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[C20] C Tomani and F Buettner,  
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[C21] C Tomani, S Gruber, ME Erdem, D Cremers and F Buettner,
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[C24] MW Wudenka, MG Müller, N Demmel, A Wedler, R Triebel, D Cremers and W Stuerzl,
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[C25] S Klenk, J Chui, N Demmel and D Cremers,
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[C26] L Koestler, N Yang, N Zeller and D Cremers,
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D. Cremers,
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[C67] E. Bylow, R. Maier, F. Kahl and C. Olsson,
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[C78] F. Steidle, W. Stürzl and R. Triebel, 
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[C89] V. Golkov, A. Vasilev, F. Pasa, I. Lipp, W. Boubaker, E. Sgarlata, F. Pfeiffer, V. Tomassini, D. K. Jones and D. Cremers,
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[C135] V. Golyanik, K. Kim, R. Maier, M. Niessner, D. Stricker and J. Kautz, 
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[C144] Y. Queau, J. Melou, F. Castan, D. Cremers and J.-D. Durou,
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[C148] F. Engelmann, J. Stueckler and B. Leibe,
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[C149] L. Cosmo, A. Albarelli, F. Bergamasco, A. Torsello, E. Rodola and D. Cremers,
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[C150] M. Jaimez, J. G. Monroy and J. Gonzalez-Jimenez,
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Scale Space and Variational Methods in Computer Vision (SSVM), June 2015.

[C174] C. Hazirbas, J. Diebold and D. Cremers,
Optimizing the Relevance-Redundancy Tradeoff for Efficient Semantic Segmentation,
Scale Space and Variational Methods in Computer Vision (SSVM), June 2015, Oral Presentation.

[C175] A. Kanezaki, E. Rodola and T. Harada,
RGB-D [Graph matching gakushuu wo mochiita RGB-D gazou kara no butai kenshutsu] - Learning graph matching for object detection from RGB-D images,
20 - Robotics Symposia (RS), Karuizawa, Japan, Mar 2015.
All: 1  

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[C176] T. Möllenhoff, E. Strekalovskiy, M. Möller and D. Cremers,  
Low Rank Priors for Color Image Regularization,  

[C177] M. Jaimez, M. Souiai, J. Gonzalez-Jimenez and D. Cremers,  
A Primal-Dual Framework for Real-Time Dense RGB-D Scene Flow,  
Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA), 2015.

[C178] J. Stühmer and D. Cremers,  
A Fast Projection Method for Connectivity Constraints in Image Segmentation,  

[C179] R. Mecca, E. Rodola and D. Cremers,  
Analysis of Surface Parametrizations for Modern Photometric Stereo Modeling,  
International Conference on Quality Control by Artificial Vision (QCAV), 2015.

[C180] F. Bergamasco, A. Albarelli, L. Cosmo, A. Torsello, E. Rodola and D. Cremers,  
Adopting an Unconstrained Ray Model in Light-field Cameras for 3D Shape Reconstruction,  
IEEE Conference on Computer Vision and Pattern Recognition (CVPR), 2015.

[C181] D. Mund, R. Triebel and D. Cremers,  
Active Online Confidence Boosting for Efficient Object Classification,  

Using Diffusion and Structural MRI for the Automated Segmentation of Multiple Sclerosis Lesions,  

[C183] M.I. Menzel, T. Sprenger, E.T. Tan, V. Golkov, C.J. Hardy, L. Marinelli and J.I. Sperl,  
Robustness of Phase Sensitive Reconstruction in Diffusion Spectrum Imaging,  

[C184] A. Menini, V. Golkov and F. Wiesinger,  
Free-Breathing, Self-Navigated RUFIS Lung Imaging with Motion Compensated Image Reconstruction,  

q-Space Deep Learning for Twelve-Fold Shorter and Model-Free Diffusion MRI Scans,  
Medical Image Computing and Computer Assisted Intervention (MICCAI), Munich, Germany, oct 2015.
All: 1

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[C186] A. Dosovitskiy, P. Fischer, E. Ilg, P. Haeusser, C. Hazirbas, V. Golkov, P. van der Smagt, D. Cremers and T. Brox,
FlowNet: Learning Optical Flow with Convolutional Networks,
IEEE International Conference on Computer Vision (ICCV), dec 2015.

SPENCER: A Socially Aware Service Robot for Passenger Guidance and Help in Busy Airports,

[C188] D. Holz, A. Topalidou-Kyniazopoulou, J. Stueckler and S. Behnke,
Real-Time Object Detection, Localization and Verification for Fast Robotic Depalletizing,

[C189] J. Engel, J. Stueckler and D. Cremers,
Large-Scale Direct SLAM with Stereo Cameras,

[C190] D. Caruso, J. Engel and D. Cremers,
Large-Scale Direct SLAM for Omnidirectional Cameras,

[C191] Y. Tao, R. Triebel and D. Cremers,
Semi-supervised Online Learning for Efficient Classification of Objects in 3D Data Streams,

[C192] R. Maier, J. Stueckler and D. Cremers,
Super-Resolution Keyframe Fusion for 3D Modeling with High-Quality Textures,
International Conference on 3D Vision (3DV), October 2015.

[C193] V. Usenko, J. Engel, J. Stueckler and D. Cremers,
Reconstructing Street-Scenes in Real-Time From a Driving Car,

[C194] M. Jaimez, M. Souiai, J. Stueckler, J. Gonzalez-Jimenez and D. Cremers,
Motion Cooperation: Smooth Piece-Wise Rigid Scene Flow from RGB-D Images,

[C195] E. Rodola, M. Moeller and D. Cremers,
Point-wise Map Recovery and Refinement from Functional Correspondence,
Proceedings Vision, Modeling and Visualization (VMV), Aachen, Germany, 2015, Received the Best Paper Award.

