Journal Articles

Conference and Workshop Papers

[C1] L. von Stumberg, V. Usenko and D. Cremers,
Direct Sparse Visual-Inertial Odometry using Dynamic Marginalization,
May 2018.

[C2] L. von Stumberg, V. Usenko, J. Engel, J. Stueckler and D. Cremers,
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European Conference on Mobile Robots (ECMR), September 2017.

[C3] V. Usenko, L. von Stumberg, A. Pangercic and D. Cremers,
Real-Time Trajectory Replanning for MAVs using Uniform B-splines and a
3D Circular Buffer,
Vancouver, Canada, Sep 2017, Best Paper Award - Finalist ( ).