Body Schema Learning

List of Publications

[B1] J. Sturm,
Approaches to Probabilistic Model Learning for Mobile Manipulation Robots,
Springer 2013.

[PhD1] J. Sturm,
Approaches to Probabilistic Model Learning for Mobile Manipulation Robots,
University of Freiburg, Germany, May 2011, Received the Artificial Intelligence Dis-
sertation Award 2011 (ECCAI) and the Wolfgang-Genter-Award 2011 (Uni-
versity of Freiburg); Finalist at the Georges-Giralt-Award 2012 (EURON);
Selected for the Best Paper Track at IJCAI 2013.

[J1] J. Sturm, C. Plagemann and W. Burgard,
Body schema learning for robotic manipulators from visual self-perception,

[C1] H. Schulz, L. Ott, J. Sturm and W. Burgard,
Learning Kinematics from Direct Self-Observation Using Nearest-Neighbor Methods,

[C1] J. Sturm, C. Plagemann and W. Burgard,
Unsupervised Body Scheme Learning through Self-Perception,
Int. Conf. on Robotics and Automation, Pasadena, CA, USA, 3328-3333, May 2008.

[C2] J. Sturm, C. Plagemann and W. Burgard,
Adaptive Body Scheme Models for Robust Robotic Manipulation,
Robotics: Science and Systems Conference (RSS), Zurich, Switzerland, June 2008.

[C3] J. Sturm, C. Plagemann and W. Burgard,
Body Scheme Learning and Life-Long Adaptation for Robotic Manipulation,
Proc. of the Workshop on Robot Manipulation at the Robotics: Science and Systems Con-
ference (RSS), Zurich, Switzerland, June 2008.