, Z., Gao, M., Wu, T., Queau, Y., Cremers and D.,
Variational Uncalibrated Photometric Stereo under General Lighting,
International Conference on Computer Vision (ICCV), Seoul, South Korea, October 2019.

[C6] Q. Khan, P. Wenzel, D. Cremers and L. Leal-Taixe,
Towards Generalizing Sensorimotor Control Across Weather Conditions,

[C7] M. Moeller, T. Möllenhoff and D. Cremers,
Controlling Neural Networks via Energy Dissipation,
International Conference on Computer Vision (ICCV), Seoul, South Korea, 10 2019.

[C8] S. Weiss, R. Maier, R. Westermann, D. Cremers and N. Thuerey,
Sparse Surface Constraints for Combining Physics-based Elasticity Simulation and Correspondence-Free Object Reconstruction,

[C9] D. Schubert, N. Demmel, L. von Stumberg, V. Usenko and D. Cremers,
Rolling-Shutter Modelling for Visual-Inertial Odometry,
November 2019.

[C10] C. Sommer, V. Usenko, D. Schubert, N. Demmel and D. Cremers,
Efficient Derivative Computation for Cumulative B-Splines on Lie Groups,

2018
Journal Articles

[J1] J. Engel, V. Koltun and D. Cremers,
Direct Sparse Odometry,
March 2018.

[J2] N. Yang, R. Wang, X. Gao and D. Cremers,
Challenges in Monocular Visual Odometry: Photometric Calibration, Motion Bias and Rolling Shutter Effect,
[J3] Queau, Y., Durix, B., Wu, T., Cremers, D., Lauze, F., Durou and J.-D.,
LED-based Photometric Stereo: Modeling, Calibration and Numerical Solution,

[J4] P. Bergmann, R. Wang and D. Cremers,
Online Photometric Calibration of Auto Exposure Video for Realtime Visual Odometry and SLAM,

[J5] E. Aljalbout, V. Golkov, Y. Siddiqui, M. Strobel and D. Cremers,
Clustering with Deep Learning: Taxonomy and New Methods,

[J6] L. Ma., J. Stueckler, T. Wu and D. Cremers,
Detailed Dense Inference with Convolutional Neural Networks via Discrete Wavelet Transform,
Aug 2018.

[J7] Tjaden, Henning, Schwanecke, Ulrich, Schmöer, Elmar, Cremers and Daniel,
A Region-based Gauss-Newton Approach to Real-Time Monocular Multiple Object Tracking,

Conference and Workshop Papers

[C1] Caner Hazirbas, Sebastian Georg Soyer, Maximilian Christian Staab, Laura Leal-Taixe and Daniel Cremers,
Deep Depth From Focus,
Asian Conference on Computer Vision (ACCV), December 2018.

[C2] E. Laude, T. Wu and D. Cremers,
A Nonconvex Proximal Splitting Algorithm under Moreau-Yosida Regularization,
International Conference on Artificial Intelligence and Statistics (AISTATS), 2018.

[C3] T. Möllenhoff, Z. Ye, T. Wu and D. Cremers,
Combinatorial Preconditioners for Proximal Algorithms on Graphs,
International Conference on Artificial Intelligence and Statistics (AISTATS), 2018.

q-Space Novelty Detection in Short Diffusion MRI Scans of Multiple Sclerosis, 2018.

[C6] B. T. Do, V. Golkov, G. E. Gürel and D. Cremers, 
PreCursor microRNA Identification Using Deep Convolutional Neural Networks, 
2018.

[C7] P. Haeusser, J. Plapp, V. Golkov, E. Aljalbout and D. Cremers, 
Associative Deep Clustering - Training a Classification Network with no Labels, 
Proc. of the German Conference on Pattern Recognition (GCPR), October 2018.

[C8] Nikolaus Mayer, Eddy Ilg, Philipp Fischer, Caner Hazirbas, Daniel Cremers, Alexey Dosovitskiy and Thomas Brox, 
What Makes Good Synthetic Training Data for Learning Disparity and Optical Flow Estimation?, 
September 2018.

[C9] T. Frerix, T. Möllenhoff, M. Moeller and D. Cremers, 
Proximal Backpropagation, 

[C10] L. von Stumberg, V. Usenko and D. Cremers, 
Direct Sparse Visual-Inertial Odometry using Dynamic Marginalization, 
May 2018.

