Conference and Workshop Papers


Keywords: Rgb-d Benchmark List of Publications

[C12] N. Engelhard, F. Endres, J. Hess, J. Sturm and W. Burgard, 
Real-time 3D visual SLAM with a hand-held camera, 

Towards a benchmark for RGB-D SLAM evaluation, 

[C14] F. Steinbruecker, J. Sturm and D. Cremers, 
Real-Time Visual Odometry from Dense RGB-D Images, 
Workshop on Live Dense Reconstruction with Moving Cameras at the Intl. Conf. on Computer Vision (ICCV), 2011.

MastersThesis

[M1] R. Maier, 
Out-of-Core Bundle Adjustment for 3D Workpiece Reconstruction, 
Technische Universität München, Germany, September 2013.

[M2] C. Kerl, 
Odometry from RGB-D Cameras for Autonomous Quadrocopters, 
Technical University Munich, Germany, Nov. 2012.