2020

**Journal Articles**

[J1] V. Usenko, N. Demmel, D. Schubert, J. Stueckler and D. Cremers, 
*Visual-Inertial Mapping with Non-Linear Factor Recovery*, 

[J2] L. von Stumberg, P. Wenzel, Q. Khan and D. Cremers, 

**Conference and Workshop Papers**

[C1] Sang, L., Haefner, B., Cremers and D., 
*Inferring Super-Resolution Depth from a Moving Light-Source Enhanced RGB-D Sensor: A Variational Approach*, 

[C2] R. Wang, N. Yang, J. Stueckler and D. Cremers, 
*DirectShape: Photometric Alignment of Shape Priors for Visual Vehicle Pose and Shape Estimation*, 

2019

**Journal Articles**

[J1] F. Pasa, V. Golkov, F. Pfeiffer, D. Cremers and D. Pfeiffer, 
*Efficient Deep Network Architectures for Fast Chest X-Ray Tuberculosis Screening and Visualization*, 

[J2] J. Schuchardt, V. Golkov and D. Cremers, 
*Learning to Evolve*, 

*A Non-invasive 3D Body Scanner and Software Tool towards Analysis of Scoliosis*, 

[J4] M. Eisenberger, Z. Lähner and D. Cremers, 
*Smooth Shells: Multi-Scale Shape Registration with Functional Maps*, 

[J5] Haefner, B., Peng, S., Verma, A., Queau, Y., Cremers and D., 
*Photometric Depth Super-Resolution*, 
[J6] Brahimi, M., Queau, Y., Haefner, B., Cremers and D.,
On well-posedness of uncalibrated photometric stereo under general lighting,

[J7] Laude, E., Ochs, P., Cremers and D.,
Bregman Proximal Mappings and Bregman-Moreau Envelopes under Relative
Prox-Regularity,
2019.

[J8] Mahesh Chandra Mukkamala, Felix Westerkamp, Emanuel Laude, Daniel Cremers and
Peter Ochs,
Bregman Proximal Framework for Deep Linear Neural Networks,

Conference and Workshop Papers

[C1] A. Vasilev, V. Golkov, M. Meissner, I. Lipp, E. Sgarlata, V. Tomassini, D. K. Jones and
D. Cremers,
q-Space Novelty Detection with Variational Autoencoders,
*MICCAI 2019 International Workshop on Computational Diffusion MRI*, 2019, Oral Pre-
sentation.

[C2] P. Swazinna, V. Golkov, I. Lipp, E. Sgarlata, V. Tomassini, D. K. Jones and D. Cremers,
Negative-Unlabeled Learning for Diffusion MRI,
2019.

[C3] T. Möllenhoff and D. Cremers,
Lifting Vectorial Variational Problems: A Natural Formulation based on Geo-
metric Measure Theory and Discrete Exterior Calculus,
2019, Oral Presentation.

[C4] Haefner, B., Ye, Z., Gao, M., Wu, T., Queau, Y., Cremers and D.,
Variational Uncalibrated Photometric Stereo under General Lighting,
*International Conference on Computer Vision (ICCV)*, Seoul, South Korea, October 2019.

[C5] Q. Khan, P. Wenzel, D. Cremers and L. Leal-Taixe,
Towards Generalizing Sensorimotor Control Across Weather Conditions,

[C6] M. Moeller, T. Möllenhoff and D. Cremers,
Controlling Neural Networks via Energy Dissipation,
*International Conference on Computer Vision (ICCV)*, Seoul, South Korea, 10 2019.

[C7] S. Weiss, R. Maier, R. Westermann, D. Cremers and N. Thuerey,
Sparse Surface Constraints for Combining Physics-based Elasticity Simulation
and Correspondence-Free Object Reconstruction,

[C8] D. Schubert, N. Demmel, L. von Stumberg, V. Usenko and D. Cremers,
Rolling-Shutter Modelling for Visual-Inertial Odometry,
November 2019.

[C9] C. Sommer, V. Usenko, D. Schubert, N. Demmel and D. Cremers,
Efficient Derivative Computation for Cumulative B-Splines on Lie Groups,
Author: Cremers
List of Publications

[C10] P. Brechet, T. Wu, T. Möllenhoff and D. Cremers,
Informative GANs via Structured Regularization of Optimal Transport,

2018
Journal Articles

[J1] J. Engel, V. Koltun and D. Cremers,
Direct Sparse Odometry,
March 2018.

