Conference and Workshop Papers

[C1] C. Kerl, J. Sturm and D. Cremers, 
Robust Odometry Estimation for RGB-D Cameras, 

[C2] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers, 
Real-Time Camera Tracking and 3D Reconstruction Using Signed Distance Functions, 

[C3] D. Bender, M. Schikora, J. Sturm and D. Cremers, 
Graph-based bundle adjustment for INS-camera calibration, 
*Unmanned Aerial Vehicle in Geomatics (UAV-g)*, Rostock, Germany, September 2013, 
*Best research paper award.*

[C4] J. Sturm, E. Bylow, F. Kahl and D. Cremers, 
CopyMe3D: Scanning and Printing Persons in 3D, 
*German Conference on Pattern Recognition (GCPR)*, Saarbrücken, Germany, September 2013.

[C5] F. Endres, J. Hess, N. Engelhard, J. Sturm, D. Cremers and W. Burgard, 
An Evaluation of the RGB-D SLAM System, 

[C6] J. Engel, J. Sturm and D. Cremers, 
Camera-Based Navigation of a Low-Cost Quadrocopter, 

[C7] J. Sturm, N. Engelhard, F. Endres, W. Burgard and D. Cremers, 
A Benchmark for the Evaluation of RGB-D SLAM Systems, 

[C8] J. Sturm, V. Pradeep, C. Stachniss, C. Plagemann, K. Konolige and W. Burgard, 
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*Proc. of the International Joint Conference on Artificial Intelligence (IJCAI)*, July 2009.

[C9] J. Sturm, C. Plagemann and W. Burgard, 
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PhDThesis

[PhD1] J. Sturm, 
Approaches to Probabilistic Model Learning for Mobile Manipulation Robots, 
University of Freiburg, Germany, May 2011, Received the Artificial Intelligence Dissertation Award 2011 (ECCAI) and the Wolfgang-Genter-Award 2011 (University of Freiburg); Finalist at the Georges-Giralt-Award 2012 (EURON); Selected for the Best Paper Track at IJCAI 2013.