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Challenger: Training with Attribution Maps,

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Rendering, 2022.

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tions,
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Equipped With Stereo Cameras, 

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F. Steidle, A. Wedler, W. Stürzl and R. Triebel, 
ARDEA—An MAV with skills for future planetary missions, 

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Accelerating in vivo fast spin echo high angular resolution diffusion imaging 
with an isotropic resolution in mice through compressed sensing, 

[J18] G Fabbro, V Golkov, T Kemp and D Cremers, 
Speech Synthesis and Control Using Differentiable DSP, 

[J19] I Chiotellis and D Cremers, 
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Video Object Segmentation without Temporal Information, 

[J21] E Rodola, Z Lähner, AM. Bronstein, MM. Bronstein and J Solomon, 
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[J22] H Tjaden, U Schwanecke, E Schömer and D Cremers, 
A Region-based Gauss-Newton Approach to Real-Time Monocular Multiple 
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[C176] M Durner, S Kriegel, S Riedel, M Brucker, ZC Marton, F Balint-Benczedi and R Triebel,
Experience-based Optimization of Robotic Perception,
International Conference on Advanced Robotics (ICAR), 2017.
[C177] Y. Queau, J. Melou, F. Castan, D. Cremers and J.-D. Durou,
A Variational Approach to Shape-from-shading Under Natural Illumination,

[C178] F. Bernard, F. R. Schmidt, J. Thunberg and D. Cremers,
A Combinatorial Solution to Non-Rigid 3D Shape-to-Image Matching,

[C179] Y. Kuznetsov, J. Stueckler and B. Leibe,
Semi-Supervised Deep Learning for Monocular Depth Map Prediction,

[C180] A. Kasyanov, F. Engelmann, J. Stueckler and B. Leibe,
Keyframe-Based Visual-Inertial Online SLAM with Relocalization,

[C181] F. Engelmann, J. Stueckler and B. Leibe,
SAMP: Shape and Motion Priors for 4D Vehicle Reconstruction,

[C182] L. Cosmo, A. Albarelli, F. Bergamasco, A. Torsello, E. Rodola and D. Cremers,
A game-theoretical approach for joint matching of multiple feature throughout unordered images,

[C183] M. Jaimez, J. G. Monroy and J. Gonzalez-Jimenez,
Planar Odometry from a Radial Laser Scanner. A Range Flow-based Approach,
*Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA)*, 4479-4485, 2016.

[C184] N. Mayer, E. Ilg, P. Häusser, P. Fischer, D. Cremers, A. Dosovitskiy and T. Brox,
A Large Dataset to Train Convolutional Networks for Disparity, Optical Flow, and Scene Flow Estimation,

[C185] V. Golkov, T. Sprenger, J. I. Sperl, M. I. Menzel, M. Czisch, P. Sämann and D. Cremers,
Model-Free Novelty-Based Diffusion MRI,
*IEEE International Symposium on Biomedical Imaging (ISBI)*, Prague, Czech Republic, apr 2016.

[C186] V. Golkov, M. J. Skwark, A. Golkov, A. Dosovitskiy, T. Brox, J. Meiler and D. Cremers,
Protein Contact Prediction from Amino Acid Co-Evolution Using Convolutional Networks for Graph-Valued Images,
*Annual Conference on Neural Information Processing Systems (NIPS)*, Barcelona, Spain, dec 2016, Oral Presentation (acceptance rate: under 2%).

[C187] Z. Lähner, E. Rodola, F. R. Schmidt, M. M. Bronstein and D. Cremers,
Efficient Globally Optimal 2D-to-3D Deformable Shape Matching,
*IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, May 2016.
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[C188] V. Usenko, J. Engel, J. Stueckler and D. Cremers,
Direct Visual-Inertial Odometry with Stereo Cameras,
International Conference on Robotics and Automation (ICRA), May 2016.

[C189] A. Narr, R. Triebel and D. Cremers,
Stream-based Active Learning for Efficient and Adaptive Classification of 3D Objects,
International Conference on Robotics and Automation (ICRA), May 2016.

