Journal Articles

[J1] J. Engel, J. Sturm and D. Cremers,
Scale-Aware Navigation of a Low-Cost Quadrocopter with a Monocular Camera,

[J2] F. Endres, J. Hess, J. Sturm, D. Cremers and W. Burgard,
3D Mapping with an RGB-D Camera,

[J3] Liu, Z., Beetz, M., Cremers, D., Gall, J., Li, W., Pangercic, D., Sturm, J., Tai and Y.-W.,
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[J4] S. Chitta, J. Sturm, M. Piccoli and W. Burgard,
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[J5] J. Sturm, C. Stachniss and W. Burgard,
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[J6] J. Sturm, C. Plagemann and W. Burgard,
Body schema learning for robotic manipulators from visual self-perception,

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[B1] J. Sturm,
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[BC1] Sturm, J., Plagemann, C., Burgard and W.,
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[C1] M. Dzitsink, J. Sturm, R. Maier, L. Ma and D. Cremers,
De-noising, Stabilizing and Completing 3D Reconstructions On-the-go using Plane Priors,
[C2] F. Steinbruecker, J. Sturm and D. Cremers, 
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[C3] H. Alvarez, L.M. Paz, J. Sturm and D. Cremers, 
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[C4] R. Maier, J. Sturm and D. Cremers, 
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[C5] O. Dunkley, J. Engel, J. Sturm and D. Cremers, 
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INS-Camera Calibration without Ground Control Points, 
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[C8] C. Kerl, J. Sturm and D. Cremers, 
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[C9] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers, 
Real-Time Camera Tracking and 3D Reconstruction Using Signed Distance Functions, 

[C10] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers, 
Direct Camera Pose Tracking and Mapping With Signed Distance Functions, 
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[C12] C. Kerl, J. Sturm and D. Cremers, 
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[C13] T. Naseer, J. Sturm and D. Cremers, 
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[C14] M. Klodt, J. Sturm and D. Cremers, 
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[C22] T. Ruehr, J. Sturm, D. Pangercic, M. Beetz and D. Cremers, 
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[C24] J. Engel, J. Sturm and D. Cremers, 
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[C25] J. Sturm, N. Engelhard, F. Endres, W. Burgard and D. Cremers, 
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C28] J. Hess, J. Sturm and W. Burgard,
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[C49] A. Visser, P. van Rossum, J. Westra, J. Sturm, D. A. van Soest and M. de Greef,
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[PhD1] J. Sturm,
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