The TUM VI Benchmark for Evaluating Visual-Inertial Odometry, 
October 2018.

[C12] X. Gao, R. Wang, N. Demmel and D. Cremers, 
LDSO: Direct Sparse Odometry with Loop Closure, 
iros, October 2018.

[C13] Z. Lähner, D. Cremers and T. Tung, 
DeepWrinkles: Accurate and Realistic Clothing Modeling, 
September 2018, Oral Presentation.

[C14] D. Schubert, N. Demmel, V. Usenko, J. Stueckler and D. Cremers, 
Direct Sparse Odometry With Rolling Shutter, 
September 2018, Oral Presentation.

[C15] V. Usenko, N. Demmel and D. Cremers, 
The Double Sphere Camera Model, 

[C16] I. Chiotellis, F. Zimmermann, D. Cremers and R. Triebel, 
Incremental Semi-Supervised Learning from Streams for Object Classification, 

[C17] P. Wenzel, Q. Khan, D. Cremers and L. Leal-Taixe, 
Modular Vehicle Control for Transferring Semantic Information Between Weather Conditions Using GANs, 
Conference on Robot Learning (CoRL), 2018.
[C18] Haefner, B., Queau, Y., Möllenhoff, T., Cremers and D.,
Fight ill-posedness with ill-posedness: Single-shot variational depth super-resolution from shading,
*IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2018, Spotlight Presentation.

2017

Journal Articles

[J1] V. Golkov, M. J. Skwark, A. Mirchev, G. Dikov, A. R. Geanes, J. Mendenhall, J. Meiler and D. Cremers,
3D Deep Learning for Biological Function Prediction from Physical Fields,

Genetic defects in s-spectrin and tau sensitize C. elegans axons to movement-induced damage via torque-tension coupling,

Tau Like Proteins Reduce Torque Generation in Microtubule Bundles,

[J4] J. Kukacka, V. Golkov and D. Cremers,
Regularization for Deep Learning: A Taxonomy,

Conference and Workshop Papers

[C1] M. Jaimez, T. J. Cashman, A. Fitzgibbon, J. Gonzalez-Jimenez and D. Cremers,
An Efficient Background Term for 3D Reconstruction and Tracking with Smooth Subdivision Surface Models,
2017.

[C2] L. Ma, J. Stueckler, C. Kerl and D. Cremers,
Multi-View Deep Learning for Consistent Semantic Mapping with RGB-D Cameras,
Vancouver, Canada, Sep 2017.

[C3] Vestner, M., Litman, R., Rodola, E., Bronstein, A., Cremers and D.,
Product Manifold Filter: Non-Rigid Shape Correspondence via Kernel Density Estimation in the Product Space,
2017.

[C4] M. Dzitsiuk, J. Sturm, R. Maier, L. Ma and D. Cremers,
De-noising, Stabilizing and Completing 3D Reconstructions On-the-go using Plane Priors,

[C5] L. von Stumberg, V. Usenko, J. Engel, J. Stueckler and D. Cremers,
From Monocular SLAM to Autonomous Drone Exploration,
[C6] Florian Walch, Caner Hazirbas, Laura Leal-Taixe, Torsten Sattler, Sebastian Hilsenbeck and Daniel Cremers,

*Establishment of an interdisciplinary workflow of machine learning-based Radiomics in sarcoma patients*,

[C8] Queau, Y., Pizenberg, M., Durou, J.-D., Cremers and D.,
*Microgeometry capture and RGB albedo estimation by photometric stereo without demosaicing*,

[C9] P. Haeusser, A. Mordvintsev and D. Cremers,
*Learning by Association - A versatile semi-supervised training method for neural networks*,
2017.

[C10] V. Usenko, L. von Stumberg, A. Pangercic and D. Cremers,
*Real-Time Trajectory Replanning for MAVs using Uniform B-splines and a 3D Circular Buffer*,
Vancouver, Canada, Sep 2017.

[C11] Tim Meinhardt, Michael Moeller, Caner Hazirbas and Daniel Cremers,
*Learning Proximal Operators: Using Denoising Networks for Regularizing Inverse Imaging Problems*,
October 2017.

*One-Shot Video Object Segmentation*,
Honolulu, USA, 2017.