SHREC’16: Matching of Deformable Shapes with Topological Noise,
Proc. of Eurographics Workshop on 3D Object Retrieval (3DOR), May 2016.

[C191] L. Cosmo, E. Rodola, M. M. Bronstein, A. Torsello, D. Cremers and Y. Sahillioglu,
SHREC’16: Partial Matching of Deformable Shapes,
Proc. of Eurographics Workshop on 3D Object Retrieval (3DOR), May 2016.

[C192] T. Möllenhoff, E. Laude, M. Moeller, J. Lellmann and D. Cremers,
Sublabel-Accurate Relaxation of Nonconvex Energies,
IEEE Conference on Computer Vision and Pattern Recognition (CVPR), 2016, Oral Presentation, Received the Best Paper Honorable Mention Award at CVPR 2016.

[C193] L. Ma, C. Kerl, J. Stueckler and D. Cremers,
CPA-SLAM: Consistent Plane-Model Alignment for Direct RGB-D SLAM,
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[C194] J. Engel, V. Usenko and D. Cremers,
A Photometrically Calibrated Benchmark For Monocular Visual Odometry,

[C195] J. Engel, V. Koltun and D. Cremers,
Direct Sparse Odometry,

[C196] E. Laude, T. Möllenhoff, M. Moeller, J. Lellmann and D. Cremers,
Sublabel-Accurate Convex Relaxation of Vectorial Multilabel Energies,
European Conference on Computer Vision (ECCV), October 2016.

[C197] D. Bender, D. Cremers and W. Koch,
A position free boresight calibration for INS-camera systems,

[C198] I. Chiotellis, R. Triebel, T. Windheuser and D. Cremers,
Non-Rigid 3D Shape Retrieval via Large Margin Nearest Neighbor Embedding,
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[C199] T. Windheuser and D. Cremers,
A Convex Solution to Spatially-Regularized Correspondence Problems,
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[C200] S. Sharifzadeh, I. Chiotellis, R. Triebel and D. Cremers,
Learning to Drive using Inverse Reinforcement Learning and Deep Q-Networks,
NIPS Workshops, December 2016.

[C201] D. Bender, F. Rouatbi, M. Schikora, D. Cremers and W. Koch,
Scaling the world of monocular SLAM with INS-measurements for UAS navigation,

[C202] D. Klostermann, A. Osep, J. Stueckler and B. Leibe,
Unsupervised Learning of Shape-Motion Patterns for Objects in Urban Street Scenes,
British Machine Vision Conference (BMVC), 2016.

[C203] D. Kochanov, A. Osep, J. Stueckler and B. Leibe,
Scene Flow Propagation for Semantic Mapping and Object Discovery in Dynamic Street Scenes,

[C204] F. Engelmann, J. Stueckler and B. Leibe,
Joint Object Pose Estimation and Shape Reconstruction in Urban Street Scenes Using 3D Shape Priors,
Proc. of the German Conference on Pattern Recognition (GCPR), 2016.

[C205] M. Moeller, J. Diebold, G. Gilboa and D. Cremers,
Learning Nonlinear Spectral Filters for Color Image Reconstruction,
IEEE International Conference on Computer Vision (ICCV), 2015.

[C206] J. Diebold, N. Demmel, C. Hazirbas, M. Möller and D. Cremers,
Interactive Multi-label Segmentation of RGB-D Images,
Scale Space and Variational Methods in Computer Vision (SSVM), June 2015.

[C207] C. Hazirbas, J. Diebold and D. Cremers,
Optimizing the Relevance-Redundancy Tradeoff for Efficient Semantic Segmentation,
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[C208] A. Kanezaki, E. Rodola and T. Harada,
RGB-D [Graph matching gakushuu wo mochiita RGB-D gazou kara no buttai kenshutsu] - Learning graph matching for object detection from RGB-D images,
20 - Robotics Symposia (RS), Karuizawa, Japan, Mar 2015.

