Conference and Workshop Papers

[C1] R. Maier, R. Schaller and D. Cremers,
**Efficient Online Surface Correction for Real-time Large-Scale 3D Reconstruction,**
*British Machine Vision Conference (BMVC),* London, United Kingdom, September 2017.

[C2] R. Maier, J. Sturm and D. Cremers,
**Submap-based Bundle Adjustment for 3D Reconstruction from RGB-D Data,**
*German Conference on Pattern Recognition (GCPR),* Münster, Germany, September 2014,
*Oral Presentation.*

[C3] C. Kerl, J. Sturm and D. Cremers,
**Robust Odometry Estimation for RGB-D Cameras,**
May 2013, *Best Vision Paper Award - Finalist.*

[C4] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers,
**Real-Time Camera Tracking and 3D Reconstruction Using Signed Distance Functions,**

[C5] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers,
**Direct Camera Pose Tracking and Mapping With Signed Distance Functions,**
*Demo Track of the RGB-D Workshop on Advanced Reasoning with Depth Cameras at the Robotics: Science and Systems Conference (RSS),* June 2013.

[C6] C. Kerl, J. Sturm and D. Cremers,
**Dense Visual SLAM for RGB-D Cameras,**
*Proc. of the Int. Conf. on Intelligent Robot Systems (IROS),* 2013.

[C7] J. Sturm, E. Bylow, F. Kahl and D. Cremers,
**Dense Tracking and Mapping with a Quadrocopter,**
*Unmanned Aerial Vehicle in Geomatics (UAV-g),* Rostock, Germany, September 2013.

[C8] J. Sturm, E. Bylow, F. Kahl and D. Cremers,
**CopyMe3D: Scanning and Printing Persons in 3D,**
*German Conference on Pattern Recognition (GCPR),* Saarbrücken, Germany, September 2013.

[C9] F. Endres, J. Hess, N. Engelhard, J. Sturm, D. Cremers and W. Burgard,
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[C10] J. Sturm, N. Engelhard, F. Endres, W. Burgard and D. Cremers,
**A Benchmark for the Evaluation of RGB-D SLAM Systems,**

[C11] J. Sturm, W. Burgard and D. Cremers,
**Evaluating Egomotion and Structure-from-Motion Approaches Using the TUM RGB-D Benchmark,**
Keywords: Rgb-d Benchmark List of Publications

[C12] N. Engelhard, F. Endres, J. Hess, J. Sturm and W. Burgard,
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Towards a benchmark for RGB-D SLAM evaluation,

[C14] F. Steinbruecker, J. Sturm and D. Cremers,
Real-Time Visual Odometry from Dense RGB-D Images,
Workshop on Live Dense Reconstruction with Moving Cameras at the Intl. Conf. on Computer Vision (ICCV), 2011.

MastersThesis

[M1] R. Maier,
Out-of-Core Bundle Adjustment for 3D Workpiece Reconstruction,
Technische Universität München, Germany, September 2013.

[M2] C. Kerl,
Odometry from RGB-D Cameras for Autonomous Quadrocopters,
Technical University Munich, Germany, Nov. 2012.