[C13] Queau, Y., Melou, J., Durou, J.-D., Cremers and D.,
*Dense Multi-view 3D-reconstruction Without Dense Correspondences*,

[C14] P. Haeusser, T. Frerix, A. Mordvintsev and D. Cremers,
*Associative Domain Adaptation*,
2017.

*Efficient Deformable Shape Correspondence via Kernel Matching*,
*International Conference on 3D Vision (3DV)*, Qingdao, China, October 2017, Oral Presentation.

[C16] R. Maier, K. Kim, D. Cremers, J. Kautz and M. Niessner,
*Intrinsic3D: High-Quality 3D Reconstruction by Joint Appearance and Geometry Optimization with Spatially-Varying Lighting*,
[C17] T. Möllenhoff and D. Cremers,  
Sublabel-Accurate Discretization of Nonconvex Free-Discontinuity Problems,  

[C18] Queau, Y., Melou, J., Castan, F., Cremers, D., Durou and J.-D.,  
A Variational Approach to Shape-from-shading Under Natural Illumination,  

[C19] F. Bernard, F. R. Schmidt, J. Thunberg and D. Cremers,  
A Combinatorial Solution to Non-Rigid 3D Shape-to-Image Matching,  

[C20] Peng, S., Haefner, B., Queau, Y., Cremers and D.,  
Depth Super-Resolution Meets Uncalibrated Photometric Stereo,  
*International Conference on Computer Vision Workshops (ICCVW)*, 2017, Oral Presentation at ICCV Workshop on Color and Photometry in Computer Vision.

**2016**

**Journal Articles**

[J1] L. Cosmo, E. Rodola, A. Albarelli, F. Memoli and D. Cremers,  
Consistent Partial Matching of Shape Collections via Sparse Modeling,  

Anisotropic Diffusion Descriptors,  

[J3] V. Golkov, A. Dosovitskiy, J. I. Sperl, M. I. Menzel, M. Czisch, P. Sämann, T. Brox and D. Cremers,  
q-Space Deep Learning: Twelve-Fold Shorter and Model-Free Diffusion MRI Scans,  
35: 2016, Special Issue on Deep Learning.

[J4] O. Litany, E. Rodola, A. M. Bronstein, M. M. Bronstein and D. Cremers,  
Non-Rigid Puzzles,  

[J5] Vestner, M., Litman, R., Bronstein, A., Rodola, E., Cremers and D.,  
Bayesian Inference of Bijective Non-Rigid Shape Correspondence,  

**Book Chapters**

[BC1] Vestner, M., Rodola, E., Windheuser, T., Bulo, Rota Bulo, S., Cremers and D.,  
Applying Random Forests to the Problem of Dense Non-rigid Shape Correspondence,  

**Conference and Workshop Papers**
[C1] N. Mayer, E. Ilg, P. Haeusser, P. Fischer, D. Cremers, A. Dosovitskiy and T. Brox,
A Large Dataset to Train Convolutional Networks for Disparity, Optical Flow, and Scene Flow Estimation,
IEEE International Conference on Computer Vision and Pattern Recognition (CVPR), 2016.

Model-Free Novelty-Based Diffusion MRI,
Prague, Czech Republic, April 2016.

[C3] V. Golkov, M. J. Skwark, A. Golkov, A. Dosovitskiy, T. Brox, J. Meiler and D. Cremers,
Protein Contact Prediction from Amino Acid Co-Evolution Using Convolutional Networks for Graph-Valued Images,
Barcelona, Spain, December 2016.

[C4] Z. Lähner, E. Rodola, F. R. Schmidt, M. M. Bronstein and D. Cremers,
Efficient Globally Optimal 2D-to-3D Deformable Shape Matching,
May 2016.

[C5] A. Narr, R. Triebel and D. Cremers,
Stream-based Active Learning for Efficient and Adaptive Classification of 3D Objects,
May 2016.

SHREC16: Matching of Deformable Shapes with Topological Noise,
May 2016.

SHREC16: Partial Matching of Deformable Shapes,
May 2016.

[C8] T. Möllenhoff, E. Laude, M. Moeller, J. Lellmann and D. Cremers,
Sublabel-Accurate Relaxation of Nonconvex Energies,
2016.