[C209] T. Möllenhoff, E. Strekalovskiy, M. Möller and D. Cremers,
Low Rank Priors for Color Image Regularization,

[C210] M. Jaimez, M. Souiai, J. Gonzalez-Jimenez and D. Cremers,
A Primal-Dual Framework for Real-Time Dense RGB-D Scene Flow,
Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA), 2015.
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[C211] J. Stühmer and D. Cremers,
A Fast Projection Method for Connectivity Constraints in Image Segmentation,

[C212] R. Mecca, E. Rodola and D. Cremers,
Analysis of Surface Parametrizations for Modern Photometric Stereo Modeling,
International Conference on Quality Control by Artificial Vision (QCAV), 2015.

[C213] F. Bergamasco, A. Albarelli, L. Cosmo, A. Torsello, E. Rodola and D. Cremers,
Adopting an Unconstrained Ray Model in Light-field Cameras for 3D Shape Reconstruction,
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[C214] D. Mund, R. Triebel and D. Cremers,
Active Online Confidence Boosting for Efficient Object Classification,

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[C216] M.I. Menzel, T. Sprenger, E.T. Tan, V. Golkov, C.J. Hardy, L. Marinelli and J.I. Sperl,
Robustness of Phase Sensitive Reconstruction in Diffusion Spectrum Imaging,

[C217] A. Menini, V. Golkov and F. Wiesinger,
Free-Breathing, Self-Navigated RUFIS Lung Imaging with Motion Compensated Image Reconstruction,

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[C219] A. Dosovitskiy, P. Fischer, E. Ilg, P. Haeusser, C. Hazirbas, V. Golkov, P. van der Smagt, D. Cremers and T. Brox,
FlowNet: Learning Optical Flow with Convolutional Networks,
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SPENCER: A Socially Aware Service Robot for Passenger Guidance and Help in Busy Airports,

[C221] D. Holz, A. Topalidou-Kyniazopoulou, J. Stueckler and S. Behnke,

Real-Time Object Detection, Localization and Verification for Fast Robotic Depalletizing,

[C222] J. Engel, J. Stueckler and D. Cremers,

Large-Scale Direct SLAM with Stereo Cameras,

[C223] D. Caruso, J. Engel and D. Cremers,

Large-Scale Direct SLAM for Omnidirectional Cameras,

[C224] Y. Tao, R. Triebel and D. Cremers,

Semi-supervised Online Learning for Efficient Classification of Objects in 3D Data Streams,

[C225] R. Maier, J. Stueckler and D. Cremers,

Super-Resolution Keyframe Fusion for 3D Modeling with High-Quality Textures,
International Conference on 3D Vision (3DV), October 2015.

[C226] V. Usenko, J. Engel, J. Stueckler and D. Cremers,

Reconstructing Street-Scenes in Real-Time From a Driving Car,

[C227] M. Jaimez, M. Souiai, J. Stueckler, J. Gonzalez-Jimenez and D. Cremers,

Motion Cooperation: Smooth Piece-Wise Rigid Scene Flow from RGB-D Images,

[C228] E. Rodola, M. Moeller and D. Cremers,

Point-wise Map Recovery and Refinement from Functional Correspondence,
Proceedings Vision, Modeling and Visualization (VMV), Aachen, Germany, 2015, Received the Best Paper Award.

[C229] C. Kerl, J. Stueckler and D. Cremers,

Dense Continuous-Time Tracking and Mapping with Rolling Shutter RGB-D Cameras,
IEEE International Conference on Computer Vision (ICCV), Santiago, Chile, 2015.

[C230] M. Souiai, M. R. Oswald, Y. Kee, J. Kim, M. Pollefeys and D. Cremers,

Entropy Minimization for Convex Relaxation Approaches,
IEEE International Conference on Computer Vision (ICCV), Santiago, Chile, 2015.
F. Stark, C. Hazirbas, R. Triebel and D. Cremers, 
CAPTCHA Recognition with Active Deep Learning,
GCPR Workshop on New Challenges in Neural Computation, Aachen, Germany, 2015.

