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[C129] J. Geiping, H. Dirks and D. Cremers,
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[C130] V. Golyanik, K. Kim, R. Maier, M. Niessner, D. Stricker and J. Kautz,
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A Large Dataset to Train Convolutional Networks for Disparity, Optical Flow, and Scene Flow Estimation,

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[C149] Z. Lähner, E. Rodola, F. R. Schmidt, M. M. Bronstein and D. Cremers,
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Proc. of Eurographics Workshop on 3D Object Retrieval (3DOR), May 2016.

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[C155] L. Ma, C. Kerl, J. Stueckler and D. Cremers,
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A Photometrically Calibrated Benchmark For Monocular Visual Odometry,

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Learning to Drive using Inverse Reinforcement Learning and Deep Q-Networks,
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[C163] D. Bender, F. Rouatbi, M. Schikora, D. Cremers and W. Koch,
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[C168] J. Diebold, N. Demmel, C. Hazirbas, M. Möller and D. Cremers,
Interactive Multi-label Segmentation of RGB-D Images,
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[C169] C. Hazirbas, J. Diebold and D. Cremers,
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*20 - Robotics Symposium (RS)*, Karuizawa, Japan, mar 2015.

[C171] T. Möllenhoff, E. Strekalovskiy, M. Möller and D. Cremers,
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*Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA)*, 2015.

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A Fast Projection Method for Connectivity Constraints in Image Segmentation,

[C174] R. Mecca, E. Rodola and D. Cremers,
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*International Conference on Quality Control by Artificial Vision (QCAV)*, 2015.

[C175] F. Bergamasco, A. Albarelli, L. Cosmo, A. Torsello, E. Rodola and D. Cremers,
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*IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2015.

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[C178] M.I. Menzel, T. Sprenger, E.T. Tan, V. Golkov, C.J. Hardy, L. Marinelli and J.I. Sperl,
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[C190] E. Rodola, M. Moeller and D. Cremers,
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*Proceedings Vision, Modeling and Visualization (VMV)*, Aachen, Germany, 2015, Received the Best Paper Award.

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Dense Continuous-Time Tracking and Mapping with Rolling Shutter RGB-D Cameras,
*IEEE International Conference on Computer Vision (ICCV)*, Santiago, Chile, 2015.

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