Conference and Workshop Papers

[C1] J. Sturm, C. Plagemann and W. Burgard,
Adaptive Body Scheme Models for Robust Robotic Manipulation,
Robotsics: Science and Systems Conference (RSS), Zurich, Switzerland, June 2008.

[C2] J. Sturm, C. Plagemann and W. Burgard,
Body Scheme Learning and Life-Long Adaptation for Robotic Manipulation,