N. Nagaraja, F. R. Schmidt and T. Brox,
Video Segmentation with Just a Few Strokes,
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J. Stühmer, S. Nowozin, A. Fitzgibbon, R. Szeliski, T. Perry, S. Acharya, D. Cremers and J. Shotton,
Model-Based Tracking at 300Hz using Raw Time-of-Flight Observations,
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J. Duran, M. Moeller, C. Sbert and D. Cremers,
A Novel Framework for Nonlocal Vectorial Total Variation Based on $l^{p,q,r}$ norms,

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V. Golkov, M.I. Menzel, T. Sprenger, A. Haase, D. Cremers and J.I. Sperl,
Semi-Joint Reconstruction for Diffusion MRI Denoising Imposing Similarity of Edges in Similar Diffusion-Weighted Images,

V. Golkov, M.I. Menzel, T. Sprenger, M. Souiai, A. Haase, D. Cremers and J.I. Sperl,
Improved Diffusion Kurtosis Imaging and Direct Propagator Estimation Using 6-D Compressed Sensing,

D. B. AD. C J. C D. Weikersdorfer,
Event-based 3D SLAM with a depth-augmented dynamic vision sensor,
[C241] F. Steinbruecker, J. Sturm and D. Cremers, 
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[C242] E. Rodola, S. R Bulo, T. Windheuser, M. Vestner and D. Cremers, 
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[C243] Y. Kee, M. Souiai, D. Cremers and J. Kim, 
Sequential Convex Relaxation for Mutual-Information-Based Unsupervised 
Figure-Ground Segmentation, 
*IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2014.

[C244] H. Alvarez, L.M. Paz, J. Sturm and D. Cremers, 
Collision Avoidance for Quadrotors with a Monocular Camera, 

[C245] J. Engel, T. Schöps and D. Cremers, 
LSD-SLAM: Large-Scale Direct Monocular SLAM, 
*European Conference on Computer Vision (ECCV)*, September 2014, Oral Presentation.

[C246] T. Schöps, J. Engel and D. Cremers, 
Semi-Dense Visual Odometry for AR on a Smartphone, 

[C247] T. Windheuser, M. Vestner, E. Rodola, R. Triebel and D. Cremers, 
Optimal Intrinsic Descriptors for Non-Rigid Shape Analysis, 

[C248] M. Strobel, J. Diebold and D. Cremers, 
Flow and Color Inpainting for Video Completion, 
*German Conference on Pattern Recognition (GCPR)*, Münster, Germany, September 2014, Oral Presentation.

[C249] R. Maier, J. Sturm and D. Cremers, 
Submap-based Bundle Adjustment for 3D Reconstruction from RGB-D Data, 
*German Conference on Pattern Recognition (GCPR)*, Münster, Germany, September 2014, Oral Presentation.

[C250] T. Gurdan, M. R. Oswald, D. Gurdan and D. Cremers, 
Spatial and Temporal Interpolation of Multi-View Image Sequences, 
*German Conference on Pattern Recognition (GCPR)*, Münster, Germany, Vol. 36, sep 2014.

[C251] M. R. Oswald and D. Cremers, 
Surface Normal Integration for Convex Space-time Multi-view Reconstruction, 

[C252] C. Nieuwenhuis, S. Hawe, M. Kleinsteuber and D. Cremers, 
Co-Sparse Textural Similarity for Interactive Segmentation, 

[C253] M. R. Oswald, J. Stühmer and D. Cremers, 
Generalized Connectivity Constraints for Spatio-temporal 3D Reconstruction, 
[C254] E. Strekalovskiy and D. Cremers,
Real-Time Minimization of the Piecewise Smooth Mumford-Shah Functional,

[C255] A. Kanezaki, E. Rodola and T. Harada,
RGB-D [RGB-D gazou kara no buttai kenshutsu ni okeru taiou tenshuugou
ruijido no gakushuu],

[C256] A. Kanezaki, E. Rodola, D. Cremers and T. Harada,
[Taiou tenshuugou ruijido gakushuu wo mochiita goutai-higoutai buttai kenshutsu],

[C257] M. Andreux, E. Rodola, M. Aubry and D. Cremers,
Anisotropic Laplace-Beltrami Operators for Shape Analysis,
Sixth Workshop on Non-Rigid Shape Analysis and Deformable Image Alignment (NOR-DIA), 2014.

