RGB-D SLAM Dataset and Benchmark List of Publications

[C1] R. Maier, J. Sturm and D. Cremers,
Submap-based Bundle Adjustment for 3D Reconstruction from RGB-D Data,
*German Conference on Pattern Recognition (GCPR)*, Münster, Germany, September 2014.

[C1] C. Kerl, J. Sturm and D. Cremers,
Robust Odometry Estimation for RGB-D Cameras,
*Int. Conf. on Robotics and Automation*, May 2013, Best Vision Paper Award - Finalist.

[C2] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers,
Real-Time Camera Tracking and 3D Reconstruction Using Signed Distance Functions,

[C3] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers,
Direct Camera Pose Tracking and Mapping With Signed Distance Functions,
Demo Track of the RGB-D Workshop on Advanced Reasoning with Depth Cameras at the

[C4] C. Kerl, J. Sturm and D. Cremers,
Dense Visual SLAM for RGB-D Cameras,

[C5] J. Sturm, E. Bylow, F. Kahl and D. Cremers,
Dense Tracking and Mapping with a Quadrocopter,
*Unmanned Aerial Vehicle in Geomatics (UAV-g)*, Rostock, Germany, September 2013.

[C6] J. Sturm, E. Bylow, F. Kahl and D. Cremers,
CopyMe3D: Scanning and Printing Persons in 3D,
*German Conference on Pattern Recognition (GCPR)*, Saarbrücken, Germany, September 2013.

[M1] R. Maier,
Out-of-Core Bundle Adjustment for 3D Workpiece Reconstruction,
Technische Universität München, Germany, September 2013.

[C1] F. Endres, J. Hess, N. Engelhard, J. Sturm, D. Cremers and W. Burgard,
An Evaluation of the RGB-D SLAM System,

[C2] J. Sturm, N. Engelhard, F. Endres, W. Burgard and D. Cremers,
A Benchmark for the Evaluation of RGB-D SLAM Systems,

[C3] J. Sturm, W. Burgard and D. Cremers,
Evaluating Egomotion and Structure-from-Motion Approaches Using the TUM RGB-D Benchmark,
[M1] C. Kerl,
Odometry from RGB-D Cameras for Autonomous Quadrocopters,
Technical University Munich, Germany, Nov. 2012.

[C1] N. Engelhard, F. Endres, J. Hess, J. Sturm and W. Burgard,
Real-time 3D visual SLAM with a hand-held camera,
Proc. of the RGB-D Workshop on 3D Perception in Robotics at the European Robotics
Forum, Vasteras, Sweden, April 2011.

and R. Siegwart,
Towards a benchmark for RGB-D SLAM evaluation,
Proc. of the RGB-D Workshop on Advanced Reasoning with Depth Cameras at Robotics:
Science and Systems Conf. (RSS), Los Angeles, USA, June 2011.

[C3] F. Steinbruecker, J. Sturm and D. Cremers,
Real-Time Visual Odometry from Dense RGB-D Images,
Workshop on Live Dense Reconstruction with Moving Cameras at the Intl. Conf. on Com-