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[C17] Caner Hazirbas, Sebastian Georg Soyer, Maximilian Christian Staab, Laura Leal-Taixe 
and Daniel Cremers, 
Deep Depth From Focus, 
Asian Conference on Computer Vision (ACCV), December 2018.

[C18] E. Laude, T. Wu and D. Cremers, 
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[C19] T. Möllenhoff, Z. Ye, T. Wu and D. Cremers, 
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[C20] V. Golkov, A. Vasilyev, F. Pasa, I. Lipp, W. Boubaker, E. Sgarlata, F. Pfeiffer, V. Tomassini, 
D. K. Jones and D. Cremers, 
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2018.

Pasa, F. Pfeiffer, G. J. Biessels, A. Leemans and D. Cremers, 
q-Space Deep Learning for Alzheimer’s Disease Diagnosis: Global Prediction 
and Weakly-Supervised Localization, 
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[C23] P. Haeusser, J. Plapp, V. Golkov, E. Aljalbout and D. Cremers,

Associative Deep Clustering - Training a Classification Network with no Labels,

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[C24] Nikolaus Mayer, Eddy Ilg, Philipp Fischer, Caner Hazirbas, Daniel Cremers, Alexey Dosovitskiy and Thomas Brox,

What Makes Good Synthetic Training Data for Learning Disparity and Optical Flow Estimation?,

September 2018.

[C25] T. Frerix, T. Möllenhoff, M. Moeller and D. Cremers,

Proximal Backpropagation,


Discrete-Continuous ADMM for Transductive Inference in Higher-Order MRFs,

2018.

[C27] L. von Stumberg, V. Usenko and D. Cremers,

Direct Sparse Visual-Inertial Odometry using Dynamic Marginalization,

May 2018.


The TUM VI Benchmark for Evaluating Visual-Inertial Odometry,

October 2018.

[C29] X. Gao, R. Wang, N. Demmel and D. Cremers,

LDSO: Direct Sparse Odometry with Loop Closure,

iros, October 2018.

[C30] Z. Lähner, D. Cremers and T. Tung,

DeepWrinkles: Accurate and Realistic Clothing Modeling,

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[C31] D. Schubert, N. Demmel, V. Usenko, J. Stueckler and D. Cremers,

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[C32] V. Usenko, N. Demmel and D. Cremers,

The Double Sphere Camera Model,


[C33] I. Chiotellis, F. Zimmermann, D. Cremers and R. Triebel,

Incremental Semi-Supervised Learning from Streams for Object Classification,


6DoF Pose Estimation for Industrial Manipulation based on Synthetic Data,

[C35] C. Nissler, M. Durner, Z.-C. Marton and R. Triebel, 
Simultaneous Calibration and Mapping, 

[C36] P. Wenzel, Q. Khan, D. Cremers and L. Leal-Taixe, 
Modular Vehicle Control for Transferring Semantic Information Between Weather Conditions Using GANs, 
*Conference on Robot Learning (CoRL)*, 2018.

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Fight ill-posedness with ill-posedness: Single-shot variational depth super-resolution from shading, 
*IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2018, Spotlight Presentation.

[C38] I. Grixa, P. Schulz, W. Stürzl and R. Triebel, 
Appearance-Based Along-Route Localization for Planetary Missions, 

Implicit 3D Orientation Learning for 6D Object Detection from RGB Images, 
September 2018, Best Paper Award.

[C40] M. Denninger and R. Triebel, 
Persistent Anytime Learning of Objects from Unseen Classes, 

[C41] M. Jaimez, C. Kerl, J. Gonzalez-Jimenez and D. Cremers, 
Fast Odometry and Scene Flow from RGB-D Cameras based on Geometric Clustering, 
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An Efficient Background Term for 3D Reconstruction and Tracking with Smooth Subdivision Surface Models, 
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[C43] L. Ma, J. Stueckler, C. Kerl and D. Cremers, 
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[C44] Vestner, M., Litman, R., Rodola, E., Bronstein, A., Cremers and D., 
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De-noising, Stabilizing and Completing 3D Reconstructions On-the-go using Plane Priors, 

[C46] L. von Stumberg, V. Usenko, J. Engel, J. Stueckler and D. Cremers, 
From Monocular SLAM to Autonomous Drone Exploration, 
[C47] Florian Walch, Caner Hazirbas, Laura Leal-Taixe, Torsten Sattler, Sebastian Hilsenbeck and Daniel Cremers,
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Establishment of an interdisciplinary workflow of machine learning-based Radiomics in sarcoma patients,