[C196] C. Kerl, J. Stueckler and D. Cremers,
Dense Continuous-Time Tracking and Mapping with Rolling Shutter RGB-D Cameras,
IEEE International Conference on Computer Vision (ICCV), Santiago, Chile, 2015.
[C197] M. Souiai, M. R. Oswald, Y. Kee, J. Kim, M. Pollefeys and D. Cremers,
Entropy Minimization for Convex Relaxation Approaches,
IEEE International Conference on Computer Vision (ICCV), Santiago, Chile, 2015.

[C198] F. Stark, C. Hazirbas, R. Triebel and D. Cremers,
CAPTCHA Recognition with Active Deep Learning,
GCPR Workshop on New Challenges in Neural Computation, Aachen, Germany, 2015.

[C199] N. Nagaraja, F. R. Schmidt and T. Brox,
Video Segmentation with Just a Few Strokes,
IEEE International Conference on Computer Vision (ICCV), Santiago, Chile, Dec 2015.

Model-Based Tracking at 300Hz using Raw Time-of-Flight Observations,
IEEE International Conference on Computer Vision (ICCV), Santiago, Chile, 2015.

[C201] J. Duran, M. Moeller, C. Sbert and D. Cremers,
A Novel Framework for Nonlocal Vectorial Total Variation Based on \( p^{\alpha, \tau} \hat{A} \) \( \alpha \) \( \tau \) norms,

Novel Acquisition Scheme for Diffusion Kurtosis Imaging Based on Compressed-Sensing Accelerated DSI Yielding Superior Image Quality,

Total Variation-Regularized Compressed Sensing Reconstruction for Multi-Shell Diffusion Kurtosis Imaging,

Direct Reconstruction of the Average Diffusion Propagator with Simultaneous Compressed-Sensing-Accelerated Diffusion Spectrum Imaging and Image Denoising by Means of Total Generalized Variation Regularization,

[C205] V. Golkov, M.I. Menzel, T. Sprenger, A. Haase, D. Cremers and J.I. Sperl,
Semi-Joint Reconstruction for Diffusion MRI Denoising Imposing Similarity of Edges in Similar Diffusion-Weighted Images,

Improved Diffusion Kurtosis Imaging and Direct Propagator Estimation Using 6-D Compressed Sensing,
[C207] D. B. AD. CJ. C D. Weikersdorfer, 
Event-based 3D SLAM with a depth-augmented dynamic vision sensor, 

[C208] F. Steinbruecker, J. Sturm and D. Cremers, 
Volumetric 3D Mapping in Real-Time on a CPU, 

[C209] E. Rodola, S. R Bulo, T. Windheuser, M. Vestner and D. Cremers, 
Dense Non-Rigid Shape Correspondence Using Random Forests, 
*IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2014.

[C210] Y. Kee, M. Souiai, D. Cremers and J. Kim, 
Sequential Convex Relaxation for Mutual-Information-Based Unsupervised Figure-Ground Segmentation, 
*IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2014.

[C211] H. Alvarez, L.M. Paz, J. Sturm and D. Cremers, 
Collision Avoidance for Quadrotors with a Monocular Camera, 

[C212] J. Engel, T. Schöps and D. Cremers, 
LSD-SLAM: Large-Scale Direct Monocular SLAM, 
*European Conference on Computer Vision (ECCV)*, September 2014, Oral Presentation.

[C213] T. Schöps, J. Engel and D. Cremers, 
Semi-Dense Visual Odometry for AR on a Smartphone, 

[C214] T. Windheuser, M. Vestner, E. Rodola, R. Triebel and D. Cremers, 
Optimal Intrinsic Descriptors for Non-Rigid Shape Analysis, 

[C215] M. Strobel, J. Diebold and D. Cremers, 
Flow and Color Inpainting for Video Completion, 
*German Conference on Pattern Recognition (GCPR)*, Münster, Germany, September 2014, Oral Presentation.

[C216] R. Maier, J. Sturm and D. Cremers, 
Submap-based Bundle Adjustment for 3D Reconstruction from RGB-D Data, 
*German Conference on Pattern Recognition (GCPR)*, Münster, Germany, September 2014, Oral Presentation.

[C217] T. Gurdan, M. R. Oswald, D. Gurdan and D. Cremers, 
Spatial and Temporal Interpolation of Multi-View Image Sequences, 
*German Conference on Pattern Recognition (GCPR)*, Münster, Germany, Vol. 36, sep 2014.

[C218] M. R. Oswald and D. Cremers, 
Surface Normal Integration for Convex Space-time Multi-view Reconstruction, 

[C219] C. Nieuwenhuis, S. Hawe, M. Kleinsteuber and D. Cremers, 
Co-Sparse Textural Similarity for Interactive Segmentation, 


[C233] J. Stueckler, A. Gutt and S. Behnke, **Combining the Strengths of Sparse Interest Point and Dense Image Registration for RGB-D Odometry**, *Proc. of the Joint 45th International Symposium on Robotics (ISR) and 8th German Conference on Robotics (ROBOTIK)*, to appear, jun 2014.


[C240] F. Bergamasco, A. Albarelli, E. Rodola and A. Torsello, **Can a fully unconstrained imaging model be applied effectively to central cameras?**, *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2013.
M. Souiai, C. Nieuwenhuis, E. Strekalovskiy and D. Cremers, 
Convex Optimization for Scene Understanding, 
ICCV Workshop on Graphical Models for Scene Understanding, 2013.

