An appearance-based visual compass for mobile robots,

[C1] D. A. van Soest, M. de Greef, J. Sturm and A. Visser,
Autonomous Color Learning in an Artificial Environment,

[C2] J. Sturm, P. van Rossum and A. Visser,
Panoramic Localization in the 4-Legged League,

[C3] A. Visser, J. Sturm and F.C.A. Groen,
Robot companion localization at home and in the office,

Dutch AIBO Team at RoboCup 2006,

[M1] J. Sturm,
An appearance-based Visual Compass for Mobile Robots,
University of Amsterdam, the Netherlands, Dec. 2006.

[R1] A. Visser, J. Sturm, P. van Rossum, J. Westra and T. Bink,
Dutch Aibo Team: Technical Report RoboCup 2006,

[C1] N. Wijngaards, F. Dignum, P. Jonker, T. de Ridder, A. Visser, S. Leijnen, J. Sturm and S. van Weers,
Dutch AIBO Team at RoboCup 2005,

[R1] J. Sturm, A. Visser and N. Wijngaards,
Dutch Aibo Team: Technical Report RoboCup 2005,