[C9] L. Ma, C. Kerl, J. Stueckler and D. Cremers,
CPA-SLAM: Consistent Plane-Model Alignment for Direct RGB-D SLAM,
May 2016.

[C10] J. Engel, V. Usenko and D. Cremers,
A Photometrically Calibrated Benchmark For Monocular Visual Odometry,

[C11] J. Engel, V. Koltun and D. Cremers,
Direct Sparse Odometry,

[C12] E. Laude, T. Möllenhoff, M. Moeller, J. Lellmann and D. Cremers,
Sublabel-Accurate Convex Relaxation of Vectorial Multilabel Energies,
October 2016.

[C13] T. Windheuser and D. Cremers,
A Convex Solution to Spatially-Regularized Correspondence Problems,
October 2016.
[C14] S. Sharifzadeh, I. Chiotellis, R. Triebel and D. Cremers,
Learning to Drive using Inverse Reinforcement Learning and Deep Q-Networks,
NIPS Workshops, December 2016.

2015
Journal Articles

[J1] J. Diebold, C. Nieuwenhuis and D. Cremers,
Midrange Geometric Interactions for Semantic Segmentation,
2015.

[J2] J. Diebold, S. Tari and D. Cremers,
The Role of Diffusion in Figure Hunt Games,

[J3] S. Madhogaria, P. M. Baggenstoss, M. Schikora, W. Koch and D. Cremers,
Car detection by fusion of HOG and causal MRF,

[J4] M. Klodt, K. Herzog, R. Töpfer and D. Cremers,
Field phenotyping of grapevine growth using dense stereo reconstruction,

[J5] E. Rodola, A. Albarelli, D. Cremers and A. Torsello,
A Simple and Effective Relevance-based Point Sampling for 3D Shapes,

[J6] R. Mecca, E. Rodola and D. Cremers,
Realistic Photometric Stereo Using Partial Differential Irradiance Equation Ratios,

[J7] T. Möllenhoff, E. Strekalovskiy, M. Möller and D. Cremers,
The Primal-Dual Hybrid Gradient Method for Semiconvex Splittings,

Book Chapters

[BC1] V. Golkov, J. M. Portegies, A. Golkov, R. Duits and D. Cremers,
Holistic Image Reconstruction for Diffusion MRI,
Computational Diffusion MRI, Munich, Germany, Springer, October 2015, Book Chapter, and Oral Presentation at MICCAI 2015 Workshop on Computational Diffusion MRI.

Conference and Workshop Papers

[C1] M. Moeller, J. Diebold, G. Gilboa and D. Cremers,
Learning Nonlinear Spectral Filters for Color Image Reconstruction,
2015.

[C2] J. Diebold, N. Demmel, C. Hazirbas, M. Möller and D. Cremers,
Interactive Multi-label Segmentation of RGB-D Images,
2015.
[C3] C. Hazirbas, J. Diebold and D. Cremers, 
*Optimizing the Relevance-Redundancy Tradeoff for Efficient Semantic Segmentation*, 
2015.

[C4] T. Möllenhoff, E. Strekalovskiy, M. Möller and D. Cremers, 
*Low Rank Priors for Color Image Regularization*, 
2015.

[C5] M. Jaimez, M. Souiai, J. Gonzalez-Jimenez and D. Cremers, 
*A Primal-Dual Framework for Real-Time Dense RGB-D Scene Flow*, 
Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA), 2015.

[C6] J. Stühmer and D. Cremers, 
*A Fast Projection Method for Connectivity Constraints in Image Segmentation*, 
X.-C. Tai, E. Bae, T. F. Chan and M. Lysaker(Eds.), , 2015.

[C7] R. Mecca, E. Rodola and D. Cremers, 
*Analysis of Surface Parametrizations for Modern Photometric Stereo Modeling*, 
International Conference on Quality Control by Artificial Vision (QCAV), 2015.

[C8] F. Bergamasco, A. Albarelli, L. Cosmo, A. Torsello, E. Rodola and D. Cremers, 
*Adopting an Unconstrained Ray Model in Light-field Cameras for 3D Shape Reconstruction*, 
2015.

[C9] D. Mund, R. Triebel and D. Cremers, 
*Active Online Confidence Boosting for Efficient Object Classification*, 

P. A. Gomez, A. Haase, T. Brox and D. Cremers, 
*q-Space Deep Learning for Twelve-Fold Shorter and Model-Free Diffusion MRI Scans*, 
Munich, Germany, October 2015.