J. Bergbauer, C. Nieuwenhuis, M. Souiai and D. Cremers, 
Proximity Priors for Variational Semantic Segmentation and Recognition, 
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V. Golkov, T. Sprenger, A. Menini, M.I. Menzel, D. Cremers and J.I. Sperl, 
Effects of Low-Rank Constraints, Line-Process Denoising, and q-Space Compressed Sensing on Diffusion MR Image Reconstruction and Kurtosis Tensor Estimation, 

V. Golkov, T. Sprenger, M.I. Menzel, D. Cremers and J.I. Sperl, 
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European Society for Magnetic Resonance in Medicine and Biology (ESMRMB) Annual Meeting, 2013, Certificate of Merit Award.

V. Golkov, M.I. Menzel, T. Sprenger, A. Menini, D. Cremers and J.I. Sperl, 
Reconstruction, Regularization, and Quality in Diffusion MRI Using the Example of Accelerated Diffusion Spectrum Imaging, 
16th Annual Meeting of the German Chapter of the ISMRM, 2013, Oral Presentation.

V. Golkov, M.I. Menzel, T. Sprenger, A. Menini, D. Cremers and J.I. Sperl, 
Corrected Joint SENSE Reconstruction, Low-Rank Constraints, and Compressed-Sensing-Accelerated Diffusion Spectrum Imaging in Denoising and Kurtosis Tensor Estimation, 
ISMRM Workshop on Diffusion as a Probe of Neural Tissue Microstructure, 2013.

SNR-dependent Quality Assessment of Compressed-Sensing-Accelerated Diffusion Spectrum Imaging Using a Fiber Crossing Phantom, 

J.I. Sperl, E.T. Tan, T. Sprenger, V. Golkov, K.F. King, C.J. Hardy, L. Marinelli and M.I. Menzel, 
Phase Sensitive Reconstruction in Diffusion Spectrum Imaging Enabling Velocity Encoding and Unbiased Noise Distribution, 

V. Golkov, T. Sprenger, M.I. Menzel, E.T. Tan, K.F. King, C.J. Hardy, L. Marinelli, D. Cremers and J.I. Sperl, 
Noise Reduction in Accelerated Diffusion Spectrum Imaging through Integration of SENSE Reconstruction into Joint Reconstruction in Combination with q-Space Compressed Sensing, 
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[C250] C. Kerl, J. Sturm and D. Cremers,
Robust Odometry Estimation for RGB-D Cameras,

[C251] E. Toeppe, C. Nieuwenhuis and D. Cremers,
Volume Constraints for Single View Reconstruction,
*IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Portland, USA, 2013.

Toward Automated Driving in Cities using Close-to-Market Sensors,

[C253] H. Grimmett, R. Paul, R. Triebel and I. Posner,
Knowing When We Don’t Know: Introspective Classification for Mission-Critical Decision Making,

[C254] A. SD. C D. Weikersdorfer,
Depth-adative Supervoxels for RGB-D Video Segmentation,

[C255] R. Triebel, H. Grimmett and I. Posner,
Confidence Boosting: Improving the Introspectiveness of a Boosted Classifier for Efficient Learning,

[C256] R. Triebel, H. Grimmett, R. Paul and I. Posner,
Introspective Active Learning for Scalable Semantic Mapping,

[C257] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers,
Real-Time Camera Tracking and 3D Reconstruction Using Signed Distance Functions,

[C258] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers,
Direct Camera Pose Tracking and Mapping With Signed Distance Functions,
*Demo Track of the RGB-D Workshop on Advanced Reasoning with Depth Cameras at the Robotics: Science and Systems Conference (RSS)*, June 2013.

[C259] J. Sturm and W. Burgard,
Learning Probabilistic Models for Mobile Manipulation Robots,
*Proc. of the International Joint Conference on Artificial Intelligence (IJCAI)*, Track on Best papers in Sister Conferences, 2013.
All: 1
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[C260] M. Souiai, E. Strekalovskiy, C. Nieuwenhuis and D. Cremers,
A Co-occurrence Prior for Continuous Multi-Label Optimization,

[C261] F. Stangl, M. Souiai and D. Cremers,
Performance Evaluation of Narrow Band Methods for Variational Stereo,
*35th German Conference on Pattern Recognition (GCPR)*, 2013.

[C262] T. Möllenhoff, C. Nieuwenhuis, E. Toeppe and D. Cremers,
Efficient Convex Optimization for Minimal Partition Problems with Volume Constraints,

[C263] C. Kerl, J. Sturm and D. Cremers,
Dense Visual SLAM for RGB-D Cameras,

[C264] T. Naseer, J. Sturm and D. Cremers,
FollowMe: Person Following and Gesture Recognition with a Quadrocopter,

[C265] M. Klodt, J. Sturm and D. Cremers,
Scale-Aware Object Tracking with Convex Shape Constraints on RGB-D Images,
*German Conference on Pattern Recognition (GCPR)*, Saarbrücken, Germany, September 2013.

[C266] J. Sturm, E. Bylow, F. Kahl and D. Cremers,
Dense Tracking and Mapping with a Quadrocopter,
*Unmanned Aerial Vehicle in Geomatics (UAV-g)*, Rostock, Germany, September 2013.

[C267] D. Bender, M. Schikora, J. Sturm and D. Cremers,
Graph-based bundle adjustment for INS-camera calibration,
*Unmanned Aerial Vehicle in Geomatics (UAV-g)*, Rostock, Germany, September 2013, Best research paper award.

[C268] J. Sturm, E. Bylow, F. Kahl and D. Cremers,
CopyMe3D: Scanning and Printing Persons in 3D,
*German Conference on Pattern Recognition (GCPR)*, Saarbrücken, Germany, September 2013.