[J2] N. Yang, R. Wang, X. Gao and D. Cremers,
Challenges in Monocular Visual Odometry: Photometric Calibration, Motion Bias and Rolling Shutter Effect,

[J3] Queau, Y., Durix, B., Wu, T., Cremers, D., Lauze, F., Durou and J.-D.,
LED-based Photometric Stereo: Modeling, Calibration and Numerical Solution,

[J4] P. Bergmann, R. Wang and D. Cremers,
Online Photometric Calibration of Auto Exposure Video for Realtime Visual Odometry and SLAM,

[J5] E. Aljalbout, V. Golkov, Y. Siddiqui, M. Strobel and D. Cremers,
Clustering with Deep Learning: Taxonomy and New Methods,

[J6] L. Ma,, J. Stueckler, T. Wu and D. Cremers,
Detailed Dense Inference with Convolutional Neural Networks via Discrete Wavelet Transform,
Aug 2018.

[J7] Tjaden, Henning, Schwanecke, Ulrich, Schömer, Elmar, Cremers and Daniel,
A Region-based Gauss-Newton Approach to Real-Time Monocular Multiple Object Tracking,

Conference and Workshop Papers

[C1] Caner Hazirbas, Sebastian Georg Soyer, Maximilian Christian Staab, Laura Leal-Taixe and Daniel Cremers,
Deep Depth From Focus,
*Asian Conference on Computer Vision (ACCV)*, December 2018.

[C2] E. Laude, T. Wu and D. Cremers,
A Nonconvex Proximal Splitting Algorithm under Moreau-Yosida Regularization,
*International Conference on Artificial Intelligence and Statistics (AISTATS)*, 2018.
T. Möllenhoff, Z. Ye, T. Wu and D. Cremers,
Combinatorial Preconditioners for Proximal Algorithms on Graphs,
*International Conference on Artificial Intelligence and Statistics (AISTATS)*, 2018.

V. Golkov, A. Vasilev, F. Pasa, I. Lipp, W. Boubaker, E. Sgarlata, F. Pfeiffer, V. Tomassini,
D. K. Jones and D. Cremers,
q-Space Novelty Detection in Short Diffusion MRI Scans of Multiple Sclerosis,
2018.

V. Golkov, P. Swazinna, M. M. Schmitt, Q. A. Khan, C. M. W. Tax, M. Serahlazau, F.
Pasa, F. Pfeiffer, G. J. Biessels, A. Leemans and D. Cremers,
q-Space Deep Learning for Alzheimer’s Disease Diagnosis: Global Prediction and Weakly-Supervised Localization,
2018.

B. T. Do, V. Golkov, G. E. Gürel and D. Cremers,
Precursor microRNA Identification Using Deep Convolutional Neural Networks,
2018.

P. Haeusser, J. Plapp, V. Golkov, E. Aljalbout and D. Cremers,
Associative Deep Clustering - Training a Classification Network with no Labels,
*Proc. of the German Conference on Pattern Recognition (GCPR)*, October 2018.

Nikolaus Mayer, Eddy Ilg, Philipp Fischer, Caner Hazirbas, Daniel Cremers, Alexey Dosovitskiy and Thomas Brox,
What Makes Good Synthetic Training Data for Learning Disparity and Optical Flow Estimation?,
September 2018.

T. Frerix, T. Möllenhoff, M. Moeller and D. Cremers,
Proximal Backpropagation,

L. von Stumberg, V. Usenko and D. Cremers,
Direct Sparse Visual-Inertial Odometry using Dynamic Marginalization,
May 2018.

D. Schubert, T. Goll, N. Demmel, V. Usenko, J. Stueckler and D. Cremers,
The TUM VI Benchmark for Evaluating Visual-Inertial Odometry,
October 2018.

X. Gao, R. Wang, N. Demmel and D. Cremers,
LDSO: Direct Sparse Odometry with Loop Closure,
*iros*, October 2018.

Z. Lähner, D. Cremers and T. Tung,
DeepWrinkles: Accurate and Realistic Clothing Modeling,
September 2018, *Oral Presentation*.

D. Schubert, N. Demmel, V. Usenko, J. Stueckler and D. Cremers,
Direct Sparse Odometry With Rolling Shutter,
September 2018, *Oral Presentation*.
Author: Cremers
List of Publications

[C15] V. Usenko, N. Demmel and D. Cremers,
The Double Sphere Camera Model,

[C16] I. Chiotellis, F. Zimmermann, D. Cremers and R. Triebel,
Incremental Semi-Supervised Learning from Streams for Object Classification,

[C17] P. Wenzel, Q. Khan, D. Cremers and L. Leal-Taixe,
Modular Vehicle Control for Transferring Semantic Information Between Weather Conditions Using GANs,
Conference on Robot Learning (CoRL), 2018.

