

Avoiding obstacles while following a line

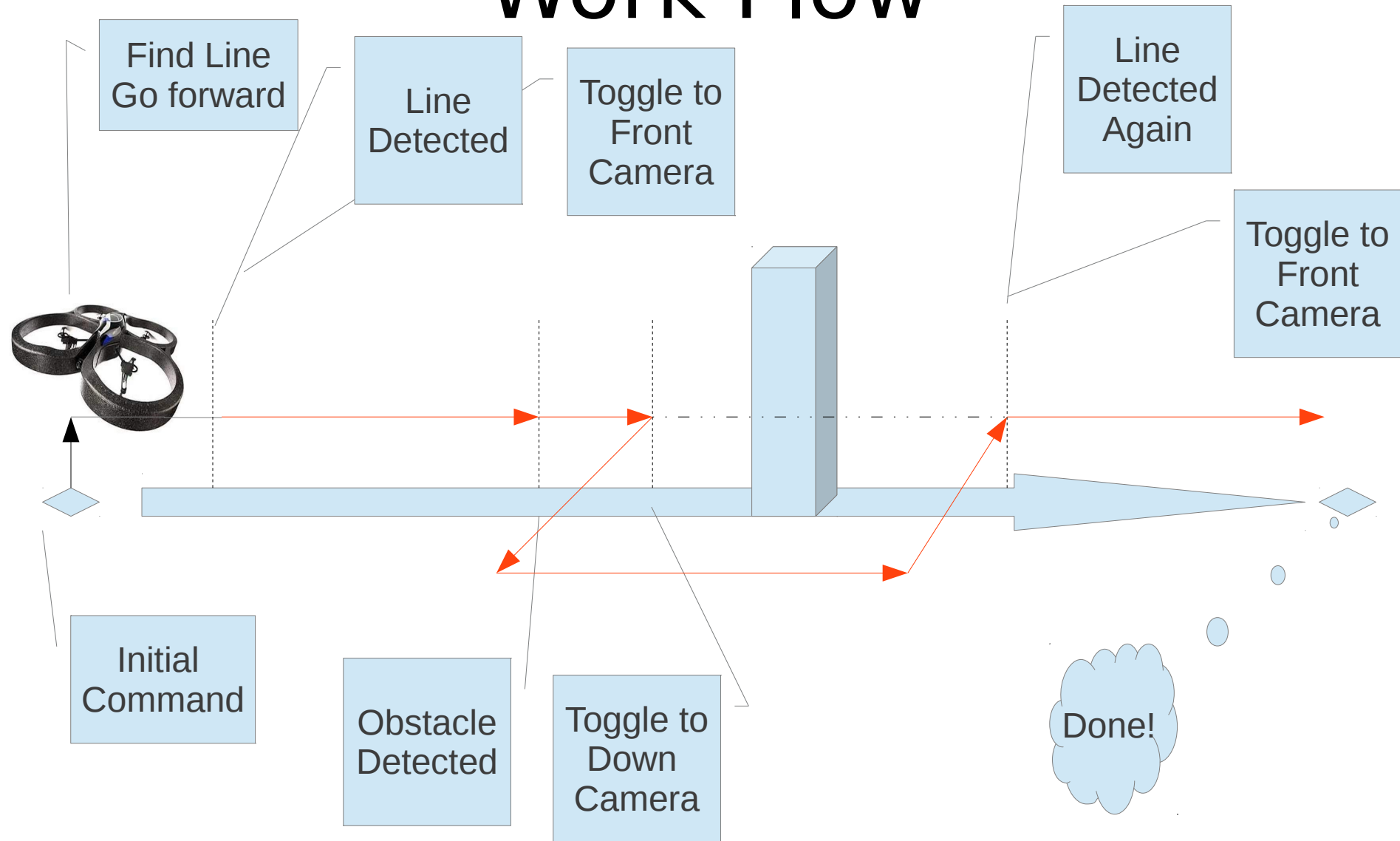
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Challenges

- *Both cameras have to be used!*
 - *Due to mirror reflection, the line disappears in the front camera*
- *Switching between cameras and control strategies*
- *Obstacle detection and distance estimation*

Work Flow



Milestones

- Line Detection - Done !
- Control Strategy - on going
- Obstacle Detection - waiting