Journal Articles

[J1] M. Jaimez and J. Gonzalez-Jimenez,
Fast Visual Odometry for 3-D Range Sensors,

Conference and Workshop Papers

[C1] R Scona, M Jaimez, YR. Petillot, M Fallon and D Cremers,
StaticFusion: Background Reconstruction for Dense RGB-D SLAM in Dynamic Environments,

[C2] M. Jaimez, C. Kerl, J. Gonzalez-Jimenez and D. Cremers,
Fast Odometry and Scene Flow from RGB-D Cameras based on Geometric Clustering,
*Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA)*, 2017.

[C3] M. Jaimez, T. J. Cashman, A. Fitzgibbon, J. Gonzalez-Jimenez and D. Cremers,
An Efficient Background Term for 3D Reconstruction and Tracking with Smooth Subdivision Surface Models,

[C4] M. Jaimez, J. G. Monroy and J. Gonzalez-Jimenez,
Planar Odometry from a Radial Laser Scanner. A Range Flow-based Approach,
*Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA)*, 4479-4485, 2016.

[C5] M. Jaimez, M. Souiai, J. Gonzalez-Jimenez and D. Cremers,
A Primal-Dual Framework for Real-Time Dense RGB-D Scene Flow,
*Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA)*, 2015.

[C6] M. Jaimez, M. Souiai, J. Stueckler, J. Gonzalez-Jimenez and D. Cremers,
Motion Cooperation: Smooth Piece-Wise Rigid Scene Flow from RGB-D Images,