[C18] Haefner, B., Queau, Y., Möllenhoff, T., Cremers and D.,
Fight ill-posedness with ill-posedness: Single-shot variational depth super-resolution from shading,

2017
Journal Articles

[J1] V. Golkov, M. J. Skwark, A. Mirchev, G. Dikov, A. R. Geanes, J. Mendenhall, J. Meiler and D. Cremers,
3D Deep Learning for Biological Function Prediction from Physical Fields,

Tau Like Proteins Reduce Torque Generation in Microtubule Bundles,

[J3] J. Kukacka, V. Golkov and D. Cremers,
Regularization for Deep Learning: A Taxonomy,

Conference and Workshop Papers

[C1] M. Jaimez, T. J. Cashman, A. Fitzgibbon, J. Gonzalez-Jimenez and D. Cremers,
An Efficient Background Term for 3D Reconstruction and Tracking with Smooth Subdivision Surface Models,
2017.

[C2] L. Ma, J. Stueckler, C. Kerl and D. Cremers,
Multi-View Deep Learning for Consistent Semantic Mapping with RGB-D Cameras,
Vancouver, Canada, Sep 2017.

[C3] Vestner, M., Litman, R., Rodola, E., Bronstein, A., Cremers and D.,
Product Manifold Filter: Non-Rigid Shape Correspondence via Kernel Density Estimation in the Product Space,
2017.


2016
Journal Articles


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[BC1] Vestner, M., Rodola, E., Windheuser, T., Bulo, Rota Bulo, S., Cremers and D.,
Applying Random Forests to the Problem of Dense Non-rigid Shape Correspondence,

Conference and Workshop Papers

[C1] N.Mayer, E.Ilg, P.Haeusser, P.Fischer, D.Cremers, A.Dosovitskiy and T.Brox,
A Large Dataset to Train Convolutional Networks for Disparity, Optical Flow, and Scene Flow Estimation,
IEEE International Conference on Computer Vision and Pattern Recognition (CVPR),
2016.

Model-Free Novelty-Based Diffusion MRI,
Prague, Czech Republic, April 2016.

[C3] V. Golkov, M. J. Skwark, A. Golkov, A. Dosovitskiy, T. Brox, J. Meiler and D. Cremers,
Protein Contact Prediction from Amino Acid Co-Evolution Using Convolutional Networks for Graph-Valued Images,
Barcelona, Spain, December 2016.

[C4] Z. Lähner, E. Rodola, F. R. Schmidt, M. M. Bronstein and D. Cremers,
Efficient Globally Optimal 2D-to-3D Deformable Shape Matching,
May 2016.

[C5] A. Narr, R. Triebel and D. Cremers,
Stream-based Active Learning for Efficient and Adaptive Classification of 3D Objects,
May 2016.

SHREC16: Matching of Deformable Shapes with Topological Noise,
May 2016.

SHREC16: Partial Matching of Deformable Shapes,
May 2016.

[C8] T. Möllenhoff, E. Laude, M. Moeller, J. Lellmann and D. Cremers,
Sublabel-Accurate Relaxation of Nonconvex Energies,
2016.

[C9] L. Ma, C. Kerl, J. Stueckler and D. Cremers,
CPA-SLAM: Consistent Plane-Model Alignment for Direct RGB-D SLAM,
May 2016.

[C10] J. Engel, V. Usenko and D. Cremers,
A Photometrically Calibrated Benchmark For Monocular Visual Odometry,
J. Engel, V. Koltun and D. Cremers, 
Direct Sparse Odometry, 

E. Laude, T. Möllenhoff, M. Moeller, J. Lellmann and D. Cremers, 
Sublabel-Accurate Convex Relaxation of Vectorial Multilabel Energies, 
October 2016.

T. Windheuser and D. Cremers, 
A Convex Solution to Spatially-Regularized Correspondence Problems, 
October 2016.

S. Sharifzadeh, I. Chiotellis, R. Triebel and D. Cremers, 
Learning to Drive using Inverse Reinforcement Learning and Deep Q-Networks, 
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J. Diebold, C. Nieuwenhuis and D. Cremers, 

J. Diebold, S. Tari and D. Cremers, 
The Role of Diffusion in Figure Hunt Games, 52(1): 108-123, 2015.

S. Madhogaria, P. M. Baggenstoss, M. Schikora, W. Koch and D. Cremers, 

M. Klodt, K. Herzog, R. Töpfer and D. Cremers, 

E. Rodola, A. Albarelli, D. Cremers and A. Torsello, 

R. Mecca, E. Rodola and D. Cremers, 

T. Möllenhoff, E. Strekalovskiy, M. Möller and D. Cremers, 

Book Chapters

V. Golkov, J. M. Portegies, A. Golkov, R. Duits and D. Cremers, 
Holistic Image Reconstruction for Diffusion MRI, Computational Diffusion MRI, Munich, Germany, Springer, October 2015, Book Chapter, and Oral Presentation at MICCAI 2015 Workshop on Computational Diffusion MRI.
Conference and Workshop Papers

[C1] M. Moeller, J. Diebold, G. Gilboa and D. Cremers,
Learning Nonlinear Spectral Filters for Color Image Reconstruction,
2015.

