J1] J. Engel, J. Sturm and D. Cremers,
Scale-Aware Navigation of a Low-Cost Quadrocopter with a Monocular Camera,

C1] J. Engel, J. Sturm and D. Cremers,
Camera-Based Navigation of a Low-Cost Quadrocopter,

C2] J. Engel, J. Sturm and D. Cremers,
Accurate Figure Flying with a Quadrocopter Using Onboard Visual and Inertial Sensing,

M1] J. Engel,
Autonomous Camera-Based Navigation of a Quadrocopter,
Technical University Munich, Germany, Dec. 2011, Distinguished with the SIEMENS award for best Master’s Thesis 2012.