[C269] E. Rodola, T. Harada, Y. Kuniyoshi and D. Cremers,
Efficient Shape Matching using Vector Extrapolation,

[C270] J. Engel, J. Sturm and D. Cremers,
Semi-Dense Visual Odometry for a Monocular Camera,
*IEEE International Conference on Computer Vision (ICCV)*, Sydney, Australia, December 2013.

[C271] E. Rodola, A. Torsello, T. Harada, Y. Kuniyoshi and D. Cremers,
Elastic Net Constraints for Shape Matching,
*IEEE International Conference on Computer Vision (ICCV)*, Sydney, Australia, December 2013.
[C272] J. Lellmann, E. Strekalovskiy, S. Koetter and D. Cremers,
Total Variation Regularization for Functions with Values in a Manifold,
*IEEE International Conference on Computer Vision (ICCV)*, Sydney, Australia, December 2013.

[C273] C. Nieuwenhuis, E. Strekalovskiy and D. Cremers,
Proportion Priors for Image Sequence Segmentation,
*IEEE International Conference on Computer Vision (ICCV)*, Sydney, Australia, December 2013.

[C274] J. Stühmer, P. Schröder and D. Cremers,
Tree Shape Priors with Connectivity Constraints using Convex Relaxation on General Graphs,
*IEEE International Conference on Computer Vision (ICCV)*, Sydney, Australia, December 2013, *Oral Presentation*.

[C275] G. Kuschk and D. Cremers,
Fast and Accurate Large-scale Stereo Reconstruction using Variational Methods,
*ICCV Workshop on Big Data in 3D Computer Vision*, Sydney, Australia, December 2013.

[C276] M. R. Oswald and D. Cremers,
A Convex Relaxation Approach to Space Time Multi-view 3D Reconstruction,
*ICCV Workshop on Dynamic Shape Capture and Analysis (4DMOD)*, 2013.

[C277] F. Steinbruecker, C. Kerl, J. Sturm and D. Cremers,
Large-Scale Multi-Resolution Surface Reconstruction from RGB-D Sequences,
*IEEE International Conference on Computer Vision (ICCV)*, Sydney, Australia, 2013.

[C278] T. Naseer, J. Sturm and D. Cremers,
Interactive Person Following and Gesture Recognition with a Flying Robot,
*Proc. of the Assistance and Service Robotics Workshop (ASROB) at the IEEE. Int. Conf. on Intelligent Robots and Systems (IROS)*, Nov. 2013.

Driven Learning for Driving: How Introspection Improves Semantic Mapping,
*The International Symposium on Robotics Research (ISRR)*, 2013.

[C280] D. Cremers, E. Rodola and T. Windheuser,
Relaxations for Minimizing Metric Distortion and Elastic Energies for 3D Shape Matching,

[C281] M. Schadler, J. Stueckler and S. Behnke,
Multi-resolution surfel mapping and real-time pose tracking using a continuously rotating 2D laser scanner,

[C282] J. Stueckler and S. Behnke,
Efficient Dense 3D Rigid-Body Motion Segmentation in RGB-D Video,
M. McElhone, J. Stueckler and S. Behnke,
Joint detection and pose tracking of multi-resolution surfel models in RGB-D,

T. Fiolka, J. Stueckler, D. A. Klein, D. Schulz and S. Behnke,
Distinctive 3D surface entropy features for place recognition.,

A. Berner, J Li, D. Holz, J. Stueckler, S. Behnke and R. Klein,
Combining contour and shape primitives for object detection and pose estimation of prefabricated parts,

J. Stueckler and S. Behnke,
Hierarchical Object Discovery and Dense Modelling From Motion Cues in RGB-D Video,

M. Nieuwenhuisen, D. Droeschel, D. Holz, J. Stueckler, A. Berner, J Li, R. Klein and S. Behnke,
Mobile bin picking with an anthropomorphic service robot,

L. Gorelick, F. R. Schmidt and Y. Boykov,
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L. Ma, T. Whelan, E. Bondarev, P. H. N. de With and J. McDonald,
Planar simplification and texturing of dense point cloud maps,

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A game-theoretic approach to deformable shape matching,

F. Endres, J. Hess, N. Engelhard, J. Sturm, D. Cremers and W. Burgard,
An Evaluation of the RGB-D SLAM System,

T. Ruehr, J. Sturm, D. Pangercic, M. Beetz and D. Cremers,
A Generalized Framework for Opening Doors and Drawers in Kitchen Environments,

D Joho, GD Tipaldi, N Engelhard, C Stachniss and W Burgard,
Nonparametric Bayesian Models for Unsupervised Scene Analysis and Reconstruction,
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[C294] M. Schikora, A. Gning, L. Mihaylova, D. Cremers, W. Koch and R. Streit,
\textbf{Box-Particle Intensity Filter,}

[C295] M. Schikora, A. Gning, L. Mihaylova, D. Cremers and W. Koch,
\textbf{Box-Particle PHD Filter for Multi-Target Tracking,}
\textit{15th International Conference on Information Fusion (FUSION)}, Singapore, July 2012.

[C296] L. Zhang, J. Sturm, D. Cremers and D. Lee,
\textbf{Real-Time Human Motion Tracking using Multiple Depth Cameras,}

[C297] E. Strekalovskiy, C. Nieuwenhuis and D. Cremers,
\textbf{Nonmetric Priors for Continuous Multilabel Optimization,}

[C298] T. Windheuser, H. Ishikawa and D. Cremers,
\textbf{Generalized Roof Duality for Multi-Label Optimization: Optimal Lower Bounds and Persistency,}
\textit{European Conference on Computer Vision (ECCV)}, Firenze, Italy, oct 2012.