[C2] J. Diebold, N. Demmel, C. Hazirbas, M. Möller and D. Cremers,
Interactive Multi-label Segmentation of RGB-D Images,
2015.

[C3] C. Hazirbas, J. Diebold and D. Cremers,
Optimizing the Relevance-Redundancy Tradeoff for Efficient Semantic Seg-
mentation,
2015.

[C4] T. Möllenhoff, E. Strekalovskiy, M. Möller and D. Cremers,
Low Rank Priors for Color Image Regularization,
2015.

[C5] M. Jaimez, M. Souiai, J. Gonzalez-Jimenez and D. Cremers,
A Primal-Dual Framework for Real-Time Dense RGB-D Scene Flow,
Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA), 2015.

[C6] J. Stühmer and D. Cremers,
A Fast Projection Method for Connectivity Constraints in Image Segmentati-
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X.-C. Tai, E. Bae, T. F. Chan and M. Lysaker(Eds.), , 2015.

[C7] R. Mecca, E. Rodola and D. Cremers,
Analysis of Surface Parametrizations for Modern Photometric Stereo Mode-
ling,
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[C8] F. Bergamasco, A. Albarelli, L. Cosmo, A. Torsello, E. Rodola and D. Cremers,
Adopting an Unconstrained Ray Model in Light-field Cameras for 3D Shape
Reconstruction,
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[C9] D. Mund, R. Triebel and D. Cremers,
Active Online Confidence Boosting for Efficient Object Classification,

P. A. Gomez, A. Haase, T. Brox and D. Cremers,
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Scans,
Munich, Germany, October 2015.

[C11] A. Dosovitskiy, P. Fischer, E. Ilg, P. Haeusser, C. Hazirbas, V. Golkov, P. van der Smagt,
D. Cremers and T. Brox,
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Semi-supervised Online Learning for Efficient Classification of Objects in 3D Data Streams,
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Super-Resolution Keyframe Fusion for 3D Modeling with High-Quality Textures,
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Point-wise Map Recovery and Refinement from Functional Correspondence,
Aachen, Germany, 2015, Received the Best Paper Award.

Dense Continuous-Time Tracking and Mapping with Rolling Shutter RGB-D Cameras,
Santiago, Chile, 2015.

Entropy Minimization for Convex Relaxation Approaches,
Santiago, Chile, 2015.

CAPTCHA Recognition with Active Deep Learning,
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Santiago, Chile, 2015.
2014
Journal Articles

[J1] B. Goldluecke, M. Aubry, K. Kolev and D. Cremers,
A Super-resolution Framework for High-Accuracy Multiview Reconstruction,

[J2] E. Strekalovskiy, A. Chambolle and D. Cremers,
Convex Relaxation of Vectorial Problems with Coupled Regularization,

[J3] J. Engel, J. Sturm and D. Cremers,
Scale-Aware Navigation of a Low-Cost Quadrocopter with a Monocular Camera,

[J4] E. Rodola, S. Rota Bulo and D. Cremers,
Robust Region Detection via Consensus Segmentation of Deformable Shapes,

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[B1] D. Cremers, I. Reid, H. Saito and M.-S. Yang (Editors),
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Joint Super-Resolution Using Only One Anisotropic Low-Resolution Image per q-Space Coordinate,
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2014.

Semi-Joint Reconstruction for Diffusion MRI Denoising Imposing Similarity of Edges in Similar Diffusion-Weighted Images,
2014.

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[C4] D. Weikersdorfer, D. B. Adrian, D. Cremers and J. Conrad,
Event-based 3D SLAM with a depth-augmented dynamic vision sensor,
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[C5] F. Steinbruecker, J. Sturm and D. Cremers,
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Hongkong, China, 2014.

[C6] E. Rodola, S. Rota Bulo, T. Windheuser, M. Vestner and D. Cremers,
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[C7] Y. Kee, M. Souiai, D. Cremers and J. Kim,
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Figure-Ground Segmentation,
2014.

[C8] H. Alvarez, L.M. Paz, J. Sturm and D. Cremers,
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[C9] J. Engel, T. Schöps and D. Cremers,
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September 2014, Oral Presentation.