[C11] A. Dosovitskiy, P. Fischer, E. Ilg, P. Haeusser, C. Hazirbas, V. Golkov, P. van der Smagt, 
D. Cremers and T. Brox, 
*FlowNet: Learning Optical Flow with Convolutional Networks*, 
December 2015.

V. Evers, M. Fiore, H. Hung, O. A. Islas Ramirez, M. Joosse, H. Khambhaita, T. Kucner, 
Rafi, M. van Rooij and L. Zhang, 
*SPENCER: A Socially Aware Service Robot for Passenger Guidance and Help in Busy Airports*, 

[C13] J. Engel, J. Stueckler and D. Cremers, 
*Large-Scale Direct SLAM with Stereo Cameras*, 
2015.
Author: Cremers  List of Publications

[C14] D. Caruso, J. Engel and D. Cremers,  
Large-Scale Direct SLAM for Omnidirectional Cameras,  
2015.

[C15] Y. Tao, R. Triebel and D. Cremers,  
Semi-supervised Online Learning for Efficient Classification of Objects in 3D Data Streams,  
2015.

[C16] R. Maier, J. Stueckler and D. Cremers,  
Super-Resolution Keyframe Fusion for 3D Modeling with High-Quality Textures,  
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[C17] M. Jaimez, M. Souiai, J. Stueckler, J. Gonzalez-Jimenez and D. Cremers,  
Motion Cooperation: Smooth Piece-Wise Rigid Scene Flow from RGB-D Images,  

[C18] E. Rodola, M. Moeller and D. Cremers,  
Point-wise Map Recovery and Refinement from Functional Correspondence, Aachen, Germany, 2015, Received the Best Paper Award.

[C19] C. Kerl, J. Stueckler and D. Cremers,  
Dense Continuous-Time Tracking and Mapping with Rolling Shutter RGB-D Cameras,  
Santiago, Chile, 2015.

[C20] M. Souiai, M. R. Oswald, Y. Kee, J. Kim, M. Pollefeys and D. Cremers,  
Entropy Minimization for Convex Relaxation Approaches,  
Santiago, Chile, 2015.

[C21] F. Stark, C. Hazirbas, R. Triebel and D. Cremers,  
CAPTCHA Recognition with Active Deep Learning,  
GCPR Workshop on New Challenges in Neural Computation, Aachen, Germany, 2015.

[C22] J. Stühmer, S. Nowozin, A. Fitzgibbon, R. Szeliski, T. Perry, S. Acharya, D. Cremers and J. Shotton,  
Model-Based Tracking at 300Hz using Raw Time-of-Flight Observations,  
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2014  
Journal Articles

[J1] B. Goldluecke, M. Aubry, K. Kolev and D. Cremers,  
A Super-resolution Framework for High-Accuracy Multiview Reconstruction,  

[J2] E. Strekalovskiy, A. Chambolle and D. Cremers,  
Convex Relaxation of Vectorial Problems with Coupled Regularization,  

[J3] J. Engel, J. Sturm and D. Cremers,  
Scale-Aware Navigation of a Low-Cost Quadrocopter with a Monocular Camera,  
Author: Cremers

List of Publications

[J4] E. Rodola, S. Rota Bulo and D. Cremers,
Robust Region Detection via Consensus Segmentation of Deformable Shapes,

Books

[B1] D. Cremers, I. Reid, H. Saito and M.-S. Yang (Editors),
Computer Vision: ACCV 2014,
Springer 2014.

Book Chapters

Joint Super-Resolution Using Only One Anisotropic Low-Resolution Image per q-Space Coordinate,
Computational Diffusion MRI, Springer, 2014, Book Chapter, and Oral Presentation at MICCAI 2014 Workshop on Computational Diffusion MRI.

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[C4] D. Weikersdorfer, D. B. Adrian, D. Cremers and J. Conrad,
Event-based 3D SLAM with a depth-augmented dynamic vision sensor, 2014.

[C5] F. Steinbruecker, J. Sturm and D. Cremers,
Volumetric 3D Mapping in Real-Time on a CPU, Hongkong, China, 2014.

