Journal Articles

Cloud-based collaborative 3D mapping in real-time with low-cost robots,  

Conference and Workshop Papers

[C1] V. Usenko, N. Demmel, D. Schubert, J. Stueckler and D. Cremers,  
Visual-Inertial Mapping with Non-Linear Factor Recovery,  

[C2] L. von Stumberg, V. Usenko and D. Cremers,  
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May 2018.

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[C4] D. Schubert, N. Demmel, V. Usenko, J. Stueckler and D. Cremers,  
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[C7] V. Usenko, L. von Stumberg, A. Pangercic and D. Cremers,  
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[C8] V. Usenko, J. Engel, J. Stueckler and D. Cremers,  
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[C10] V. Usenko, J. Engel, J. Stueckler and D. Cremers,  
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