Journal Articles

Cloud-based collaborative 3D mapping in real-time with low-cost robots,

Conference and Workshop Papers

[C1] V. Usenko, N. Demmel, D. Schubert, J. Stueckler and D. Cremers,
Visual-Inertial Mapping with Non-Linear Factor Recovery,

[C2] D. Schubert, N. Demmel, L. von Stumberg, V. Usenko and D. Cremers,
Rolling-Shutter Modelling for Visual-Inertial Odometry,
November 2019.

[C3] C. Sommer, V. Usenko, D. Schubert, N. Demmel and D. Cremers,
Efficient Derivative Computation for Cumulative B-Splines on Lie Groups,

[C4] L. von Stumberg, V. Usenko and D. Cremers,
Direct Sparse Visual-Inertial Odometry using Dynamic Marginalization,
May 2018.

The TUM VI Benchmark for Evaluating Visual-Inertial Odometry,
October 2018.

[C6] D. Schubert, N. Demmel, V. Usenko, J. Stueckler and D. Cremers,
Direct Sparse Odometry With Rolling Shutter,
September 2018, Oral Presentation.

[C7] V. Usenko, N. Demmel and D. Cremers,
The Double Sphere Camera Model,

[C8] L. von Stumberg, V. Usenko, J. Engel, J. Stueckler and D. Cremers,
From Monocular SLAM to Autonomous Drone Exploration,
European Conference on Mobile Robots (ECMR), September 2017.

[C9] V. Usenko, L. von Stumberg, A. Pangeric and D. Cremers,
Real-Time Trajectory Replanning for MAVs using Uniform B-splines and a 3D Circular Buffer,
Vancouver, Canada, Sep 2017, Best Paper Award - Finalist ()

[C10] V. Usenko, J. Engel, J. Stueckler and D. Cremers,
Direct Visual-Inertial Odometry with Stereo Cameras,
May 2016.

[C11] J. Engel, V. Usenko and D. Cremers,
A Photometrically Calibrated Benchmark For Monocular Visual Odometry,
Author: V. Usenko

List of Publications

[C12] V. Usenko, J. Engel, J. Stueckler and D. Cremers,
Reconstructing Street-Scenes in Real-Time From a Driving Car,

Furniture Classification using WWW CAD Models,

PhDThesis