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Interactive Multi-label Segmentation of RGB-D Images,
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[C228] M. Souiai, M. R. Oswald, Y. Kee, J. Kim, M. Pollefeys and D. Cremers,
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[C230] N. Nagaraja, F. R. Schmidt and T. Brox,
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A Novel Framework for Nonlocal Vectorial Total Variation Based on $\ell^{p,q,r}$-norms,

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All: 1

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[C239] F. Steinbruecker, J. Sturm and D. Cremers,
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[C243] J. Engel, T. Schöps and D. Cremers,
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[C244] T. Schöps, J. Engel and D. Cremers,
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[C245] T. Windheuser, M. Vestner, E. Rodola, R. Triebel and D. Cremers,
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[C247] R. Maier, J. Sturm and D. Cremers,
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*German Conference on Pattern Recognition (GCPR)*, Münster, Germany, Vol. 36, sep 2014.

[C249] M. R. Oswald and D. Cremers,
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[C250] C. Nieuwenhuis, S. Hawe, M. Kleinsteuber and D. Cremers,
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[C251] M. R. Oswald, J. Stühmer and D. Cremers,
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[C252] E. Strekalovskiy and D. Cremers,
Real-Time Minimization of the Piecewise Smooth Mumford-Shah Functional,

[C253] A. Kanezaki, E. Rodola and T. Harada,
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[C254] A. Kanezaki, E. Rodola, D. Cremers and T. Harada,
[Taiou tenshuugou ruijido gakushuu wo mochiita goutai-higoutai buttai kenshutsu],

[C255] M. Andreux, E. Rodola, M. Aubry and D. Cremers,
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[C270] J Bergbauer and S Tari,  
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*ICCV Workshop on Graphical Models for Scene Understanding*, 2013.

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*European Society for Magnetic Resonance in Medicine and Biology (ESMRMB) Annual Meeting*, 2013, **Certificate of Merit Award**.

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**Introspective Active Learning for Scalable Semantic Mapping,**  

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**Real-Time Camera Tracking and 3D Reconstruction Using Signed Distance Functions,**  

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**Direct Camera Pose Tracking and Mapping With Signed Distance Functions,**  
*Demo Track of the RGB-D Workshop on Advanced Reasoning with Depth Cameras at the Robotics: Science and Systems Conference (RSS)*, June 2013.
[C290] J. Sturm and W. Burgard, 
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[C291] M. Souiai, E. Strekalovskiy, C. Nieuwenhuis and D. Cremers, 
A Co-occurrence Prior for Continuous Multi-Label Optimization, 

[C292] F. Stangl, M. Souiai and D. Cremers, 
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[C293] T. Möllenhoff, C. Nieuwenhuis, E. Toeppe and D. Cremers, 
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[C294] C. Kerl, J. Sturm and D. Cremers, 
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[C296] M. Klodt, J. Sturm and D. Cremers, 
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Dense Tracking and Mapping with a Quadrocopter, 
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[C298] D. Bender, M. Schikora, J. Sturm and D. Cremers, 
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Unmanned Aerial Vehicle in Geomatics (UAV-g), Rostock, Germany, September 2013, Best research paper award.

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[C300] E. Rodola, T. Harada, Y. Kuniyoshi and D. Cremers, 
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[C301] J. Engel, J. Sturm and D. Cremers, 
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[C302] E. Rodola, A. Torsello, T. Harada, Y. Kuniyoshi and D. Cremers, 
Elastic Net Constraints for Shape Matching, 
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[C303] J. Lellmann, E. Strekalovskiy, S. Koetter and D. Cremers, 
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[C306] G. Kuschk and D. Cremers, 
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[C307] M. R. Oswald and D. Cremers, 
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[C308] F. Steinbruecker, C. Kerl, J. Sturm and D. Cremers, 
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[C309] T. Naseer, J. Sturm and D. Cremers, 
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*Proc. of the Assistance and Service Robotics Workshop (ASROB) at the IEEE Int. Conf. on Intelligent Robots and Systems (IROS)*, Nov. 2013.

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[C311] D. Cremers, E. Rodola and T. Windheuser, 
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[C312] M. Schadler, J. Stueckler and S. Behnke, 
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All: 1

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[C314] M. McElhone, J. Stueckler and S. Behnke,  
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[C315] T. Fiolka, J. Stueckler, D. A. Klein, D. Schulz and S. Behnke,  
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[C316] A. Berner, J Li, D. Holz, J. Stueckler, S. Behnke and R. Klein,  
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[C317] J. Stueckler and S. Behnke,  
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[C318] M. Nieuwenhuisen, D. Droeschel, D. Holz, J. Stueckler, A. Berner, J Li, R. Klein and S. Behnke,  
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[C319] L. Gorelick, F. R. Schmidt and Y. Boykov,  
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[C320] L. Ma, T. Whelan, E. Bondarev, P. H. N. de With and J. McDonald,  
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struction, 

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[C326] M. Schikora, A. Gning, L. Mihaylova, D. Cremers and W. Koch, 
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15th International Conference on Information Fusion (FUSION), Singapore, July 2012.

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[C329] T. Windheuser, H. Ishikawa and D. Cremers, 
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[C330] T. Windheuser, H. Ishikawa and D. Cremers, 
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Meeting on Image Recognition and Understanding, Fukuoka, Japan, aug 2012.

[C331] M. R. Oswald, E. Toeppe and D. Cremers, 
Fast and Globally Optimal Single View Reconstruction of Curved Objects, 
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A Benchmark for the Evaluation of RGB-D SLAM Systems, 

[C335] J. Engel, J. Sturm and D. Cremers, 
Accurate Figure Flying with a Quadrocopter Using Onboard Visual and Iner-
tial Sensing, 
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Wehrli 2.0: An Algorithm for ”Tidying up Art”,

Semantic Categorization of Outdoor Scenes with Uncertainty Estimates using Multi-Class Gaussian Process Classification,

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[C342] U. Hubert, J. Stueckler and S. Behnke,
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[C344] J. Stueckler and S. Behnke,
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