[C1] V. Usenko, J. Engel, J. Stueckler and D. Cremers,
Direct Visual-Inertial Odometry with Stereo Cameras,
Int. Conf. on Robotics and Automation, May 2016.

[C2] J. Engel, V. Usenko and D. Cremers,
A Photometrically Calibrated Benchmark For Monocular Visual Odometry,

[C3] L. von Stumberg, V. Usenko, J. Engel, J. Stückler and D. Cremers,
Autonomous Exploration with a Low-Cost Quadrocopter using Semi-Dense Monocular SLAM,

Cloud-based collaborative 3D mapping in real-time with low-cost robots,

[C1] V. Usenko, J. Engel, J. Stueckler and D. Cremers,
Reconstructing Street-Scenes in Real-Time From a Driving Car,

[C1] V. Usenko, F. Seidel, Z. Marton, D. Pangeric and M. Beetz,
Furniture Classification using WWW CAD Models,