[C299] T. Windheuser, H. Ishikawa and D. Cremers,
\textbf{QPBO [QPBO arugorizumu no tachika ni yoru hiretsu mojura enerugi saishoka],}
\textit{Meeting on Image Recognition and Understanding}, Fukuoka, Japan, aug 2012.

[C300] M. R. Oswald, E. Toeppe and D. Cremers,
\textbf{Fast and Globally Optimal Single View Reconstruction of Curved Objects,}

[C301] E. Strekalovskiy, A. Chambolle and D. Cremers,
\textbf{A Convex Representation for the Vectorial Mumford-Shah Functional,}
\textit{IEEE Conference on Computer Vision and Pattern Recognition (CVPR)}, Providence, Rhode Island, jun 2012.

[C302] J. Engel, J. Sturm and D. Cremers,
\textbf{Camera-Based Navigation of a Low-Cost Quadrocopter,}

[C303] J. Sturm, N. Engelhard, F. Endres, W. Burgard and D. Cremers,
\textbf{A Benchmark for the Evaluation of RGB-D SLAM Systems,}

[C304] J. Engel, J. Sturm and D. Cremers,
\textbf{Accurate Figure Flying with a Quadrocopter Using Onboard Visual and Inertial Sensing,}

[C305] J. Sturm, W. Burgard and D. Cremers,
\textbf{Evaluating Egomotion and Structure-from-Motion Approaches Using the TUM RGB-D Benchmark,}
Evaluation of DSI Imaging with Compressed Sensing under the Presence of Different Noise Levels on a Diffusion Phantom, 

Comparison of Diffusion Kurtosis Tensor Estimation Methods in an Advanced Quality Assessment Framework, 

N. Ufer, M. Souiai and D. Cremers, 
Wehrli 2.0: An Algorithm for ”Tidying up Art”, 

R. Paul, R. Triebel, D. Rus and P. Newman, 
Semantic Categorization of Outdoor Scenes with Uncertainty Estimates using Multi-Class Gaussian Process Classification, 

R. Triebel, R. Paul, D. Rus and P. Newman, 
Parsing Outdoor Scenes from Streamed 3D Laser Data Using Online Clustering and Incremental Belief Updates, 

U. Hubert, J. Stueckler and S. Behnke, 
Bayesian calibration of the hand-eye kinematics of an anthropomorphic robot, 
Proc. of the 12th IEEE-RAS Int. Conf. on Humanoid Robots (Humanoids), 618-624, nov 2012.

J. Stueckler, N. Biresev and S. Behnke, 
Semantic mapping using object-class segmentation of RGB-D images, 

J. Stueckler and S. Behnke, 
Integrating depth and color cues for dense multi-resolution scene mapping using RGB-D cameras, 
Proc. of the IEEE Int. Conf. on Multisensor Fusion and Integration for Intelligent Systems (MFI), 162-167, sep 2012.

S. Muszynski, J. Stueckler and S. Behnke, 
Adjustable autonomy for mobile teleoperation of personal service robots, 
Proc. of the IEEE Int. Symp. on Robot and Human Interactive Communication, 933-940, sep 2012.

T. Fiolka, J. Stueckler, D. A. Klein, D. Schulz and S. Behnke, 
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[C328] T. Windheuser, U. Schlickewei, F. R. Schmidt and D. Cremers,
Geometrically Consistent Elastic Matching of 3D Shapes: A Linear Programming Solution,
*IEEE International Conference on Computer Vision (ICCV)*, 2011.

[C329] M. Aubry, U. Schlickewei and D. Cremers,
Pose-Consistent 3D Shape Segmentation Based on a Quantum Mechanical Feature Descriptor,

[C330] T. Schoenemann, S. Masnou and D. Cremers,
On a linear programming approach to the discrete Willmore boundary value problem and generalizations,

[C331] E. Strekalovskiy and D. Cremers,
Total Variation for Cyclic Structures: Convex Relaxation and Efficient Minimization,

[C332] B. Goldluecke and D. Cremers,
Introducing Total Curvature for Image Processing,
*IEEE International Conference on Computer Vision (ICCV)*, 2011.

[C333] E. Strekalovskiy, B. Goldluecke and D. Cremers,
Tight Convex Relaxations for Vector-Valued Labeling Problems,
*IEEE International Conference on Computer Vision (ICCV)*, 2011.

[C334] M. Aubry, K. Kolev, B. Goldluecke and D. Cremers,
Decoupling Photometry and Geometry in Dense Variational Camera Calibration,
*IEEE International Conference on Computer Vision (ICCV)*, 2011.

[C335] E. Strekalovskiy and D. Cremers,
Generalized Ordering Constraints for Multilabel Optimization,
*IEEE International Conference on Computer Vision (ICCV)*, 2011.

[C336] J. Hess, J. Sturm and W. Burgard,
Learning the State Transition Model to Efficiently Clean Surfaces with Mobile Manipulation Robots,
*Proc. of the Workshop on Manipulation under Uncertainty at the IEEE Int. Conf. on Robotics and Automation (ICRA)*, Shanghai, China, May 2011.

[C337] N. Engelhard, F. Endres, J. Hess, J. Sturm and W. Burgard,
Real-time 3D visual SLAM with a hand-held camera,

Towards a benchmark for RGB-D SLAM evaluation,
All: 1

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[C339] C. Nieuwenhuis, E. Toeppe and D. Cremers,

Space-Varying Color Distributions for Interactive Multiregion Segmentation: Discrete versus Continuous Approaches,


[C340] M. Klodt and D. Cremers,

A Convex Framework for Image Segmentation with Moment Constraints,

*IEEE International Conference on Computer Vision (ICCV)*, 2011.

