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[C33] T. Yenamandra, F. Bernard, J. Wang, F. Mueller and C. Theobalt,
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[C34] A. Vasilev, V. Golkov, M. Meissner, I. Lipp, E. Sgarlata, V. Tomassini, D. K. Jones and D.
Cremers,
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[C36] D. Schnibert, N. Demmel, L. von Stumberg, V. Usenko and D. Cremers,
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[C38] E. Laude, T. Wu and D. Cremers,
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[C43] E.Y. Puang, P. Lehner, Z.C. Marton, M. Durner, R. Triebel and A. Albu-Schäffer,
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[C51] C. Sommer and D. Cremers,
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[C52] C. Hazirbas, S. G. Soyer, M. C. Staab, L. Leal-Taixe and D. Cremers,
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[C53] B. Haefner, Y. Queau, T. Möllenhoff and D. Cremers,
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[C55] C Domokos, FR. Schmidt and D Cremers,
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[C69] N. Yang, R. Wang, J. Stueckler and D. Cremers,
Deep Virtual Stereo Odometry: Leveraging Deep Depth Prediction for Monocular Direct Sparse Odometry,

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[C72] M. Sundermeyer, Z. Marton, M. Durner, M. Brucker and R. Triebel, 
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[C91] Y. Queau, M. Pizenberg, J.-D. Durou and D. Cremers,
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[C99] K. Kurach, S. Gelly, M. Jastrzebski, P. Haeusser, O. Teytaud, D. Vincent and O. Bousquet,
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[C116] Y. Kuznietsov, J. Stueckler and B. Leibe, 
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[C124] Z. Lähner, E. Rodola, F. R. Schmidt, M. M. Bronstein and D. Cremers, 
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[C130] L. Ma, C. Kerl, J. Stueckler and D. Cremers,
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Direct Sparse Odometry,

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[M2] C Hazirbas,  
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[M3] T Schöps,  
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[M4] M. Shelley,  
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