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Better Text Understanding Through Image-To-Text Transfer,

[C56] P. Haeusser, T. Frerix, A. Mordvintsev and D. Cremers,
Associative Domain Adaptation,
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Efficient Deformable Shape Correspondence via Kernel Matching,
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[C60] Christian Nissler, Zoltan-Csaba Marton, Hannes Kisner, Ulrike Thomas and Rudolph Triebel, 
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[C61] Tick Son Wang, Zoltan-Csaba Marton, Manuel Brucker and Rudolph Triebel, 
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A Variational Approach to Shape-from-shading Under Natural Illumination, 

[C64] F. Bernard, F. R. Schmidt, J. Thunberg and D. Cremers, 
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[C65] A. Kasyanov, F. Engelmann, J. Stueckler and B. Leibe, 
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[C66] F. Engelmann, J. Stueckler and B. Leibe, 
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Protein Contact Prediction from Amino Acid Co-Evolution Using Convolutional Networks for Graph-Valued Images, 
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[C71] Z. Lähner, E. Rodola, F. R. Schmidt, M. M. Bronstein and D. Cremers, 
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[C72] A. Narr, R. Triebel and D. Cremers, 
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May 2016.

SHREC16: Matching of Deformable Shapes with Topological Noise, 
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[C76] L. Ma, C. Kerl, J. Stueckler and D. Cremers, 
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[C77] J. Engel, V. Usenko and D. Cremers, 
A Photometrically Calibrated Benchmark For Monocular Visual Odometry, 

[C78] J. Engel, V. Koltun and D. Cremers, 
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[C80] T. Windheuser and D. Cremers, 
A Convex Solution to Spatially-Regularized Correspondence Problems, 
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[C81] S. Sharifzadeh, I. Chiotellis, R. Triebel and D. Cremers, 
Learning to Drive using Inverse Reinforcement Learning and Deep Q-Networks, 
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[C82] D. Klostermann, A. Osep, J. Stueckler and B. Leibe, 
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[C85] M. Moeller, J. Diebold, G. Gilboa and D. Cremers,

[C86] J. Diebold, N. Demmel, C. Hazirbas, M. Möller and D. Cremers,

[C87] C. Hazirbas, J. Diebold and D. Cremers,

[C88] A. Kanezaki, E. Rodola and T. Harada,
RGB-D [Graph matching gakushuu wo mochiita RGB-D gazou kara no buttai kenshutsu] - Learning graph matching for object detection from RGB-D images,
20 - Robotics Symposia (RS), Karuizawa, Japan, March 2015.

[C89] T. Möllenhoff, E. Strekalovskiy, M. Möller and D. Cremers,

[C90] M. Jaimez, M. Souiai, J. Gonzalez-Jimenez and D. Cremers,
A Primal-Dual Framework for Real-Time Dense RGB-D Scene Flow,
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[C91] J. Stühmer and D. Cremers,
A Fast Projection Method for Connectivity Constraints in Image Segmentation,
X.-C. Tai, E. Bae, T. F. Chan and M. Lysaker(Eds.), , 2015.

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Adopting an Unconstrained Ray Model in Light-field Cameras for 3D Shape Reconstruction, 2015.

[C94] D. Mund, R. Triebel and D. Cremers,
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[C107] E. Rodola, M. Moeller and D. Cremers,
Point-wise Map Recovery and Refinement from Functional Correspondence,
Aachen, Germany, 2015, Received the Best Paper Award.

[C108] C. Kerl, J. Stueckler and D. Cremers,
Dense Continuous-Time Tracking and Mapping with Rolling Shutter RGB-D Cameras,
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[C109] M. Souiai, M. R. Oswald, Y. Kee, J. Kim, M. Pollefeys and D. Cremers,
Entropy Minimization for Convex Relaxation Approaches,
Santiago, Chile, 2015.

[C110] F. Stark, C. Hazirbas, R. Triebel and D. Cremers,
CAPTCHA Recognition with Active Deep Learning,
*GCPR Workshop on New Challenges in Neural Computation*, Aachen, Germany, 2015.

[C111] N. Nagaraja, F. R. Schmidt and T. Brox,
Video Segmentation with Just a Few Strokes,
Santiago, Chile, Dec 2015.

Model-Based Tracking at 300Hz using Raw Time-of-Flight Observations,
Santiago, Chile, 2015.

Novel Acquisition Scheme for Diffusion Kurtosis Imaging Based on Compressed-Sensing Accelerated DSI Yielding Superior Image Quality,
2014.