[C341] M. Aubry, U. Schlickewei and D. Cremers,

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*IEEE International Conference on Computer Vision (ICCV) - Workshop on Dynamic Shape Capture and Analysis (4DMOD)*, 2011.

[C342] F. Steinbruecker, J. Sturm and D. Cremers,

Real-Time Visual Odometry from Dense RGB-D Images,

Workshop on Live Dense Reconstruction with Moving Cameras at the Intl. Conf. on Computer Vision (ICCV), 2011.


Mobile Manipulation of Kitchen Containers,

*Proc. of the IROS’11 Workshop on Results, Challenges and Lessons Learned in Advancing Robots with a Common Platform*, San Francisco, CA, USA, 2011.

[C344] M. Schikora, M. Oispuu, W. Koch and D. Cremers,

Multiple Source Localization Based on Biased Bearings Using the Intensity Filter - Approach and Experimental Results,


[C345] S. Madhogaria, M. Schikora, W. Koch and D. Cremers,

Pixel-based Classification Method for Detecting Unhealthy Regions in Leaf Images,

*6th IEEE ISIF Workshop on Sensor Data Fusion: Trends, Solutions, Applications (SDF)*, Berlin, Germany, September 2011.

[C346] M. Schikora, W. Koch, R.L. Streit and D. Cremers,

Sequential Monte Carlo Method for the iFilter,

*14th International Conference on Information Fusion (FUSION)*, Chicago, IL, USA, July 2011.

[C347] M. Oispuu and M. Schikora,

Multiple Emitter Localization Using a Realistic Airborne Array Sensor,

*14th International Conference on Information Fusion (FUSION)*, Chicago, IL, USA, July 2011.

[C348] M. Schikora, W. Koch and D. Cremers,

Multi-object tracking via high accuracy optical flow and finite set statistics,

[C349] E. Toeppe, M. R. Oswald, D. Cremers and C. Rother,
Silhouette-Based Variational Methods for Single View Reconstruction,
D. Cremers, M. A. Magnor, M. R. Oswald and L. Zelnik-Manor(Eds.), Proceedings of
the 2010 international conference on Video Processing and Computational Video, Berlin,

[C350] M. R. Oswald, E. Toeppe, C. Nieuwenhuis and D. Cremers,
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[C510] D. Cremers and G. Funka-Lea,
Dynamical statistical shape priors for level set based tracking,

[C511] S. Manay, D. Cremers, A. J. Yezzi and S. Soatto,
One-shot integral invariant shape priors for variational segmentation,

[C512] B. Rosenhahn, U. Kersting, D. Smith, J. Gurney, T. Brox and R. Klette,
A system for marker-less human motion estimation,
W. Kropatsch, R. Sablatnig and A. Hanbury(Eds.), Pattern Recognition (Proc. DAGM), Vienna, Austria, Springer, LNCS, Vol. 3663, 109-116, aug 2005, 60;a href='http://www.prip.tuwien.ac.at/dagm05/awards.php’¿Received the best paper award60;/a¿.

[C513] M. Rousson and D. Cremers,
Efficient kernel density estimation of shape and intensity priors for level set segmentation,

[C514] M. Welk, D. Theis, T. Brox and J. Weickert,
PDE based deconvolution with forward-backward diffusivities and diffusion tensors,
All: 1

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[C515] B. Goldluecke and M. Magnor,
Spacetime-Continous Geometry Meshes from Multi-View Video Sequences,

[C516] I. Ihrke, B. Goldluecke and M. Magnor,
Reconstructing the Geometry of Flowing Water,

[C517] N. Wijngaards, F. Dignum, P. Jonker, T. de Ridder, A. Visser, S. Leijnen and J. Sturm,
Dutch AIBO Team at RoboCup 2005,

[C518] H. Andreasson, R. Triebel and W. Burgard,
Improving Plane Extraction from 3D Data by Fusing Laser Data and Vision,

[C519] R. Triebel and W. Burgard,
Improving Simultaneous Localization and Mapping in 3D Using Global Constraints,
*Proc. of the Twentieth National Conference on Artificial Intelligence (AAAI)*, 2005.

[C520] R. Triebel, W. Burgard and F. Dellaert,
Using Hierarchical EM to Extract Planes from 3D Range Scans,

[C521] D. Cremers,
Bayesian Approaches to Motion-based Image and Video Segmentation,

[C522] T. Brox, A. Bruhn, N. Papenberg and J. Weickert,
High accuracy optical flow estimation based on a theory for warping,

[C523] T. Brox and J. Weickert,
A TV flow based local scale measure for texture discrimination,

[C524] T. Brox and J. Weickert,
Level set based segmentation of multiple objects,

[C525] D. Cremers, S. J. Osher and S. Soatto,
Kernel density estimation and intrinsic alignment for knowledge-driven segmentation: Teaching level sets to walk,
[C526] D. Cremers, N. Sochen and C. Schnörr,
Multiphase dynamic labeling for variational recognition-driven image segmentation,

[C527] H. Jin, D. Cremers, A. Yezzi and S. Soatto,
Shedding light on stereoscopic segmentation,

[C528] M. Magnor and B. Goldluecke,
Spacetime-coherent Geometry Reconstruction from Multiple Video Streams,

[C529] B. Goldluecke and M. Magnor,
Weighted Minimal Hypersurfaces and Their Applications in Computer Vision,

[C530] B. Goldluecke and M. Magnor,
Space-Time Isosurface Evolution for Temporally Coherent 3D Reconstruction,

