Journal Articles

Conference and Workshop Papers

[C1] L. von Stumberg, V. Usenko and D. Cremers, 
Direct Sparse Visual-Inertial Odometry using Dynamic Marginalization, 
May 2018.

[C2] L. von Stumberg, V. Usenko, J. Engel, J. Stueckler and D. Cremers, 
From Monocular SLAM to Autonomous Drone Exploration, 
European Conference on Mobile Robots (ECMR), September 2017.

[C3] V. Usenko, L. von Stumberg, A. Pangeric and D. Cremers, 
Real-Time Trajectory Replanning for MAVs using Uniform B-splines and a 
3D Circular Buffer, 
Vancouver, Canada, Sep 2017, Best Paper Award - Finalist ().