[C6] E. Rodola, S. Rota Bulo, T. Windheuser, M. Vestner and D. Cremers,
Dense Non-Rigid Shape Correspondence Using Random Forests, 2014.

[C7] Y. Kee, M. Souiai, D. Cremers and J. Kim,
Sequential Convex Relaxation for Mutual-Information-Based Unsupervised Figure-Ground Segmentation, 2014.
[C8] H. Alvarez, L.M. Paz, J. Sturm and D. Cremers, 
Collision Avoidance for Quadrotors with a Monocular Camera, 

[C9] J. Engel, T. Schöps and D. Cremers, 
LSD-SLAM: Large-Scale Direct Monocular SLAM, 
September 2014, Oral Presentation.

[C10] T. Schöps, J. Engel and D. Cremers, 
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September 2014, Best Short Paper Award.

[C13] R. Maier, J. Sturm and D. Cremers, 
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[C18] E. Strekalovskiy and D. Cremers, 

[C19] A. Kanezaki, E. Rodola, D. Cremers and T. Harada, 
[Taiou tenshuugou ruijido gakushuu wo mochiita goutai-higoutai buttai kenshutsu], 

[C20] M. Andreux, E. Rodola, M. Aubry and D. Cremers, 
Anisotropic Laplace-Beltrami Operators for Shape Analysis, Sixth Workshop on Non-Rigid Shape Analysis and Deformable Image Alignment (NORDIA), 2014.
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[C21] O. Dunkley, J. Engel, J. Sturm and D. Cremers, 
Visual-Inertial Navigation for a Camera-Equipped 25g Nano-Quadrotor, 

[C22] R. Triebel, J. Stühmer, M. Souiai and D. Cremers, 
Active Online Learning for Interactive Segmentation Using Sparse Gaussian Processes, 
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[C23] S. Debnath, S. S. Baishya, R. Triebel, V. Dutt and D. Cremers, 
Environment-adaptive Learning: How Clustering Helps to Obtain Good Training Data, 

[C24] A. Kanezaki, E. Rodola, D. Cremers and T. Harada, 
Learning Similarities for Rigid and Non-Rigid Object Detection, 
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[C25] D. Bender, M. Schikora, J. Sturm and D. Cremers, 
INS-Camera Calibration without Ground Control Points, 
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[C26] C. Kerl, M. Souiai, J. Sturm and D. Cremers, 
Towards Illumination-invariant 3D Reconstruction using ToF RGB-D Cameras, 
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[C27] F. R. Schmidt, T. Windheuser, U. Schlickewei and D. Cremers, 
Dense Elastic 3D Shape Matching, 

2013 
Journal Articles

[J1] C. Nieuwenhuis and D. Cremers, 
Spatially Varying Color Distributions for Interactive Multi-Label Segmentation, 

[J2] C. Nieuwenhuis, E. Toeppe and D. Cremers, 
A Survey and Comparison of Discrete and Continuous Multi-label Optimization Approaches for the Potts Model, 

[J3] B. Goldhauke, E. Strekalovskiy and D. Cremers, 
Tight Convex Relaxations for Vector-Valued Labeling, 

[J4] F. Endres, J. Hess, J. Sturm, D. Cremers and W. Burgard, 
3D Mapping with an RGB-D Camera, 
Author: Cremers

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Book Chapters


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[C9] E. Toeppe, C. Nieuwenhuis and D. Cremers, 
*Volume Constraints for Single View Reconstruction*, 
Portland, USA, 2013.

[C10] D. Weikersdorfer, A. Schick and D. Cremers, 
*Depth-adaptive Supervoxels for RGB-D Video Segmentation*, 
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[C11] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers, 
*Real-Time Camera Tracking and 3D Reconstruction Using Signed Distance Functions*, 

[C12] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers, 
*Direct Camera Pose Tracking and Mapping With Signed Distance Functions*, 
*Demo Track of the RGB-D Workshop on Advanced Reasoning with Depth Cameras at the Robotics: Science and Systems Conference (RSS)*, June 2013.

[C13] M. Souiai, E. Strekalovskiy, C. Nieuwenhuis and D. Cremers, 
*A Co-occurrence Prior for Continuous Multi-Label Optimization*, 
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[C14] F. Stangl, M. Souiai and D. Cremers, 
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