[C258] O. Dunkley, J. Engel, J. Sturm and D. Cremers,
Visual-Inertial Navigation for a Camera-Equipped 25g Nano-Quadrotor,

[C259] R. Triebel, J. Stühmer, M. Souiai and D. Cremers,
Active Online Learning for Interactive Segmentation Using Sparse Gaussian Processes,
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[C260] S. Debnath, S. S. Baishya, R. Triebel, V. Dutt and D. Cremers,
Environment-adaptive Learning: How Clustering Helps to Obtain Good Training Data,
Carsten Lutz and Michael Thielescher(Eds.), KI 2014: Advances in Artificial Intelligence,

[C261] A. Kanezaki, E. Rodola, D. Cremers and T. Harada,
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International Conference on 3D Vision (3DV), 2014.

[C262] D. Bender, M. Schikora, J. Sturm and D. Cremers,
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2014.

[C263] C. Kerl, M. Souiai, J. Sturm and D. Cremers,
Towards Illumination-invariant 3D Reconstruction using ToF RGB-D Cameras,
International Conference on 3D Vision (3DV), 2014.

[C264] J. Stueckler and S. Behnke,
Adaptive Tool-Use Strategies for Anthropomorphic Service Robots,
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[C265] D. Droeschel, J. Stueckler and S. Behnke,
Local Multi-Resolution Surfel Grids for MAV Motion Estimation and 3D Mapping,

[C266] J. Stueckler, A. Gutt and S. Behnke,
Combining the Strengths of Sparse Interest Point and Dense Image Registration for RGB-D Odometry,
*Proc. of the Joint 45th International Symposium on Robotics (ISR) and 8th German Conference on Robotics (ROBOTIK)*, to appear, jun 2014.

[C267] J. Stueckler and S. Behnke,
Efficient deformable registration of multi-resolution surfel maps for object manipulation skill transfer,

[C268] D. Droeschel, J. Stueckler and S. Behnke,
Local multi-resolution representation for 6D motion estimation and mapping with a continuously rotating 3D laser scanner,
*Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA)*, 5221-5226, may 2014.

[C269] M. Schwarz, J. Stueckler and S. Behnke,
Mobile Teleoperation Interfaces with Adjustable Autonomy for Personal Service Robots,

[C270] F. R. Schmidt, T. Windheuser, U. Schlickewei and D. Cremers,
Dense Elastic 3D Shape Matching,

[C271] J Bergbauer and S Tari,
Wimmelbild Analysis with Approximate Curvature Coding Distance Images,

[C272] J Bergbauer and S Tari,
Top-down visual search in Wimmelbild,

[C273] F. Bergamasco, A. Albarelli, E. Rodola and A. Torsello,
Can a fully unconstrained imaging model be applied effectively to central cameras?,
*IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2013.

[C274] M. Souiai, C. Nieuwenhuis, E. Strekalovskiy and D. Cremers,
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*ICCV Workshop on Graphical Models for Scene Understanding*, 2013.
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[C275] J. Bergbauer, C. Nieuwenhuis, M. Souiai and D. Cremers,
Proximity Priors for Variational Semantic Segmentation and Recognition,
ICCV Workshop on Graphical Models for Scene Understanding, 2013.

[C276] V. Golkov, T. Sprenger, A. Menini, M.I. Menzel, D. Cremers and J.I. Sperl,
Effects of Low-Rank Constraints, Line-Process Denoising, and q-Space Compressed Sensing on Diffusion MR Image Reconstruction and Kurtosis Tensor Estimation,

[C277] V. Golkov, T. Sprenger, M.I. Menzel, D. Cremers and J.I. Sperl,
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[C278] V. Golkov, M.I. Menzel, T. Sprenger, A. Menini, D. Cremers and J.I. Sperl,
Reconstruction, Regularization, and Quality in Diffusion MRI Using the Example of Accelerated Diffusion Spectrum Imaging,
16th Annual Meeting of the German Chapter of the ISMRM, 2013, Oral Presentation.

