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*Real-Time Trajectory Replanning for MAVs using Uniform B-splines and a 3D Circular Buffer*,
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*Learning Proximal Operators: Using Denoising Networks for Regularizing Inverse Imaging Problems*,
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[C55] T. Möllenhoff and D. Cremers,
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[C56] Christian Nissler, Zoltan-Csaba Marton, Hannes Kisner, Ulrike Thomas and Rudolph Triebel,
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A Variational Approach to Shape-from-shading Under Natural Illumination,

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A. Kanezaki, E. Rodola, D. Cremers and T. Harada,
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M. Souiai, E. Strekalovskiy, C. Nieuwenhuis and D. Cremers,

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[C174] D. Bender, M. Schikora, J. Sturm and D. Cremers,

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[C191] T. Fiolka, J. Stueckler, D. A. Klein, D. Schulz and S. Behnke,
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Adjustable autonomy for mobile teleoperation of personal service robots,
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[C256] E. Toeppe, M. R. Oswald, D. Cremers and C. Rother,
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