PhD Thesis

List of Publications

[B1] J. Sturm,
Approaches to Probabilistic Model Learning for Mobile Manipulation Robots,
Springer 2013.

[PhD1] J. Sturm,
Approaches to Probabilistic Model Learning for Mobile Manipulation Robots,
University of Freiburg, Germany, May 2011, Received the Artificial Intelligence Dis-
sertation Award 2011 (ECCAI) and the Wolfgang-Genter-Award 2011 (Uni-
versity of Freiburg); Finalist at the Georges-Giralt-Award 2012 (EURON);
Selected for the Best Paper Track at IJCAI 2013.