[C279] V. Golkov, M.I. Menzel, T. Sprenger, A. Menini, D. Cremers and J.I. Sperl,
Corrected Joint SENSE Reconstruction, Low-Rank Constraints, and Compressed-Sensing-Accelerated Diffusion Spectrum Imaging in Denoising and Kurtosis Tensor Estimation,
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SNR-dependent Quality Assessment of Compressed-Sensing-Accelerated Diffusion Spectrum Imaging Using a Fiber Crossing Phantom,

Phase Sensitive Reconstruction in Diffusion Spectrum Imaging Enabling Velocity Encoding and Unbiased Noise Distribution,

Noise Reduction in Accelerated Diffusion Spectrum Imaging through Integration of SENSE Reconstruction into Joint Reconstruction in Combination with q-Space Compressed Sensing,

[C283] C. Kerl, J. Sturm and D. Cremers,
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[C284] E. Toeppe, C. Nieuwenhuis and D. Cremers,
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Toward Automated Driving in Cities using Close-to-Market Sensors,

[C286] H. Grimmett, R. Paul, R. Triebel and I. Posner,
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[C287] A. SD. C D. Weikersdorfer,
Depth-adative Supervoxels for RGB-D Video Segmentation,

[C288] R. Triebel, H. Grimmett and I. Posner,
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Introspective Active Learning for Scalable Semantic Mapping,

[C290] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers,
Real-Time Camera Tracking and 3D Reconstruction Using Signed Distance Functions,

[C291] E. Bylow, J. Sturm, C. Kerl, F. Kahl and D. Cremers,
Direct Camera Pose Tracking and Mapping With Signed Distance Functions,
Demo Track of the RGB-D Workshop on Advanced Reasoning with Depth Cameras at the Robotics: Science and Systems Conference (RSS), June 2013.

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Learning Probabilistic Models for Mobile Manipulation Robots,
*Proc. of the International Joint Conference on Artificial Intelligence (IJCAI)*, Track on Best papers in Sister Conferences, 2013.

[C293] M. Souiai, E. Strekalovskiy, C. Nieuwenhuis and D. Cremers,
A Co-occurrence Prior for Continuous Multi-Label Optimization,

[C294] F. Stangl, M. Souiai and D. Cremers,
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[C295] T. Möllenhoff, C. Nieuwenhuis, E. Toeppe and D. Cremers, 
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Constraints, 
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[C296] C. Kerl, J. Sturm and D. Cremers, 
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[C297] T. Naseer, J. Sturm and D. Cremers, 
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[C298] M. Klodt, J. Sturm and D. Cremers, 
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Images, 
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[C299] J. Sturm, E. Bylow, F. Kahl and D. Cremers, 
Dense Tracking and Mapping with a Quadrocopter, 
Unmanned Aerial Vehicle in Geomatics (UAV-g), Rostock, Germany, September 2013.

[C300] D. Bender, M. Schikora, J. Sturm and D. Cremers, 
Graph-based bundle adjustment for INS-camera calibration, 
Unmanned Aerial Vehicle in Geomatics (UAV-g), Rostock, Germany, September 2013, 
Best research paper award.

[C301] J. Sturm, E. Bylow, F. Kahl and D. Cremers, 
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[C302] E. Rodola, T. Harada, Y. Kuniyoshi and D. Cremers, 
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[C303] J. Engel, J. Sturm and D. Cremers, 
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Elastic Net Constraints for Shape Matching, 
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[C305] J. Lellmann, E. Strekalovskiy, S. Koetter and D. Cremers, 
Total Variation Regularization for Functions with Values in a Manifold, 
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[C306] C. Nieuwenhuis, E. Strekalovskiy and D. Cremers,
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[C307] J. Stühmer, P. Schröder and D. Cremers,
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[C308] G. Kuschik and D. Cremers,
Fast and Accurate Large-scale Stereo Reconstruction using Variational Methods,
*ICCV Workshop on Big Data in 3D Computer Vision*, Sydney, Australia, December 2013.

