Journal Articles

[J1] V. Usenko, N. Demmel, D. Schubert, J. Stueckler and D. Cremers,
Visual-Inertial Mapping with Non-Linear Factor Recovery,

Cloud-based collaborative 3D mapping in real-time with low-cost robots,

Conference and Workshop Papers

[C1] C. Sommer, V. Usenko, D. Schubert, N. Demmel and D. Cremers,

[C2] D. Schubert, N. Demmel, L. von Stumberg, V. Usenko and D. Cremers,

[C3] L. von Stumberg, V. Usenko and D. Cremers,

The TUM VI Benchmark for Evaluating Visual-Inertial Odometry, October 2018.

[C5] D. Schubert, N. Demmel, V. Usenko, J. Stueckler and D. Cremers,

[C6] V. Usenko, N. Demmel and D. Cremers,
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[C8] V. Usenko, L. von Stumberg, A. Pangeric and D. Cremers,
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[C9] V. Usenko, J. Engel, J. Stueckler and D. Cremers,

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PhDThesis