

Conference and Workshop Papers

- [C1] J. Sturm, C. Plagemann and W. Burgard,
Adaptive Body Scheme Models for Robust Robotic Manipulation,
Robotics: Science and Systems Conference (RSS), Zurich, Switzerland, June 2008.
- [C2] J. Sturm, C. Plagemann and W. Burgard,
Body Scheme Learning and Life-Long Adaptation for Robotic Manipulation,
Proc. of the Workshop on Robot Manipulation at the Robotics: Science and Systems Conference (RSS), Zurich, Switzerland, June 2008.