[C309] M. R. Oswald and D. Cremers,
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*ICCV Workshop on Dynamic Shape Capture and Analysis (4DMOD)*, 2013.

[C310] F. Steinbruecker, C. Kerl, J. Sturm and D. Cremers,
Large-Scale Multi-Resolution Surface Reconstruction from RGB-D Sequences,
*IEEE International Conference on Computer Vision (ICCV)*, Sydney, Australia, 2013.

[C311] T. Naseer, J. Sturm and D. Cremers,
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*Proc. of the Assistance and Service Robotics Workshop (ASROB) at the IEEE. Int. Conf. on Intelligent Robots and Systems (IROS)*, Nov. 2013.

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[C313] D. Cremers, E. Rodola and T. Windheuser,
Relaxations for Minimizing Metric Distortion and Elastic Energies for 3D Shape Matching,

[C314] M. Schadler, J. Stueckler and S. Behnke,
Multi-resolution surfel mapping and real-time pose tracking using a continuously rotating 2D laser scanner,

[C315] J. Stueckler and S. Behnke,
Efficient Dense 3D Rigid-Body Motion Segmentation in RGB-D Video,

[C316] M. McElhone, J. Stueckler and S. Behnke,
Joint detection and pose tracking of multi-resolution surfel models in RGB-D,
All: 1

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[C317] T. Fiolka, J. Stueckler, D. A. Klein, D. Schulz and S. Behnke,
Distinctive 3D surface entropy features for place recognition.,

[C318] A. Berner, J Li, D. Holz, J. Stueckler, S. Behnke and R. Klein,
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[C319] J. Stueckler and S. Behnke,
Hierarchical Object Discovery and Dense Modelling From Motion Cues in RGB-D Video,

[C320] M. Nieuwenhuisen, D. Droeschel, D. Holz, J. Stueckler, A. Berner, J Li, R. Klein and S. Behnke,
Mobile bin picking with an anthropomorphic service robot,

[C321] L. Gorelick, F. R. Schmidt and Y. Boykov,
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[C322] L. Ma, T. Whelan, E. Bondarev, P. H. N. de With and J. McDonald,
Planar simplification and texturing of dense point cloud maps,

[C323] E. Rodola, A.M. Bronstein, A. Albarelli, F. Bergamasco and A. Torsello,
A game-theoretic approach to deformable shape matching,

[C324] F. Endres, J. Hess, N. Engelhard, J. Sturm, D. Cremers and W. Burgard,
An Evaluation of the RGB-D SLAM System,

[C325] T. Ruehr, J. Sturm, D. Pangercic, M. Beetz and D. Cremers,
A Generalized Framework for Opening Doors and Drawers in Kitchen Environments,

[C326] D Joho, GD Tipaldi, N Engelhard, C Stachniss and W Burgard,
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[C327] M. Schikora, A. Gning, L. Mihaylova, D. Cremers, W. Koch and R. Streit,
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[C328] M. Schikora, A. Gning, L. Mihaylova, D. Cremers and W. Koch, 
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[C330] E. Strekalovskiy, C. Nieuwenhuis and D. Cremers, 
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[C331] T. Windheuser, H. Ishikawa and D. Cremers, 
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[C334] E. Strekalovskiy, A. Chambolle and D. Cremers, 
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Accurate Figure Flying with a Quadrocopter Using Onboard Visual and Inertial Sensing, 

[C338] J. Sturm, W. Burgard and D. Cremers, 
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All: 1

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[C362] M. Aubry, U. Schlickewei and D. Cremers,
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[C363] T. Schoenemann, S. Masnou and D. Cremers,
On a linear programming approach to the discrete Willmore boundary value problem and generalizations,

[C364] E. Strekalovskiy and D. Cremers,
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Introducing Total Curvature for Image Processing,
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[C374] M. Aubry, U. Schlickewei and D. Cremers,
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[C377] M. Schikora, M. Oispuu, W. Koch and D. Cremers,
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[C382] E. Toeppe, M. R. Oswald, D. Cremers and C. Rother,  
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