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2014.

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Improved Diffusion Kurtosis Imaging and Direct Propagator Estimation Using
6-D Compressed Sensing,
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[C118] D. Weikersdorfer, D. B. Adrian, D. Cremers and J. Conrad,
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2014.

[C119] F. Steinbruecker, J. Sturm and D. Cremers,
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[C121] Y. Kee, M. Souiai, D. Cremers and J. Kim,
Sequential Convex Relaxation for Mutual-Information-Based Unsupervised
Figure-Ground Segmentation,
2014.

[C122] H. Alvarez, L.M. Paz, J. Sturm and D. Cremers,
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[C123] J. Engel, T. Schöps and D. Cremers,
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September 2014, Oral Presentation.

[C124] T. Schöps, J. Engel and D. Cremers,
Semi-Dense Visual Odometry for AR on a Smartphone,
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[C125] T. Windheuser, M. Vestner, E. Rodola, R. Triebel and D. Cremers,
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[C127] R. Maier, J. Sturm and D. Cremers,
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[C128] T. Gurdan, M. R. Oswald, D. Gurdan and D. Cremers,
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[C129] M. R. Oswald and D. Cremers,
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[C130] C. Nieuwenhuis, S. Hawe, M. Kleinsteuber and D. Cremers, 
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2014.

[C131] M. R. Oswald, J. Stühmer and D. Cremers, 
Generalized Connectivity Constraints for Spatio-temporal 3D Reconstruction, 

[C132] E. Strekalovskiy and D. Cremers, 
Real-Time Minimization of the Piecewise Smooth Mumford-Shah Functional, 

[C133] A. Kanezaki, E. Rodola and T. Harada, 
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[C134] A. Kanezaki, E. Rodola, D. Cremers and T. Harada, 
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Anisotropic Laplace-Beltrami Operators for Shape Analysis, 
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[C137] R. Triebel, J. Stühmer, M. Souiai and D. Cremers, 
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[C139] A. Kanezaki, E. Rodola, D. Cremers and T. Harada, 
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[C141] C. Kerl, M. Souiai, J. Sturm and D. Cremers, 
Towards Illumination-invariant 3D Reconstruction using ToF RGB-D Cameras, 
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Adaptive Tool-Use Strategies for Anthropomorphic Service Robots,
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to appear, November 2014.

[C143] D. Droeschel, J. Stueckler and S. Behnke,
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Proc. of the 13th International Conference on Intelligent Autonomous Systems (IAS),

[C144] J. Stueckler, A. Gutt and S. Behnke,
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Proc. of the Joint 45th International Symposium on Robotics (ISR) and 8th German Conference on Robotics (ROBOTIK),
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[C145] J. Stueckler and S. Behnke,
Efficient deformable registration of multi-resolution surfel maps for object manipulation skill transfer,

[C146] D. Droeschel, J. Stueckler and S. Behnke,
Local multi-resolution representation for 6D motion estimation and mapping with a continuously rotating 3D laser scanner,
Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA), 5221-5226, May 2014.

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[C149] Bergbauer, Julia, Tari and Sibel,
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[C162] E. Toeppe, C. Nieuwenhuis and D. Cremers,
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[C164] H. Grimmett, R. Paul, R. Triebel and I. Posner,
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[C169] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers,
Direct Camera Pose Tracking and Mapping With Signed Distance Functions,
Demo Track of the RGB-D Workshop on Advanced Reasoning with Depth Cameras at the Robotics: Science and Systems Conference (RSS), June 2013.

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[C171] M. Souiai, E. Strekalovskiy, C. Nieuwenhuis and D. Cremers,
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[C172] F. Stangl, M. Souiai and D. Cremers,
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Images,
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Best research paper award.

[C179] J. Sturm, E. Bylow, F. Kahl and D. Cremers,
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[C180] E. Rodola, T. Harada, Y. Kuniyoshi and D. Cremers,
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[C182] E. Rodola, A. Torsello, T. Harada, Y. Kuniyoshi and D. Cremers,
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[C183] J. Lellmann, E. Strekalovskiy, S. Koetter and D. Cremers,
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[C184] C. Nieuwenhuis, E. Strekalovskiy and D. Cremers,
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[C185] J. Stühmer, P. Schröder and D. Cremers,  
Tree Shape Priors with Connectivity Constraints using Convex Relaxation on General Graphs,  
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[C186] G. Kuschk and D. Cremers,  
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[C187] M. R. Oswald and D. Cremers,  
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