[C10] T. Schöps, J. Engel and D. Cremers,
Semi-Dense Visual Odometry for AR on a Smartphone,
September 2014, Best Short Paper Award.

[C11] T. Windheuser, M. Vestner, E. Rodola, R. Triebel and D. Cremers,
Optimal Intrinsic Descriptors for Non-Rigid Shape Analysis,
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[C12] M. Strobel, J. Diebold and D. Cremers,
Flow and Color Inpainting for Video Completion,
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[C13] R. Maier, J. Sturm and D. Cremers,
Submap-based Bundle Adjustment for 3D Reconstruction from RGB-D Data,
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[C14] T. Gurdan, M. R. Oswald, D. Gurdan and D. Cremers,
Spatial and Temporal Interpolation of Multi-View Image Sequences,
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[C15] M. R. Oswald and D. Cremers,
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[C16] C. Nieuwenhuis, S. Hawe, M. Kleinsteuber and D. Cremers,
Co-Sparse Textural Similarity for Interactive Segmentation,
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[C17] M. R. Oswald, J. Stühner and D. Cremers,
Generalized Connectivity Constraints for Spatio-temporal 3D Reconstruction,
[C18] E. Strekalovskiy and D. Cremers,
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[C19] A. Kanezaki, E. Rodola, D. Cremers and T. Harada,
[Taiou tenshuungou ruijido gakushuu wo mochiita goutai-higoutai buttaikenshutsu],

[C20] M. Andreux, E. Rodola, M. Aubry and D. Cremers,
Anisotropic Laplace-Beltrami Operators for Shape Analysis,
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[C21] O. Dunkley, J. Engel, J. Sturm and D. Cremers,
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[C22] R. Triebel, J. Stühmer, M. Souiai and D. Cremers,
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[C23] S. Debnath, S. S. Baishya, R. Triebel, V. Dutt and D. Cremers,
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[C24] A. Kanezaki, E. Rodola, D. Cremers and T. Harada,
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[C25] D. Bender, M. Schikora, J. Sturm and D. Cremers,
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[C26] C. Kerl, M. Souiai, J. Sturm and D. Cremers,
Towards Illumination-invariant 3D Reconstruction using ToF RGB-D Cameras,
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[C27] F. R. Schmidt, T. Windheuser, U. Schlickewei and D. Cremers,
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[J1] C. Nieuwenhuis and D. Cremers,
Spatially Varying Color Distributions for Interactive Multi-Label Segmentation,
Author: Cremers

List of Publications

[J2] C. Nieuwenhuis, E. Toeppe and D. Cremers,
A Survey and Comparison of Discrete and Continuous Multi-label Optimization Approaches for the Potts Model,

[J3] B. Goldluecke, E. Strekalovskiy and D. Cremers,
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[J4] F. Endres, J. Hess, J. Sturm, D. Cremers and W. Burgard,
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[J5] Liu, Z., Beetz, M., Cremers, D., Gall, J., Li, W., Pangercic, D., Sturm, J., Tai and Y.-W.,
Introduction to the special issue on visual understanding and applications with RGB-D cameras,

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[BC1] M. Klodt, F. Steinbruecker and D. Cremers,
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[C3] V. Golkov, T. Sprenger, A. Menini, M.I. Menzel, D. Cremers and J.I. Sperl,
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Line-Process-Based Joint SENSE Reconstruction of Diffusion Images with Intensity Inhomogeneity Correction and Noise Non-Stationarity Correction, 2013, Certificate of Merit Award.

[C5] V. Golkov, M.I. Menzel, T. Sprenger, A. Menini, D. Cremers and J.I. Sperl,
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[C6] V. Golkov, M.I. Menzel, T. Sprenger, A. Menini, D. Cremers and J.I. Sperl,
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Noise Reduction in Accelerated Diffusion Spectrum Imaging through Integration of SENSE Reconstruction into Joint Reconstruction in Combination with q-Space Compressed Sensing, 
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[C8] C. Kerl, J. Sturm and D. Cremers, 
Robust Odometry Estimation for RGB-D Cameras, 
May 2013, Best Vision Paper Award - Finalist.

[C9] E. Toepppe, C. Nieuwenhuis and D. Cremers, 
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[C10] D. Weikersdorfer, A. Schick and D. Cremers, 
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[C11] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers, 
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[C12] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers, 
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[C13] M. Souiai, E. Strekalovskiy, C. Nieuwenhuis and D. Cremers, 
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[C17] T. Naseer, J. Sturm and D. Cremers, 
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[C18] M. Klodt, J. Sturm and D. Cremers, 
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