[C531] R. Triebel, B. Frank, J. Meyer and W. Burgard,
First steps towards a robotic system for flexible volumetric mapping of indoor environments,

[C532] T. Brox, M. Rousson, R. Deriche and J. Weickert,
Unsupervised segmentation incorporating colour, texture, and motion,

[C533] T. Brox, M. Welk, G. Steidl and J. Weickert,
Equivalence results for TV diffusion and TV regularisation,

[C534] D. Cremers,
A variational framework for image segmentation combining motion estimation and shape regularization,

[C535] D. Cremers,
A multiphase level set framework for variational motion segmentation,
[C536] D. Cremers and S. Soatto,
A pseudo-distance for shape priors in level set segmentation,

[C537] D. Cremers and S. Soatto,
Variational space-time motion segmentation,

[C538] D. Cremers, N. Sochen and C. Schnörr,
Towards Recognition-based Variational Segmentation Using Shape Priors and Dynamic Labeling,

[C539] D. Cremers and A. L. Yuille,
A generative model based approach to motion segmentation,

[C540] G. Doretto, D. Cremers, P. Favaro and S. Soatto,
Dynamic texture segmentation,

[C541] M. Rousson, T. Brox and R. Deriche,
Active unsupervised texture segmentation on a diffusion based feature space,

[C542] B. Goldluecke and M. Magnor,
Joint 3D Reconstruction and Background Separation in Multiple Views using Graph Cuts,

[C543] B. Goldluecke and M. Magnor,
Real-time Microfacet Billboarding for Free-viewpoint Video Rendering,

[C544] B. Goldluecke and M. Magnor,
Real-time, Free-viewpoint Video Rendering from Volumetric Geometry,

[C545] C. Petz, B. Goldluecke and M. Magnor,
Hardware-accelerated Autostereogram Rendering for Interactive 3D Visualization,
All: 1

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A system for volumetric robotic mapping of underground mines, 

[C547] D. Hähnel, R. Triebel, W. Burgard and S. Thrun, 
Map Building with Mobile Robots in Dynamic Environments, 

[C548] T. Brox and J. Weickert, 
Nonlinear matrix diffusion for optic flow estimation, 

[C549] J. Keuchel, C. Schnoerr, C. Schellewald and D. Cremers, 
Unsupervised Image Partitioning with Semidefinite Programming, 

[C550] D. Cremers, T. Kohlberger and C. Schnörr, 
Nonlinear shape statistics in Mumford–Shah based segmentation, 

[C551] D. Cremers and C. Schnörr, 
Motion Competition: variational integration of motion segmentation and shape regularization, 

[C552] D. Cremers and C. Schnörr, 
Statistical shape knowledge in variational motion segmentation, 
A. Pece, Y. N. Wu and R. Larsen(Eds.), 1st Internat. Workshop on Generative-Model-Based Vision, Copenhagen, Univ. of Copenhagen, June, 2 2002.

[C553] J. Weickert and T. Brox, 
Diffusion and regularization of vector- and matrix-valued images, 

[C554] B. Goldluecke, M. Magnor and B. Wilburn, 
Hardware-accelerated Dynamic Light Field Rendering, 

[C555] T. Brox, D. Farin and P. H. N. de With, 
Multi-stage region merging for image segmentation, 
Proc. 22nd Symposium on Information and Communication Theory in the Benelux, Enschede, The Netherlands, 189-196, may 2001, Received the best paper award.

[C556] D. Cremers, T. Kohlberger and C. Schnörr, 
Nonlinear shape statistics via kernel spaces, 
All: 1

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[C557] J. Keuchel, C. Schellewald, D. Cremers and C. Schnörr,
Convex Relaxations for Binary Image Partitioning and Perceptual Grouping,
Radig, B., Florczyk and S.(Eds.), Pattern Recognition, Munich, Germany, Springer, LNCS,
Vol. 2191, 353-360, Sept. 2001, Received a DAGM Paper Award.

[C558] D. Cremers, C. Schnörr and J. Weickert,
Diffusion Snakes: Combining statistical shape knowledge and image information
in a variational framework,
N. Paragios(Ed.), IEEE First Int. Workshop on Variational and Level Set Methods,
Vancouver, 137-144, 2001, Best Student Paper Award.

[C559] D. Cremers, C. Schnörr, J. Weickert and C. Schellewald,
Learning of translation invariant shape knowledge for steering diffusion snakes,
G. Baratoff and H. Neumann(Eds.), Dynamische Perzeption, Ulm Germany, Infix, Proceedings

[C560] D. Cremers, C. Schnörr, J. Weickert and C. Schellewald,
Diffusion Snakes using statistical shape knowledge,
C. Sommer and Y.Y. Zeevi(Eds.), Algebraic Frames for the Perception-Action Cycle,

PhDThesis

[PhD1] R. Maier,
High-Quality 3D Reconstruction from Low-Cost RGB-D Sensors,
Technische Universität München, München, Germany, 2020.

[PhD2] V Usenko,
Visual-Inertial Navigation for Autonomous Vehicles,
Technische Universität München, München, 2019.

[PhD3] J Stühmer,
A Convex Optimization Framework for Connectivity Constraints in Image Segmentation and 3D Reconstruction,
Technische Universität München, München, 2016.

[PhD4] J. Stueckler,
Efficient Dense Registration, Segmentation, and Modeling Methods for RGB-D Environment Perception,
Faculty of Mathematics and Natural Sciences, University of Bonn, Germany, 2014.

[PhD5] K. Kolev,
Convexity in Image-Based 3D Surface Reconstruction,
Department of Computer Science, Technical University Munich, Germany, January 2012.

[PhD6] J. Sturm,
Approaches to Probabilistic Model Learning for Mobile Manipulation Robots,
University of Freiburg, Germany, May 2011, Received the Artificial Intelligence Dissertation Award 2011 (ECCAI) and the Wolfgang-Genter-Award 2011 (University of Freiburg); Finalist at the Georges-Giralt-Award 2012 (EURON); Selected for the Best Paper Track at IJCAI 2013.

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[PhD7] C. Nieuwenhuis,  
Restoration and Prostprocessing of Optical Flows,  
Faculty of Mathematics and Computer Science, Heidelberg University, Germany, jul 2009.

[PhD8] T. Schoenemann,  
Combinatorial Solutions for Shape Optimization in Computer Vision,  
Department of Computer Science, University of Bonn, Germany, 2008.

[PhD9] B. Goldluecke,  
Multi-Camera Reconstruction and Rendering for Free-viewpoint Video,  
Max-Planck-Institute for Computer Science, Saarbrücken, Germany, jul 2006.

[PhD10] T. Brox,  
From pixels to regions: partial differential equations in image analysis,  
Faculty of Mathematics and Computer Science, Saarland University, Germany, apr 2005.

[PhD11] D. Cremers,  
Statistical shape knowledge in variational image segmentation,  
Department of Mathematics and Computer Science, University of Mannheim, Germany, 2002.

MastersThesis

[M1] K. Knese,  
Realizing Online (Self-)Collision Avoidance Based on Inequality Constraints with Hierarchical Inverse Kinematics,  
Technical University of Munich, Germany, July 2014.

[M2] C Hazirbas,  
Feature Selection and Learning for Semantic Segmentation,  
Technical University Munich, Germany, June 2014.

[M3] T Schöps,  
Semi-dense visual SLAM on mobile devices,  
Technical University Munich, Germany, May 2014.

[M4] M. Shelley,  
Monocular Visual Inertial Odometry on a Mobile Device,  
Technical University Munich, Germany, Aug. 2014.

[M5] OMW Dunkley,  
Visual Inertial Control of a Nano-Quadrotor,  
Technical University Munich, Germany, Sept. 2014.

[M6] R. Maier,  
Out-of-Core Bundle Adjustment for 3D Workpiece Reconstruction,  
Technische Universität München, Germany, September 2013.

[M7] M. Brandl,  
Face recognition with wave kernel signatures using a depth camera,  
Technical University of Munich, Germany, Aug. 2012.

[M8] C. Kerl,  
Odometry from RGB-D Cameras for Autonomous Quadrocopters,  
Technical University Munich, Germany, Nov. 2012.
[M9] J. Engel, 
*Autonomous Camera-Based Navigation of a Quadrocopter*, 
Technical University Munich, Germany, Dec. 2011, Distinguished with the SIEMENS award for best Master’s Thesis 2012.

[M10] M. Souiai, 
*Newton Methods for Total Variation Minimization*, 
Computer Vision Group, TU Munich, Germany, June 2010.

[M11] J. Stühmer, 
*Ein Variationsansatz zur Schätzung von dichten Tiefenkarten im Kontext des Structure-from-Motion*, 
TU Dresden, Germany, Jul 2010.

[M12] E. Toeppe, 
*Shape Matching mittels Graph Cuts*, 
University of Bonn, 2008, Awarded Best Master Thesis of the Year (Bonn Society for Computer Science).

[M13] M. R. Oswald, 
*Reliability Estimation Methods and their Efficient Implementation*, 
Universidad Tecnica Federico Santa Maria, Valparaiso, Chile, Jun 2008.

[M14] M. R. Oswald, 
*Concurrent Stereo Reconstruction*, 
Technische Universität Dresden, Germany, Jun 2007.

[M15] A. Wedel, 
*Detektion stationaerer Hindernisse in monokularen Bildsequenzen*, 
Computer Vision Group, University of Bonn, Germany, April 2006.

[M16] J. Sturm, 
*An appearance-based Visual Compass for Mobile Robots*, 
University of Amsterdam, the Netherlands, Dec. 2006.

[M17] T. Brox, 
*Smoothing of matrix-valued data*, 
Department of Mathematics and Computer Science, University of Mannheim, Germany, May 2002.

[M18] B. Goldluecke, 
*Nichtkonforme Finite Elemente und Kollokation für elliptische Randwertprobleme*, 

Technical Reports

[R1] M. Souiai, E. Strekalovskiy, C. Nieuwenhuis and D. Cremers, 
*Label Configuration Priors for Continuous Multi-Label Optimization*, 

[R2] A. Chambolle, D. Cremers and T. Pock, 
*A Convex Approach for Computing Minimal Partitions*, 
[R3] T. Brox, O. Kleinschmidt and D. Cremers,
Iterated and Efficient Nonlocal Means for Denoising of Textural Patterns,

[R4] A. Visser, J. Sturm, P. van Rossum, J. Westra and T. Bink,
Dutch Aibo Team: Technical Report RoboCup 2006,

[R5] T. Brox, M. Rousson, R. Deriche and J. Weickert,
Colour, texture, and motion in level set based segmentation and tracking,
Technical report 147, Dept. of Mathematics, Saarland University, Saarbrücken, Germany, aug 2005.

[R6] B. Rosenhahn, U. Kersting, L. He, A. Smith, T. Brox, R. Klette and H. P. Seidel,
A silhouette based human motion tracking system,

[R7] J. Sturm, A. Visser and N. Wijngaards,
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[R8] D. Cremers, C. Schnörr, J. Weickert and C. Schellewald,
Diffusion Snakes using statistical shape knowledge,